

SBAS260C - MAY 2002 - REVISED FEBRUARY 2007

8-Channel, 24-Bit ANALOG-TO-DIGITAL CONVERTER

FEATURES

- 24 BITS NO MISSING CODES
- INL: 0.0012% of FSR (max)
- FULL-SCALE INPUT: ±2V_{RFF}
- PGA FROM 1 TO 128
- 22 BITS EFFECTIVE RESOLUTION (PGA = 1), 19 BITS (PGA = 128)
- SINGLE CYCLE SETTLING MODE
- PROGRAMMABLE DATA OUTPUT RATES **UP TO 1kHz**
- ON-CHIP 1.25V/2.5V REFERENCE
- ON-CHIP CALIBRATION
- SPI COMPATIBLE
- POWER SUPPLY: 2.7V to 5.25V
- < 1mW POWER CONSUMPTION, V_{DD} = 3V

APPLICATIONS

- INDUSTRIAL PROCESS CONTROL
- LIQUID/GAS CHROMATOGRAPHY
- BLOOD ANALYSIS
- SMART TRANSMITTERS
- PORTABLE INSTRUMENTATION
- WEIGH SCALES
- PRESSURE TRANSDUCERS

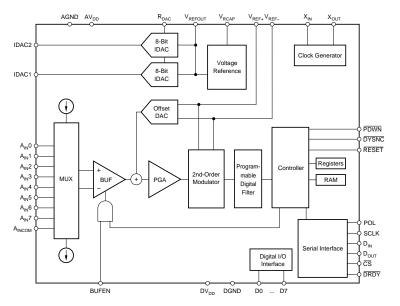
DESCRIPTION

The ADS1217 is a precision, wide dynamic range, deltasigma, Analog-to-Digital (A/D) converter with 24-bit resolution operating from 2.7V to 5.25V supplies. The delta-sigma, A/D converter provides up to 24 bits of no missing code performance and effective resolution of 22 bits.

The eight input channels are multiplexed. Internal buffering can be selected to provide a very high input impedance for direct connection to transducers or low-level voltage signals. Burnout current sources are provided that allow for the detection of an open or shorted sensor. An 8-bit Digital-to-Analog Converter (DAC) provides an offset correction with a range of 50% of the FSR (Full-Scale Range).

The PGA (Programmable Gain Amplifier) provides selectable gains of 1 to 128 with an effective resolution of 19 bits at a gain of 128. The A/D conversion is accomplished with a 2nd-order, delta-sigma modulator and programmable sinc filter. The reference input is differential and can be used for ratiometric measurements. The onboard current DACs operate independently with the maximum current set by an external resistor.

The serial interface is SPI compatible. Eight bits of digital I/O are also provided that can be used for input or output. The ADS1217 is designed for high-resolution measurement applications in smart transmitters, industrial process control, weigh scales, chromatography, and portable instrumentation.





Please be aware that an important notice concerning availability, standard warranty, and use in critical applications of Texas Instruments semiconductor products and disclaimers thereto appears at the end of this data sheet.

All trademarks are the property of their respective owners.



ABSOLUTE MAXIMUM RATINGS(1)

AV _{DD} to AGND	0.3V to +6V
DV _{DD} to DGND	
Input Current	
Input Current	10mA, Continuous
A _{IN}	GND -0.5V to AV _{DD} + 0.5V
AV _{DD} to DV _{DD}	–6V to +6V
AGND to DGND	0.3V to +0.3V
Digital Input Voltage to GND	0.3V to DV _{DD} + 0.3V
Digital Output Voltage to GND	0.3V to DV _{DD} + 0.3V
Maximum Junction Temperature	+150°C
Operating Temperature Range	40°C to +85°C
Storage Temperature Range	60°C to +150°C
Lead Temperature (soldering, 10s)	+300°C

NOTE: (1) Stresses above those listed under *Absolute Maximum Ratings* may cause permanent damage to the device. Exposure to absolute maximum conditions for extended periods may affect device reliability.

ELECTROSTATIC DISCHARGE SENSITIVITY

This integrated circuit can be damaged by ESD. Texas Instruments recommends that all integrated circuits be handled with appropriate precautions. Failure to observe proper handling and installation procedures can cause damage.

ESD damage can range from subtle performance degradation to complete device failure. Precision integrated circuits may be more susceptible to damage because very small parametric changes could cause the device not to meet its published specifications.

PACKAGE/ORDERING INFORMATION(1)

PRODUCT	PACKAGE-LEAD	PACKAGE DESIGNATOR	SPECIFIED TEMPERATURE RANGE	PACKAGE MARKING	ORDERING NUMBER	TRANSPORT MEDIA, QUANTITY
ADS1217	TQFP-48 "	PFB "	–40°C to +85°C "	ADS1217	ADS1217IPFBT ADS1217IPFBR	Tape and Reel, 250 Tape and Reel, 2000

NOTE: (1) For the most current package and ordering information, see the Package Option Addendum located at the end of this data sheet, or see the TI website at www.ti.com.

ELECTRICAL CHARACTERISTICS: AV_{DD} = 5V

All specifications at -40° C to $+85^{\circ}$ C, $AV_{DD} = +5$ V, $DV_{DD} = +2.7$ V to 5.25V, $f_{MOD} = 19.2$ kHz, PGA = 1, Buffer ON, $R_{DAC} = 150$ k Ω , $f_{DATA} = 10$ Hz, and $V_{REF} = +2.5$ V, unless otherwise specified.

			ADS1217		
PARAMETER	CONDITIONS	MIN	TYP	TYP MAX	
ANALOG INPUT (A _{IN} 0 - A _{IN} 7, A _{INCOM})					
Full-Scale Input Voltage	$(A_{IN+}) - (A_{IN-})$		±2V _{REF} /PGA		V
Analog Input Voltage	Buffer OFF	AGND - 0.1	1	AV _{DD} + 0.1	V
	Buffer ON	AGND + 0.05		AV _{DD} – 1.5	V
Differential Input Impedance	Buffer OFF		10/PGA		MΩ
Input Current	Buffer ON		0.5		nA
Bandwidth					
Fast Settling Filter	−3dB		0.469f _{DATA}		Hz
Sinc ² Filter	−3dB		0.318f _{DATA}		Hz
Sinc ³ Filter	-3dB		0.262f _{DATA}		Hz
Programmable Gain Amplifier	User Selectable Gain Ranges	1		128	
Burnout Current Sources			2		μΑ
OFFSET DAC					
Offset DAC Range			±V _{REF} /(PGA)		V
Offset DAC Monotonicity		8			Bits
Offset DAC Gain Error			±1		%
Offset DAC Gain Error Drift			1		ppm/°C
SYSTEM PERFORMANCE					
Resolution		24			Bits
No Missing Codes	Sinc ³ Filter			24	Bits
Integral Nonlinearity	End Point Fit, Differential Input,		0.0003	0.0012	% of FSR ⁽¹⁾
	Buffer Off				
Offset Error	Before Calibration		7.5		ppm of FSR
Offset Drift			0.02		ppm of FSR/°C
Gain Error	After Calibration		0.005		%
Gain Error Drift			0.5		ppm/°C
Common-Mode Rejection	at DC	100			dB
	$f_{CM} = 60Hz$, $f_{DATA} = 10Hz$		130		dB
	$f_{CM} = 50Hz$, $f_{DATA} = 50Hz$		120		dB
	$f_{CM} = 60$ Hz, $f_{DATA} = 60$ Hz		120		dB
Normal-Mode Rejection	$f_{SIG} = 50Hz$, $f_{DATA} = 50Hz$		100		dB
	$f_{SIG} = 60Hz$, $f_{DATA} = 60Hz$		100		dB
Output Noise		See	Typical Character	istics	
Power-Supply Rejection	at DC, dB = $-20\log(\Delta V_{OUT}/\Delta V_{DD})^{(2)}$	80	95		dB

NOTES: (1) FSR is Full-Scale Range. (2) ΔV_{OUT} is change in digital result. (3) 12pF switched capacitor at f_{SAMP} clock frequency.



ELECTRICAL CHARACTERISTICS: AV_{DD} = 5V (Cont.)

All specifications at -40° C to +85°C, AV_{DD} = +5V, DV_{DD} = +2.7V to 5.25V, f_{MOD} = 19.2kHz, PGA = 1, Buffer ON, R_{DAC} = 150k Ω , f_{DATA} = 10Hz, and V_{REF} = +2.5V, unless otherwise specified.

PARAMETER	CONDITIONS	MIN TYP		MAX	UNITS	
VOLTAGE REFERENCE INPUT Reference Input (V _{REF}) Negative Reference Input (V _{REF}) Positive Reference Input (V _{REF}) Common-Mode Rejection Common-Mode Rejection Bias Current ⁽³⁾	$V_{REF} = (V_{REF+}) - (V_{REF-})$ at DC $f_{VREFCM} = 60Hz, f_{DATA} = 60Hz$	0.1 AGND - 0.1 (V _{REF} -) + 0.1	2.5 120 120 1.3	2.6 (V _{REF+}) - 0.1 AV _{DD} + 0.1	V V V dB dB	
ON-CHIP VOLTAGE REFERENCE Output Voltage Short-Circuit Current Source Short-Circuit Current Sink Drift Noise Output Impedance Startup Time	$V_{REF}=2.5V,PGA=1$ $REFHI=1$ $REFHI=0$ $V_{RCAP}=0.1\mu F,BW=0.1Hzto100Hz$ $Sourcing100\mu A$	2.4	2.5 1.25 8 50 15 10 3	2.6	μΑ V V mA μΑ ppm/°C μVrms Ω ms	
IDAC Full-Scale Output Current	R_{DAC} = 150k Ω , Range = 1 R_{DAC} = 150k Ω , Range = 2 R_{DAC} = 150k Ω , Range = 3 R_{DAC} = 15k Ω , Range = 3		0.5 1 2 20		mA mA mA	
Current Setting Resistance (R _{DAC}) Monotonicity Compliance Voltage	$R_{DAC} = 150k\Omega$	10 8 0	Typical Character	AV _{DD} – 1	kΩ Bits V	
Output Impedance PSRR Gain Error Gain Error Drift Gain Error Mismatch Gain Error Mismatch Drift	V _{OUT} = AV _{DD} /2, Code > 16 Individual IDAC Individual IDAC Between IDACs, Same Range and Code Between IDACs, Same Range and Code	See	400 5 75 0.25 15	ISUCS	ppm/V % ppm/°C % ppm/°C	
POWER-SUPPLY REQUIREMENTS Power-Supply Voltage Analog Current (I _{ADC} + I _{VREF} + I _{IDAC}) A/D Converter Current (I _{ADC})	AV _{DD} PDWN = 0, or SLEEP PGA = 1, Buffer OFF PGA = 128, Buffer OFF PGA = 1, Buffer ON PGA = 128, Buffer ON	4.75	1 175 500 250 900	5.25 275 750 350 1375	V nA μA μA μA	
V_{REF} Current (I_{VREF}) I_{IDAC} Current (I_{IDAC})	Excludes Load Current		250 480	375 675	μΑ μΑ	
Digital Current	Normal Mode, $DV_{DD} = 5V$ SLEEP Mode, $DV_{DD} = 5V$ Read Data Continuous Mode, $DV_{DD} = 5V$ $\overline{PDWN} = 0$		180 150 230 1	275	μΑ μΑ μΑ nA	
Power Dissipation	PGA = 1, Buffer OFF, REFEN = 0, IDACs OFF, DV _{DD} = 5V		1.8	2.8	mW	

NOTES: (1) FSR is Full-Scale Range. (2) ΔV_{OUT} is change in digital result. (3) 12pF switched capacitor at f_{SAMP} clock frequency.

ELECTRICAL CHARACTERISTICS: $AV_{DD} = 3V$

All specifications at -40° C to +85°C, AV_{DD} = +3V, DV_{DD} = +2.7V to 5.25V, f_{MOD} = 19.2kHz, PGA = 1, Buffer ON, R_{DAC} = 75k Ω , f_{DATA} = 10Hz, and V_{REF} = +1.25V, unless otherwise specified.

PARAMETER	CONDITIONS	MIN	TYP	MAX	UNITS
ANALOG INPUT (A _{IN} 0 - A _{IN} 7, A _{INCOM}) Full-Scale Input Voltage Analog Input Range Input Impedance	(A _{IN+}) – (A _{IN}) Buffer OFF Buffer ON Buffer OFF	AGND - 0.1 AGND + 0.05	±2V _{REF} /PGA	AV _{DD} + 0.1 AV _{DD} - 1.5	V V V MΩ
Input Current Bandwidth Fast Settling Filter Sinc ² Filter	Buffer ON -3dB -3dB		0.5 0.469f _{DATA} 0.318f _{DATA}		nA Hz Hz
Sinc ³ Filter Programmable Gain Amplifier Burnout Current Sources	−3dB User Selectable Gain Ranges	1	0.262f _{DATA} 2	128	Hz μA
OFFSET DAC Offset DAC Range Offset DAC Monotonicity Offset DAC Gain Error Offset DAC Gain Error Drift		8	±V _{REF} /(PGA) ±1 2		V Bits % ppm/°C
SYSTEM PERFORMANCE					
Resolution No Missing Codes Integral Nonlinearity	Sinc ³ Filter End Point Fit, Differential Input, Buffer Off, T = 25°C	24	0.0003	24 0.0012	Bits Bits % of FSR ⁽¹⁾
Offset Error Offset Drift Gain Error Gain Error Drift	Before Calibration After Calibration		15 0.04 0.010 1.0		ppm of FSF ppm of FSR/' % ppm/°C
Common-Mode Rejection	at DC $f_{CM} = 60Hz$, $f_{DATA} = 10Hz$ $f_{CM} = 50Hz$, $f_{DATA} = 50Hz$ $f_{CM} = 60Hz$, $f_{DATA} = 60Hz$	100	130 120 120		dB dB dB dB
Normal-Mode Rejection Output Noise	$f_{SIG} = 50Hz, f_{DATA} = 50Hz$ $f_{SIG} = 60Hz, f_{DATA} = 60Hz$	Soo	100 100 Typical Characteri	ictics	dB dB
Power-Supply Rejection	at DC, dB = $-20 \log(\Delta V_{OUT}/\Delta V_{DD})^{(2)}$	75	90		dB
VOLTAGE REFERENCE INPUT Reference Input (V _{REF}) Negative Reference Input (V _{REF} -) Positive Reference Input (V _{REF} +) Common-Mode Rejection Common-Mode Rejection	$V_{REF} \equiv (V_{REF+}) - (V_{REF-})$ at DC $f_{VREFCM} = 60Hz$	0.1 AGND - 0.1 (V _{REF} -) + 0.1	1.25 120 120	1.3 (V _{REF+}) - 0.1 AV _{DD} + 0.1	V V V dB dB
Bias Current ⁽³⁾ ON-CHIP VOLTAGE REFERENCE	V _{REF} = 1.25V		0.65		μΑ
Output Voltage Short-Circuit Current Source Short-Circuit Current Sink Drift Noise Output Impedance Startup Time	REF HI = 0 $V_{RCAP} = 0.1 \mu F, \ BW = 0.1 Hz \ to \ 100 Hz \\ Sourcing \ 100 \mu A$	1.2	1.25 3 50 15 10 3 5	1.3	V mA μA ppm/°C μVrms Ω ms
IDAC Full-Scale Output Current	R_{DAC} = 75k Ω , Range = 1 R_{DAC} = 75k Ω , Range = 2 R_{DAC} = 75k Ω , Range = 3 R_{DAC} = 15k Ω , Range = 3		0.5 1 2 20		mA mA mA mA
Current Setting Resistance (R _{DAC}) Monotonicity Compliance Voltage Output Impedance PSRR Gain Error Gain Error Drift Gain Error Mismatch	$R_{DAC} = 75k\Omega$ $V_{OUT} = AV_{DD}/2, \ Code > 16$ Individual IDAC Individual IDAC Between IDACs, Same Range and Code	10 8 0 See	Typical Characteri 600 5 75 0.25	AV _{DD} – 1	kΩ Bits V ppm/V % ppm/°C %

NOTES: (1) FSR is Full-Scale Range. (2) ΔV_{OUT} is change in digital result. (3) 12pF switched capacitor at f_{SAMP} clock frequency.



ELECTRICAL CHARACTERISTICS: AV_{DD} = 3V (Cont.)

All specifications at -40° C to $+85^{\circ}$ C, $AV_{DD} = +3V$, $DV_{DD} = +2.7V$ to 5.25V, $f_{MOD} = 19.2$ kHz, PGA = 1, Buffer ON, $R_{DAC} = 75$ k Ω , $f_{DATA} = 10$ Hz, and $V_{REF} = +1.25$ V, unless otherwise specified.

		ADS1217			
PARAMETER	CONDITIONS	MIN	TYP	MAX	UNITS
POWER-SUPPLY REQUIREMENTS					
Power-Supply Voltage	AV _{DD}	2.7		3.3	V
Analog Current (I _{ADC} + I _{VREF} + I _{IDAC})	$\overline{PDWN} = 0$, or SLEEP		1		nA
A/D Converter Current (I _{ADC})	PGA = 1, Buffer OFF		160	250	μΑ
	PGA = 128, Buffer OFF		450	700	μΑ
	PGA = 1, Buffer ON		230	325	μΑ
	PGA = 128, Buffer ON		850	1325	μΑ
V _{REF} Current (I _{VREF})			250	375	μΑ
I _{IDAC} Current (I _{IDAC})	Excludes Load Current		480	675	μΑ
Digital Current	Normal Mode, DV _{DD} = 3V		90	200	μΑ
	SLEEP Mode, DV _{DD} = 3V		75		μΑ
	Read Data Continuous Mode, DV _{DD} = 3V		113		μΑ
	$\overline{PDWN} = 0$		1		nA
Power Dissipation	PGA = 1, Buffer OFF, REFEN = 0,		0.8	1.4	mW
	IDACs OFF, DV _{DD} = 3V				

NOTES: (1) FSR is Full-Scale Range. (2) ΔV_{OUT} is change in digital result. (3) 12pF switched capacitor at f_{SAMP} clock frequency.

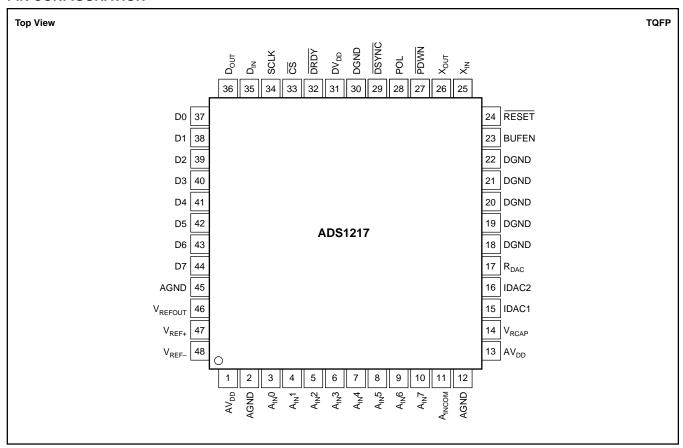
ELECTRICAL CHARACTERISTICS: Digital

All specifications at -40° C to $+85^{\circ}$ C, and DV_{DD} = +2.7V to 5.25V.

PARAMETER	CONDITIONS	MIN	TYP	MAX	UNITS
INPUT/OUTPUT					
Logic Level					
V_{IH}		$0.8 \times DV_{DD}$		DV_DD	V
$V_{ m IH}$ $V_{ m IL}^{(1)}$		DGND		$0.2 \times DV_{DD}$	V
V _{OH}	$I_{OH} = 1mA$	$DV_{DD} - 0.4$			V
V _{OL}	I _{OL} = 1mA	DGND		DGND + 0.4	V
Input Leakage: I _{IN}	$0 < V_I < DV_{DD}$	-10		10	μΑ
CLOCK RATES					
Master Clock Rate: f _{OSC}		1		8	MHz
Master Clock Period: t _{OSC}	1/f _{OSC}	125		1000	ns

NOTE: (1) Maximum V_{IL} for X_{IN} is DGND + 0.05V.

PIN CONFIGURATION

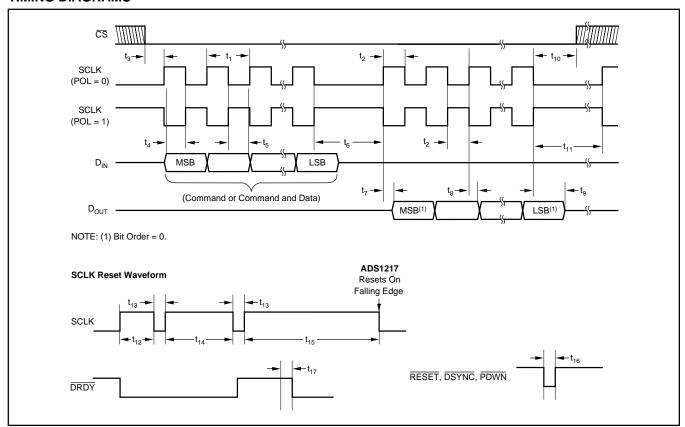


PIN DESCRIPTIONS

PIN NUMBER	NAME	DESCRIPTION	PIN NUMBER	NAME	DESCRIPTION
1	AV_{DD}	Analog Power Supply	25	X _{IN}	Clock Input
2	AGND	Analog Ground	26	X _{OUT}	Clock Output, used with crystal or resonator.
3	A _{IN} 0	Analog Input 0	27	PDWN	Active LOW. Power Down. The power-down
4	A _{IN} 1	Analog Input 1			function shuts down the analog and digital
5	A _{IN} 2	Analog Input 2			circuits.
6	A _{IN} 3	Analog Input 3	28	POL	Serial Clock Polarity Input
7	A _{IN} 4	Analog Input 4	29	DSYNC	Active LOW, Synchronization Control Input
8	A _{IN} 5	Analog Input 5	30	DGND	Digital Ground
9	A _{IN} 6	Analog Input 6	31	DV_DD	Digital Power Supply
10	A _{IN} 7	Analog Input 7	32	DRDY	Active LOW, Data Ready Output
11	A _{INCOM}	Analog Input Common	33	cs	Active LOW, Chip Select Input
12	AGND	Analog Ground	34	SCLK	Serial Clock, Schmitt Trigger
13	AV _{DD}	Analog Power Supply	35	D _{IN}	Serial Data Input, Schmitt Trigger
14	V _{RCAP}	V _{REFOUT} Bypass Capacitor	36	D _{OUT}	Serial Data Output
15	IDAC1	Current DAC1 Output	37-44	D0-D7	Digital I/O 0-7
16	IDAC1	Current DAC2 Output	45	AGND	Analog Ground
17	-	Current DAC Resistor	46	V _{REFOUT}	Voltage Reference Output
18-22	R _{DAC} DGND	Digital Ground	47	V _{REF+}	Positive Differential Reference Input
23	BUFEN	5	48	V _{REF}	Negative Differential Reference Input
· ·		Buffer Enable Input			
24	RESET	Active LOW, resets the entire chip.			



TIMING DIAGRAMS



TIMING CHARACTERISTICS

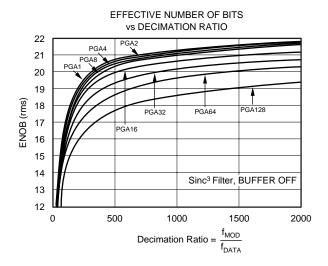
SPEC	DESCRIPTION	MIN	MAX	UNITS
t ₁	SCLK Period	4	2	t _{OSC} Periods DRDY Periods
	SCLIX Bules Width LUCLI and LOW	200	3	
t ₂	SCLK Pulse Width, HIGH and LOW	200		ns
t ₃	CS LOW to First SCLK Edge; Setup Time ⁽¹⁾	0		ns
t ₄	D _{IN} Valid to SCLK Edge; Setup Time	50		ns
t ₅	Valid D _{IN} to SCLK Edge; Hold Time	50		ns
t ₆	Delay Between Last SCLK Edge for D _{IN} and First SCLK			
	Edge for D _{OUT} :			
	RDATA, RDATAC, RREG, WREG, RRAM, WRAM	50		t _{OSC} Periods
	CSREG, CSRAMX, CSRAM	200		t _{OSC} Periods
	CSARAM, CSARAMX	1100		t _{OSC} Periods
t ₇ ⁽²⁾	SCLK Edge to Valid New D _{OUT}		50	ns
t ₈ (2)	SCLK Edge to D _{OUT} , Hold Time	0		ns
t ₉	Last SCLK Edge to D _{OUT} Tri-State	6	10	t _{OSC} Periods
	NOTE: D _{OUT} goes tri-state immediately when $\overline{\text{CS}}$ goes HIGH.			
t ₁₀	CS LOW Time After Final SCLK Edge	0		ns
t ₁₁	Final SCLK Edge of One Op Code Until First Edge SCLK			
	of Next Command:			
	RREG, WREG, RRAM, WRAM, CSRAMX, CSARAMX,			t _{OSC} Periods
	CSRAM, CSARAM, CSREG, DSYNC, SLEEP, RDATA,			
	RDATAC, STOPC	4		t _{OSC} Periods
	CREG, CRAM	220		t _{OSC} Periods
	CREGA	1600		t _{OSC} Periods
	SELFGCAL, SELFOCAL, SYSOCAL, SYSGCAL	7		DRDY Periods
	SELFCAL	14		DRDY Periods
	RESET (Input pin, command, or SCLK pattern)	16		t _{OSC} Periods
t ₁₂		300	500	t _{OSC} Periods
t ₁₃		5		t _{OSC} Periods
t ₁₄		550	750	t _{OSC} Periods
t ₁₅		1050	1250	t _{OSC} Periods
t ₁₆	Pulse Width	4		t _{OSC} Periods
t ₁₇	Data Not Valid	4		t _{OSC} Periods

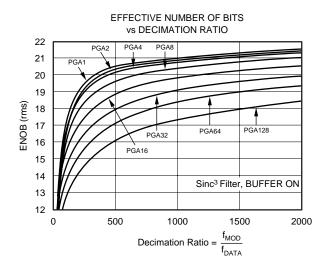
NOTES: (1) \overline{CS} may be tied LOW. (2) Load = 20pF.

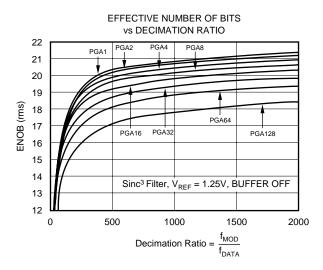


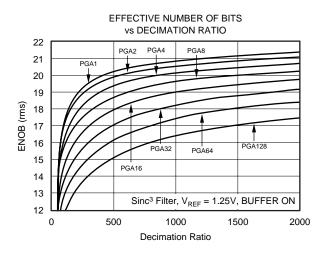
TYPICAL CHARACTERISTICS

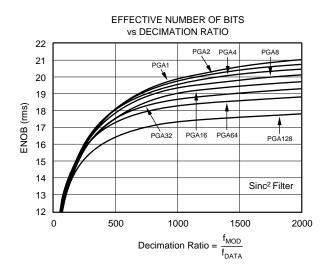
 $AV_{DD} = +5V, \ DV_{DD} = +5V, \ f_{OSC} = 2.4576MHz, \ PGA = 1, \ R_{DAC} = 150k\Omega, \ f_{DATA} = 10Hz, \ and \ V_{REF} = +2.5V, \ unless \ otherwise \ specified.$

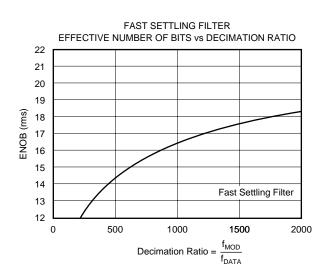






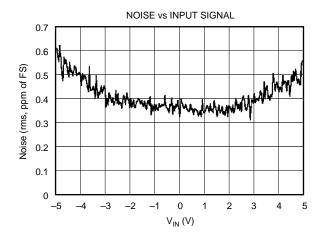


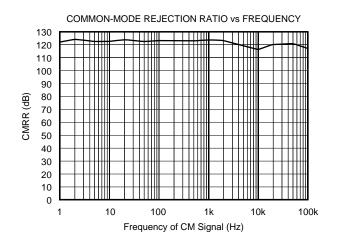


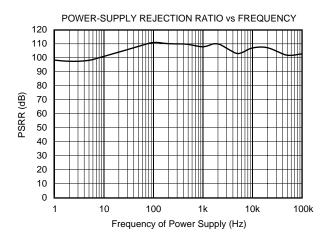


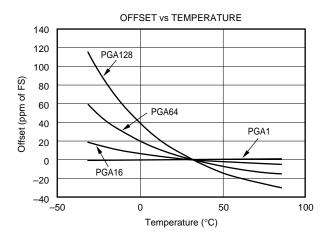
TYPICAL CHARACTERISTICS (Cont.)

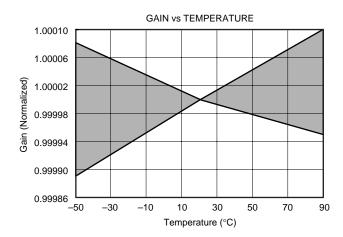
 $AV_{DD} = +5V, \ DV_{DD} = +5V, \ f_{OSC} = 2.4576MHz, \ PGA = 1, \ R_{DAC} = 150k\Omega, \ f_{DATA} = 10Hz, \ and \ V_{REF} = +2.5V, \ unless \ otherwise \ specified.$

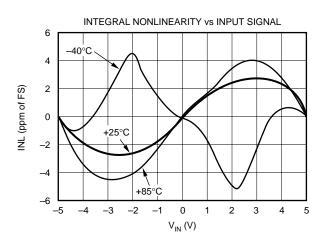








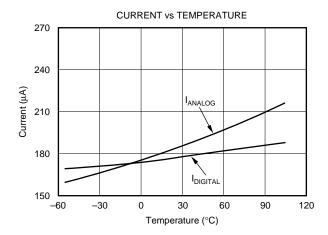


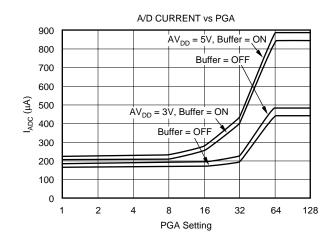


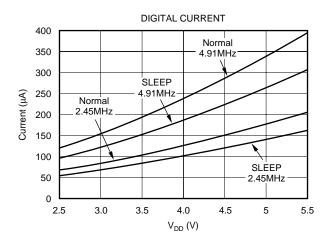


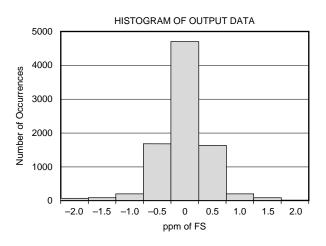
TYPICAL CHARACTERISTICS (Cont.)

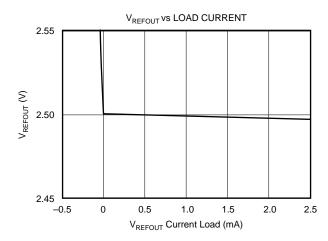
 $AV_{DD} = +5V,\ DV_{DD} = +5V,\ f_{OSC} = 2.4576MHz,\ PGA = 1,\ R_{DAC} = 150k\Omega,\ f_{DATA} = 10Hz,\ and\ V_{REF} = +2.5V,\ unless\ otherwise\ specified.$

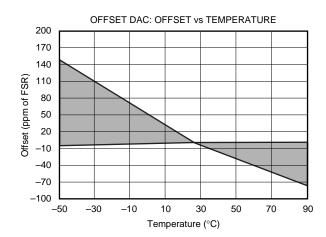






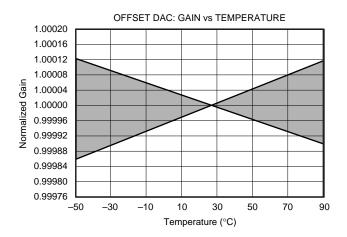


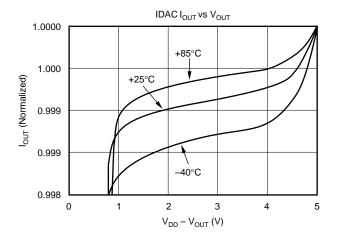


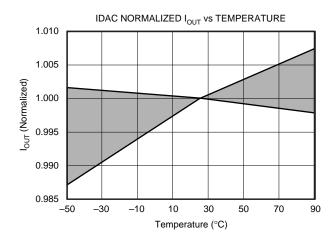


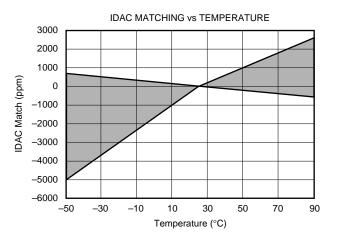
TYPICAL CHARACTERISTICS (Cont.)

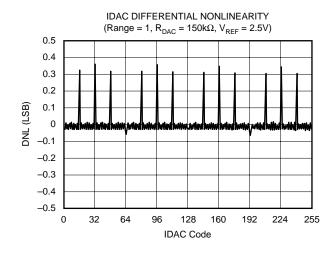
 $AV_{DD} = +5V, \ DV_{DD} = +5V, \ f_{OSC} = 2.4576MHz, \ PGA = 1, \ R_{DAC} = 150k\Omega, \ f_{DATA} = 10Hz, \ and \ V_{REF} = +2.5V, \ unless \ otherwise \ specified.$

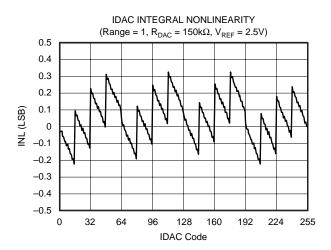












OVERVIEW

INPUT MULTIPLEXER

The input multiplexer (mux) provides for any combination of differential inputs to be selected on any of the input channels, as shown in Figure 1. If channel 1 is selected as the positive differential input channel, any other channel can be selected as the negative differential input channel. With this method, it is possible to have up to eight fully differential input channels.

In addition, current sources are supplied that will source or sink current to detect open or short circuits on the pins.

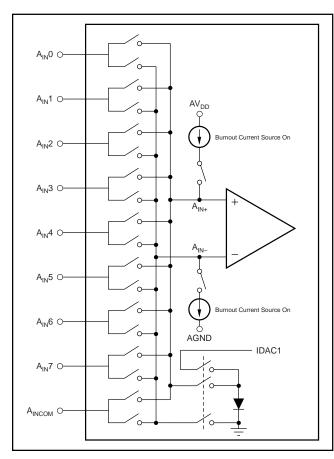


FIGURE 1. Input Multiplexer Configuration.

TEMPERATURE SENSOR

An on-chip diode provides temperature sensing capability. When the configuration register for the input MUX is set to all 1s, the diode is connected to the input of the A/D converter. All other channels are open. The anode of the diode is connected to the positive input of the A/D converter, and the cathode of the diode is connected to negative input of the A/D converter. The output of IDAC1 is connected to the anode to bias the diode and the cathode of the diode is also connected to ground to complete the circuit.

In this mode, the output of IDAC1 is also connected to the output pin, so some current may flow into an external load from IDAC1, rather than the diode. See Application Report *Measuring Temperature with the ADS1216, ADS1217, or ADS1218* (SBAA073) for more information.

BURNOUT CURRENT SOURCES

When the Burnout bit is set in the ACR configuration register, two current sources are enabled. The current source on the positive input channel sources approximately $2\mu A$ of current. The current source on the negative input channel sinks approximately $2\mu A$. This allows for the detection of an open circuit (full-scale reading) or short circuit (0V differential reading) on the selected input differential pair.

INPUT BUFFER

The input impedance of the ADS1217 without the buffer is $10M\Omega/PGA$. With the buffer enabled, the input voltage range is reduced and the analog power-supply current is higher. The buffer is controlled by ANDing the state of the buffer pin with the state of the BUFFER bit in the ACR register. See Application Report *Input Currents for High-Resolution ADCs* (SBAA090) for more information.

IDAC1 AND IDAC2

The ADS1217 has two 8-bit current output DACs that can be controlled independently. The output current is set with R_{DAC} , the range select bits in the ACR register, and the 8-bit digital value in the IDAC register. The output current = $(V_{REF}/8R_{DAC})\ (2^{RANGE-1})\ (DAC\ CODE).$ With V_{REFOUT} = 2.5V and R_{DAC} = 150k Ω , the full-scale output can be selected to be 0.5, 1, or 2mA. The compliance voltage range is AGND to within 1V of AV $_{DD}$. When the internal voltage reference of the ADS1217 is used, it is the reference for the IDAC. An external reference may be used for the IDACs by disabling the internal reference and tying the external reference input to the V_{REFOUT} pin.

PGA

The PGA can be set to gains of 1, 2, 4, 8, 16, 32, 64, or 128. Using the PGA can improve the effective resolution of the A/D converter. For instance, with a PGA of 1 on a 10V full-scale range, the A/D converter can resolve to $2\mu V$. With a PGA of 128 on a 80mV full-scale range, the A/D converter can resolve to 150nV.

PGA OFFSET DAC

The input to the PGA can be shifted by half the full-scale input range of the PGA by using the ODAC register. The ODAC (Offset DAC) register is an 8-bit value; the MSB is the sign and the seven LSBs provide the magnitude of the offset. Using the ODAC does not reduce the performance of the A/D converter. See Application Report *The Offset DAC* (SBAA077) for more information.

MODULATOR

The modulator is a single-loop, 2nd-order system. The modulator runs at a clock speed (f_{MOD}) that is derived from the external clock (f_{OSC}). The frequency division is determined by the SPEED bit in the setup register.

SPEED BIT	f _{MOD}
0	f _{OSC} /128
1	f _{OSC} /256

VOLTAGE REFERENCE INPUT

The ADS1217 uses a differential voltage reference input. The input signal is measured against the differential voltage $V_{REF} \equiv (V_{REF+}) - (V_{REF-})$. For $AV_{DD} = 5V$, V_{REF} is typically 2.5V. For $AV_{DD} = 3V$, V_{REF} is typically 1.25V. Due to the sampling nature of the modulator, the reference input current increases with higher modulator clock frequency (f_{MOD}) and higher PGA settings.

ON-CHIP VOLTAGE REFERENCE

A selectable voltage reference (1.25V or 2.5V) is available for supplying the voltage reference input. To use, connect $V_{\text{REF-}}$ to AGND and $V_{\text{REF+}}$ to $V_{\text{REFOUT}}.$ The enabling and voltage selection are controlled through bits REF EN and REF HI in the setup register. The 2.5V reference requires $AV_{DD}=5V.$ When using the on-chip voltage reference, the V_{REFOUT} pin should be bypassed with a 0.1µF capacitor to AGND.

V_{RCAP} PIN

This pin provides a bypass cap for noise filtering on internal V_{REF} circuitry only. As this is a sensitive pin, place the capacitor as close as possible and avoid any resistive loading. The recommended capacitor is a $0.001\mu F$ ceramic cap. If an external V_{REF} is used, this pin can be left unconnected.

CLOCK GENERATOR

The clock source for the ADS1217 can be provided from a crystal, oscillator, or external clock. When the clock source is a crystal, external capacitors must be provided to ensure startup and a stable clock frequency; see Figure 2 and Table I.

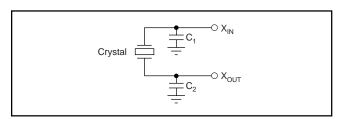


FIGURE 2. Crystal Connection.

CLOCK	FREQUENCY	C ₁	C ₂	PART NUMBER
Crysta	2.4576	0-20pF	0-20pF	ECS, ECSD 2.45 - 32
Crysta	4.9152	0-20pF	0-20pF	ECS, ECSL 4.91
Crysta	4.9152	0-20pF	0-20pF	ECS, ECSD 4.91
Crysta	4.9152	0-20pF	0-20pF	CTS, MP 042 4M9182

TABLE I. Typical Clock Sources.

CALIBRATION

The offset and gain errors in the ADS1217, or the complete system, can be reduced with calibration. Internal calibration of the ADS1217 is called self calibration. This is handled with three commands. One command does both offset and gain calibration. There is also a gain calibration command and an offset calibration command. Each calibration process takes seven t_{DATA} periods to complete. It takes 14 t_{DATA} periods to

complete both an offset and gain calibration. Self-gain calibration is optimized for PGA gains less than 8. When using higher gains, system gain calibration is recommended.

For system calibration, the appropriate signal must be applied to the inputs. The system offset command requires a "zero" differential input signal. It then computes an offset that will nullify offset in the system. The system gain command requires a positive "full-scale" differential input signal. It then computes a value to nullify gain errors in the system. Each of these calibrations will take seven t_{DATA} periods to complete.

Calibration must be performed after power on, a change in decimation ratio, or a change of the PGA. For operation with a reference voltage greater than $(AV_{DD}-1.5V)$, the buffer must also be turned off during calibration.

At the completion of calibration, the \overline{DRDY} signal goes LOW, which indicates the calibration is finished and valid data is available. See Application Report Calibration Routine and Register Value Generation for the ADS121x Series (SBAA099) for more information.

DIGITAL FILTER

The Digital Filter can use either the fast settling, sinc², or sinc³ filter, as shown in Figure 3. In addition, the Auto mode changes the sinc filter after the input channel or PGA is changed. When switching to a new channel, it will use the fast settling filter; It will then use the sinc² followed by the sinc³ filter. This combines the low-noise advantage of the sinc³ filter with the quick response of the fast settling time filter. See Figure 4 for the frequency response of each filter.

When using the fast setting filter, select a decimation value set by the DEC0 and M/DEC1 registers that is evenly divisible by four for the best gain accuracy. For example, choose 260 rather than 261.

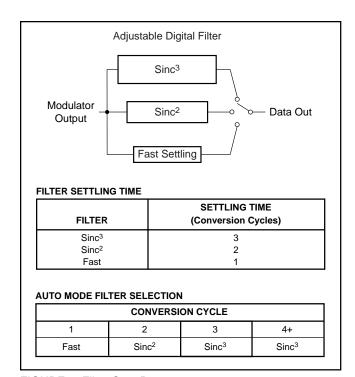


FIGURE 3. Filter Step Responses.



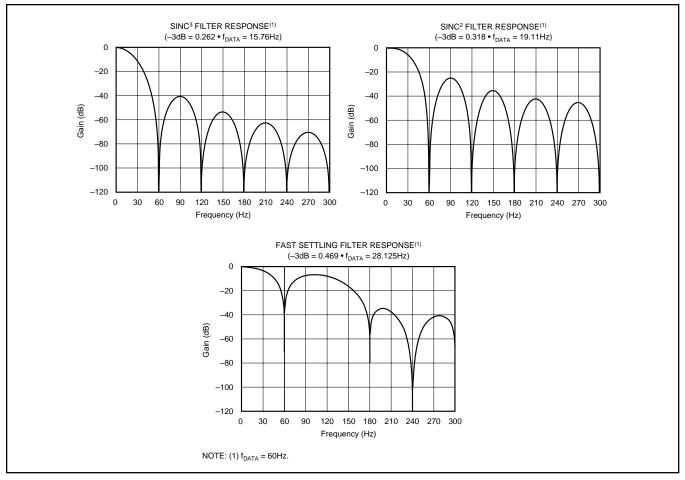


FIGURE 4. Filter Frequency Responses.

DIGITAL I/O INTERFACE

The ADS1217 has eight pins dedicated for digital I/O. The default power-up condition for the digital I/O pins are as inputs. All of the digital I/O pins are individually configurable as inputs or outputs. They are configured through the DIR control register. The DIR register defines whether the pin is an input or output, and the DIO register defines the state of the digital output. When the digital I/O are configured as inputs, DIO is used to read the state of the pin. If the digital I/O are not used, either 1) configure as outputs; or, 2) leave as inputs and tie to ground, this prevents excess power dissipation.

SERIAL PERIPHERAL INTERFACE

The Serial Peripheral Interface (SPI) allows a controller to communicate synchronously with the ADS1217. The ADS1217 operates in slave only mode.

Chip Select (CS)

The chip select (\overline{CS}) input of the ADS1217 must be externally asserted before a master device can exchange data with the ADS1217. \overline{CS} must be LOW for the duration of the transaction. \overline{CS} can be tied low.

Serial Clock (SCLK)

SCLK, a Schmitt Trigger input, clocks data transfer on the D_{IN} input and D_{OUT} output. When transferring data to or from the ADS1217, multiple bits of data may be transferred back-to-

back with no delay in SCLKs or toggling of $\overline{\text{CS}}$. Make sure to avoid glitches on SCLK as they can cause extra shifting of the data.

Polarity (POL)

The serial clock polarity is specified by the POL input. When SCLK is active HIGH, set POL HIGH. When SCLK is active LOW, set POL LOW.

DATA READY

The DRDY output is used as a status signal to indicate when data is ready to be read from the ADS1217. DRDY goes LOW when new data is available. It is reset HIGH when a read operation from the data register is complete. It also goes HIGH prior to the updating of the output register to indicate when not to read from the device to ensure that a data read is not attempted while the register is being updated.

DSYNC OPERATION

DSYNC is used to provide for synchronization of the A/D conversion with an external event. Synchronization can be achieved either through the $\overline{\text{DSYNC}}$ pin or the DSYNC command. When the $\overline{\text{DSYNC}}$ pin is used, the filter counter is reset on the falling edge of $\overline{\text{DSYNC}}$. The modulator is held in reset until $\overline{\text{DSYNC}}$ is taken HIGH. Synchronization occurs on the next rising edge of the system clock after $\overline{\text{DSYNC}}$ is taken HIGH.



When the DSYNC command is sent, the filter counter is reset on the edge of the last SCLK on the DSYNC command. The modulator is held in reset until the next edge of SCLK is detected. Synchronization occurs on the next rising edge of the system clock after the first SCLK after the DSYNC command. After a DSYNC operation, \overline{DRDY} is held HIGH until valid data is ready.

RESET

There are three methods to reset the ADS1217: the RESET input, the RESET command, and a special SCLK input pattern. When using the RESET input, take it LOW to force a reset. Make sure to follow the minimum pulse width timing specifications before taking the RESET input back high. Also, avoid glitches on the RESET input as these may cause accidental resets. The RESET command takes effect after all 8 bits have been shifted into DIN. Afterwards, the reset releases automatically. The ADS1217 can also be reset with a special pattern on SCLK, see the Timing Diagram. Reset occurs on the falling edge of the last SCLK edge in the pattern (for POL = 0). Afterwards, the reset releases automatically.

POWER-UP—SUPPLY VOLTAGE RAMP RATE

The power-on reset circuitry was designed to accommodate digital supply ramp rates as slow as 1V/10ms. To ensure proper operation, the power supply should ramp monotonically.

MEMORY

Two types of memory are used on the ADS1217: registers and RAM. 16 registers directly control the various functions (PGA, DAC value, Decimation Ratio, etc.) and can be directly read or written. Collectively, the registers contain all the information needed to configure the part, such as data format, mux settings, calibration settings, decimation ratio, etc. Additional registers, such as output data, are accessed through dedicated instructions.

REGISTER BANK TOPOLOGY

The operation of the device is set up through individual registers. The set of the 16 registers required to configure the device is referred to as a Register Bank, as shown in Figure 5.

Reads and Writes to Registers and RAM occur on a byte basis. However, copies between registers and RAM occurs on a bank basis. The RAM is independent of the Registers; that is, the RAM can be used as general-purpose RAM.

The ADS1217 supports any combination of eight analog inputs. With this flexibility, the device could easily support eight unique configurations—one per input channel. In order to facilitate this type of usage, eight separate register banks are available. Therefore, each configuration could be written once and recalled as needed without having to serially retransmit all the configuration data. Checksum commands are also included, which can be used to verify the integrity of RAM.

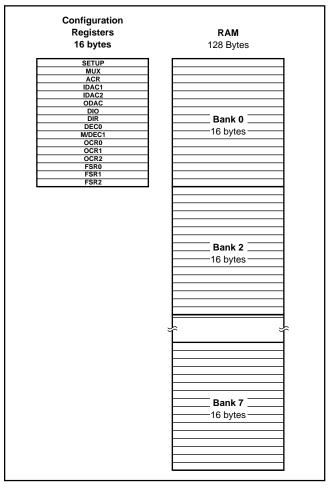


FIGURE 5. Memory Organization.

The RAM provides eight "banks", with a bank consisting of 16 bytes. The total size of the RAM is 128 bytes. Copies between the registers and RAM are performed on a bank basis. Also, the RAM can be directly read or written through the serial interface on power-up. The banks allow separate storage of settings for each input.

The RAM address space is linear, therefore accessing RAM is done using an auto-incrementing pointer. Access to RAM in the entire memory map can be done consecutively without having to address each bank individually. For example, if you were currently accessing bank 0 at offset 0F $_{\rm H}$ (the last location of bank 0), the next access would be bank 1 and offset 00 $_{\rm H}$. Any access after bank 7 and offset 0F $_{\rm H}$ will wrap around to bank 0 and Offset 00 $_{\rm H}$.

Although the Register Bank memory is linear, the concept of addressing the device can also be thought of in terms of bank and offset addressing. Looking at linear and bank addressing syntax, we have the following comparison: in the linear memory map, the address 14_H is equivalent to bank 1 and offset 04_H. Simply stated, the most significant four bits represent the bank, and the least significant four bits represent the offset. The offset is equivalent to the register address for that bank of memory.



REGISTER MAP

ADDRESS	REGISTER	BIT 7	BIT 6	BIT 5	BIT 4	BIT 3	BIT 2	BIT 1	BIT 0
00 _H	SETUP	ID	ID	ID	SPEED	REF EN	REF HI	BUF EN	BIT ORDER
01 _H	MUX	PSEL3	PSEL2	PSEL1	PSEL0	NSEL3	NSEL2	NSEL1	NSEL0
02 _H	ACR	BOCS	IDAC2R1	IDAC2R0	IDAC1R1	IDAC1R0	PGA2	PGA1	PGA0
03 _H	IDAC1	IDAC1_7	IDAC1_6	IDAC1_5	IDAC1_4	IDAC1_3	IDAC1_2	IDAC1_1	IDAC1_0
04 _H	IDAC2	IDAC2_7	IDAC2_6	IDAC2_5	IDAC2_4	IDAC2_3	IDAC2_2	IDAC2_1	IDAC2_0
05 _H	ODAC	SIGN	OSET_6	OSET_5	OSET_4	OSET_3	OSET_2	OSET_1	OSET_0
06 _H	DIO	DIO_7	DIO_6	DIO_5	DIO_4	DIO_3	DIO_2	DIO_1	DIO_0
07 _H	DIR	DIR_7	DIR_6	DIR_5	DIR_4	DIR_3	DIR_2	DIR_1	DIR_0
08 _H	DEC0	DEC07	DEC06	DEC05	DEC04	DEC03	DEC02	DEC01	DEC00
09 _H	M/DEC1	DRDY	U/B	SMODE1	SMODE0	Reserved	DEC10	DEC09	DEC08
0A _H	OCR0	OCR07	OCR06	OCR05	OCR04	OCR03	OCR02	OCR01	OCR00
0B _H	OCR1	OCR15	OCR14	OCR13	OCR12	OCR11	OCR10	OCR09	OCR08
0C _H	OCR2	OCR23	OCR22	OCR21	OCR20	OCR19	OCR18	OCR17	OCR16
0D _H	FSR0	FSR07	FSR06	FSR05	FSR04	FSR03	FSR02	FSR01	FSR00
0E _H	FSR1	FSR15	FSR14	FSR13	FSR12	FSR11	FSR10	FSR09	FSR08
0F _H	FSR2	FSR23	FSR22	FSR21	FSR20	FSR19	FSR18	FSR17	FSR16

TABLE II. Registers.

DETAILED REGISTER DEFINITIONS

 $\textbf{SETUP} \; (\text{Address} \; \mathbf{00_H}) \; \text{Setup} \; \text{Register}$

Reset Value = iii01110

bit 7	bit 6	bit 5	bit 4	bit 3	bit 2	bit 1	bit 0
ID	ID	ID	SPEED	REF EN	REF HI	BUF EN	BIT ORDER

bit 7-5 Factory Programmed Bits

bit 4 SPEED: Modulator Clock Speed

 $0: f_{MOD} = f_{OSC}/128 \text{ (default)}$

1: $f_{MOD} = f_{OSC}/256$

bit 3 REF EN: Internal Voltage Reference Enable

0 = Internal Voltage Reference Disabled

1 = Internal Voltage Reference Enabled (default)

bit 2 REF HI: Internal Reference Voltage Select

0 = Internal Reference Voltage = 1.25V

1 = Internal Reference Voltage = 2.5V (default)

bit 1 BUF EN: Buffer Enable

0 = Buffer Disabled

1 = Buffer Enabled (default)

bit 0 BIT ORDER: Set Order Bits are Transmitted

0 = Most Significant Bit Transmitted First (default)

1 = Least Significant Bit Transmitted First

Data is always shifted into the part most significant bit first. Data is always shifted out of the part most significant byte first. This configuration bit only controls the bit order within the byte of data that is shifted out.

MUX (Address 01_H) Multiplexer Control Register

Reset Value = 01_H

bit 7	bit 6	bit 5	bit 4	bit 3	bit 2	bit 1	bit 0
PSEL3	PSEL2	PSEL1	PSEL0	NSEL3	NSEL2	NSEL1	NSEL0

bit 7-4 PSEL3: PSEL2: PSEL1: PSEL0: Positive Channel

Select

0000 = AIN0 (default)

0001 = AIN1

0010 = AIN2

0011 = AIN3

0100 = AIN4

0101 = AIN5

0110 = AIN60111 = AIN7

1xxx = AINCOM (except when all bits are 1s)

1111 = Temperature Sensor Diode

bit 3-0 NSEL3: NSEL2: NSEL1: NSEL0: Negative Channel

Select

0000 = AIN0

0001 = AIN1 (default)

0010 = AIN2

0011 = AIN3

0100 = AIN4

0101 = AIN5

0110 = AIN6

0111 = AIN7

1xxx = AINCOM (except when all bits are 1s)

1111 = Temperature Sensor Diode



ACR (Address 02_H) Analog Control Register

Reset Value = 00_H

bit 7	bit 6	bit 5	bit 4	bit 3	bit 2	bit 1	bit 0
BOCS	IDAC2R1	IDAC2R0	IDAC1R1	IDAC1R0	PGA2	PGA1	PGA0

bit 7 BOCS: Burnout Current Source

0 = Disabled (default)

1 = Enabled

IDAC Current =
$$\left(\frac{V_{REF}}{8R_{DAC}}\right) (2^{RANGE-1}) (DAC Code)$$

bit 6-5 IDAC2R1: IDAC2R0: Full-Scale Range Select for IDAC2

00 = Off (default)

01 = Range 1

10 = Range 2

11 = Range 3

bit 4-3 IDAC1R1: IDAC1R0: Full-Scale Range Select for IDAC1

00 = Off (default)

01 = Range 1

10 = Range 2

11 = Range 3

bit 2-0 PGA2: PGA1: PGA0: Programmable Gain Amplifier Gain Selection

000 = 1 (default)

001 = 2

010 = 4

011 = 8

100 = 16

100 = 10 101 = 32

110 = 64

111 = 128

IDAC1 (Address 03_H) Current DAC 1

Reset Value = 00_H

bit 7	bit 6	bit 5	bit 4	bit 3	bit 2	bit 1	bit 0
IDAC1_7	IDAC1_6	IDAC1_5	IDAC1_4	IDAC1_3	IDAC1_2	IDAC1_1	IDAC1_0

The DAC code bits set the output of DAC1 from 0 to full-scale. The value of the full-scale current is set by this Byte, V_{REF} , R_{DAC} , and the DAC1 range bits in the ACR register.

IDAC2 (Address 04_H) Current DAC 2

Reset Value = 00_H

bit 7	bit 6				bit 2		bit 0
IDAC2_7	IDAC2_6	IDAC2_5	IDAC2_4	IDAC1_3	IDAC1_2	IDAC1_1	IDAC1_0

The DAC code bits set the output of DAC2 from 0 to full-scale. The value of the full-scale current is set by this Byte, V_{REF} , R_{DAC} , and the DAC2 range bits in the ACR register.

ODAC (Address 05_H) Offset DAC Setting

Reset Value = 00_H

bit 7	bit 6	bit 5	bit 4	bit 3	bit 2	bit 1	bit 0
SIGN	OSET6	OSET5	OSET4	OSET3	OSET2	OSET1	OSET0

bit 7 Offset Sign

0 = Positive

1 = Negative

bit 6-0 Offset =
$$\frac{V_{REF}}{PGA} \cdot \left(\frac{Code}{127}\right)$$

NOTE: The offset must be used after calibration or the calibration will notify the effects.

DIO (Address 06_H) Digital I/O

Reset Value = 00_H

bit 7	bit 6	bit 5	bit 4	bit 3	bit 2	bit 1	bit 0
DIO7	DIO6	DIO5	DIO4	DIO3	DIO2	DIO1	DIO0

A value written to this register will appear on the digital I/O pins if the pin is configured as an output in the DIR register. Reading this register will return the value of the digital I/O pins.

DIR (Address 07_H) Direction control for digital I/O

Reset Value = FF_H

bit 7	bit 6	bit 5	bit 4	bit 3	bit 2	bit 1	bit 0
DIR7	DIR6	DIR5	DIR4	DIR3	DIR2	DIR1	DIR0

Each bit controls whether the Digital I/O pin is an output (= 0) or input (= 1). The default power-up state is as inputs.

DEC0 (Address 08_H) Decimation Register (Least Significant 8 bits)

Reset Value = 80_H

bit 7	bit 6	bit 5	bit 4	bit 3	bit 2	bit 1	bit 0
DEC07	DEC06	DEC05	DEC04	DEC03	DEC02	DEC01	DEC00

The decimation value is defined with 11 bits for a range of 20 to 2047. This register is the least significant 8 bits. The 3 most significant bits are contained in the M/DEC1 register. The default data rate is 10Hz with a 2.4576MHz crystal.

M/DEC1 (Address 09_H) Mode and Decimation Register Reset Value = 07_H

bit 7	bit 6	bit 5	bit 4	bit 3	bit 2	bit 1	bit 0
DRDY	U/B	SMODE1	SMODE0	Reserved	DEC10	DEC09	DEC08

bit 7 DRDY: Data Ready (Read Only)

This bit duplicates the state of the DRDY pin.

bit 6 U/B: Data Format

0 = Bipolar (default)

1 = Unipolar

U/B	ANALOG INPUT	DIGITAL OUTPUT
	+FS	0x7FFFFF
0	Zero	0x000000
	–FS	0x800000
	+FS	0xFFFFFF
1	Zero	0x000000
	–FS	0x000000

bit 5-4 SMODE1: SMODE0: Settling Mode

00 = Auto (default)

01 = Fast Settling filter

 $10 = Sinc^2$ filter

 $11 = Sinc^3$ filter

bit 2-0 DEC10: DEC09: DEC08: Most Significant Bits of

the Decimation Value

OCR0 (Address 0A_H) Offset Calibration Coefficient (Least Significant Byte)

Reset Value = 00_H

bit 7	bit 6	bit 5	bit 4	bit 3	bit 2	bit 1	bit 0
OCR07	OCR06	OCR05	OCR04	OCR03	OCR02	OCR01	OCR00

OCR1 (Address 0B_H) Offset Calibration Coefficient (Middle Byte)

Reset Value = 00_H

bit 7	bit 6	bit 5	bit 4	bit 3	bit 2	bit 1	bit 0
OCR15	OCR14	OCR13	OCR12	OCR11	OCR10	OCR09	OCR08

OCR2 (Address 0C_H) Offset Calibration Coefficient (Most Significant Byte)

Reset Value = 00_H

bit 7	bit 6	bit 5	bit 4	bit 3	bit 2	bit 1	bit 0
OCR23	OCR22	OCR21	OCR20	OCR19	OCR18	OCR17	OCR16

FSR0 (Address 0D_H) Full-Scale Register

(Least Significant Byte)

Reset Value = 24_H

bit 7	bit 6	bit 5	bit 4	bit 3	bit 2	bit 1	bit 0
FSR07	FSR06	FSR05	FSR04	FSR03	FSR02	FSR01	FSR00

FSR1 (Address 0E_H) Full-Scale Register

(Middle Byte)

Reset Value = 90_H

bit 7	bit 6	bit 5	bit 4	bit 3	bit 2	bit 1	bit 0
FSR15	FSR14	FSR13	FSR12	FSR011	FSR10	FSR09	FSR08

FSR2 (Address $0F_H$) Full-Scale Register

(Most Significant Byte)

Reset Value = 67_H

bit 7	bit 6	bit 5	bit 4	bit 3	bit 2	bit 1	bit 0
FSR23	FSR22	FSR21	FSR20	FSR019	FSR18	FSR17	FSR16

COMMAND DEFINITIONS

The commands listed below control the operation of the ADS1217. Some of the commands are stand-alone commands (e.g., RESET) while others require additional bytes (e.g., WREG requires command, count, and the data bytes). Commands that output data require a minimum of four f_{OSC} cycles before the data is ready (e.g., RDATA).

Operands:

n = count (0 to 127)

r = register (0 to 15)

x = don't care

a = RAM bank address (0 to 7)

COMMANDS	DESCRIPTION	COMMAND BYTE	2ND COMMAND BYTE
RDATA	Read Data	0000 0001 (01 _H)	_
RDATAC	Read Data Continuously	0000 0011 (03 _H)	_
STOPC	Stop Read Data Continuously	0000 1111 (0F _H)	_
RREG	Read from REG Bank rrrr	0001 rrrr (1x _H)	xxxx_nnnn (# of reg-1)
RRAM	Read from RAM Bank aaa	0010 0aaa (2x _H)	xnnn_nnnn (# of bytes-1)
CREG	Copy REGs to RAM Bank aaa	0100 0aaa (4x _H)	_
CREGA	Copy REGS to all RAM Banks	0100 1000 (48 _H)	_
WREG	Write to REG rrrr	0101 rrrr (5x _H)	xxxx_nnnn (# of reg-1)
WRAM	Write to RAM Bank aaa	0110 0aaa (6x _H)	xnnn_nnnn (# of bytes-1)
CRAM	Copy RAM Bank aaa to REG	1100 0aaa (Cx _H)	_
CSRAMX	Calc RAM Bank aaa Checksum	1101 0aaa (Dx _H)	_
CSARAMX	Calc all RAM Bank Checksum	1101 1000 (D8 _H)	_
CSREG	Calc REG Checksum	1101 1111 (DF _H)	_
CSRAM	Calc RAM Bank aaa Checksum	1110 0aaa (Ex _H)	_
CSARAM	Calc all RAM Banks Checksum	1110 1000 (E8 _H)	_
SELFCAL	Self Cal Offset and Gain	1111 0000 (F0 _H)	_
SELFOCAL	Self Cal Offset	1111 0001 (F1 _H)	_
SELFGCAL	Self Cal Gain	1111 0010 (F2 _H)	_
SYSOCAL	Sys Cal Offset	1111 0011 (F3 _H)	_
SYSGCAL	Sys Cal Gain	1111 0100 (F4 _H)	_
WAKEUP	Wake Up From Sleep Mode	1111 1011 (FB _H)	_
DSYNC	Sync DRDY	1111 1100 (FC _H)	_
SLEEP	Put in Sleep Mode	1111 1101 (FD _H)	_
RESET	Reset to Power-Up Values	1111 1110 (FE _H)	_

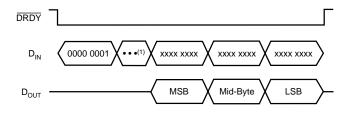
TABLE III. Command Summary.

RDATA Read Data

Description: Read a single 24-bit ADC conversion result. On completion of read back, \overline{DRDY} goes HIGH.

Operands: None Bytes: 1

Encoding: 0000 0001 **Data Transfer Sequence:**



RDATAC

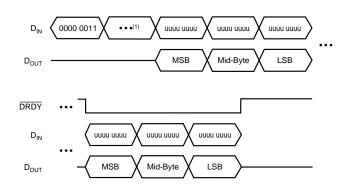
Read Data Continuous

Description: Read Data Continuous mode enables the continuous output of new data on each \overline{DRDY} . This command eliminates the need to send the Read Data Command on each \overline{DRDY} . This mode may be terminated by either the STOP Read Continuous command or the RESET command.

Operands: None Bytes: 1

Encoding: 0000 0011 **Data Transfer Sequence:**

Command terminated when *uuuu uuuu* equals STOPC or RESET.



NOTE: (1) For wait time, refer to timing specification.



STOPC

Stop Continuous

CREG Copy Registers to RAM Bank

Description: Ends the continuous data output mode.

Operands: None Bytes: 1

Encoding: 0000 1111 **Data Transfer Sequence:**



RREG

Read from Registers

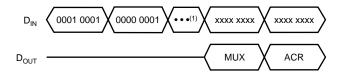
Description: Output the data from up to 16 registers starting with the register address specified as part of the instruction. The number of registers read will be one plus the second byte. If the count exceeds the remaining registers, the addresses will wrap back to the beginning.

Operands: r, n **Bytes:** 2

Encoding: 0001 rrrr xxxx nnnn

Data Transfer Sequence:

Read Two Registers Starting from Register 01_H (MUX)



RRAM

Read from RAM

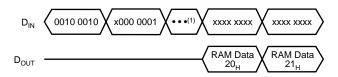
Description: Up to 128 bytes can be read from RAM starting at the bank specified in the op code. All reads start at the address for the beginning of the RAM bank. The number of bytes to read will be one plus the value of the second byte.

Operands: a, n Bytes: 2

Encoding: 0010 0aaa xnnn nnnn

Data Transfer Sequence:

Read Two RAM Locations Starting from 20_H



Description: Copy the 16 control registers to the RAM bank specified in the op code. Refer to timing specifications for command execution time.

Operands: a Bytes: 1

Encoding: 0100 0aaa **Data Transfer Sequence:**

Copy Register Values to RAM Bank 3



CREGA Copy Registers to All RAM Banks

Description: Duplicate the 16 control registers to all the RAM banks. Refer to timing specifications for command execution time.

Operands: None Bytes: 1

Encoding: 0100 1000 **Data Transfer Sequence:**



WREG

Write to Register

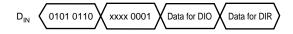
Description: Write to the registers starting with the register specified as part of the instruction. The number of registers that will be written is one plus the value of the second byte.

Operands: r, n **Bytes:** 2

Encoding: 0101 rrrr xxxx nnnn

Data Transfer Sequence:

Write Two Registers Starting from 06_H (DIO)



Calculate the Checksum for all RAM Banks

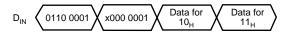
Description: Write up to 128 RAM locations starting at the beginning of the RAM bank specified as part of the instruction. The number of bytes written is RAM is one plus the value of the second byte.

Operands: a, n **Bytes:** 2

Encoding: 0110 0aaa xnnn nnnn

Data Transfer Sequence:

Write to Two RAM Locations starting from 10_H



CRAM Copy RAM Bank to Registers

Description: Copy the selected RAM Bank to the Configuration Registers. This will overwrite all of the registers with the data from the RAM bank.

Operands: a Bytes: 1

Encoding: 1100 0aaa

Data Transfer Sequence:

Copy RAM Bank 0 to the Registers



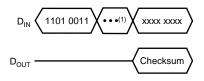
CSRAMX Calculate RAM Bank Checksum

Description: Calculate the checksum of the selected RAM Bank. The checksum is calculated as a sum of all the bytes with the carry ignored. The ID, $\overline{\text{DRDY}}$, and DIO bits are masked so they are not included in the checksum.

Operands: a Bytes: 1

Encoding: 1101 0aaa **Data Transfer Sequence:**

Calculate Checksum for RAM Bank 3



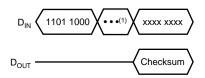
Description: Calculate the checksum of all RAM Banks. The checksum is calculated as a sum of all the bytes with the carry ignored. The ID, DRDY, and DIO bits are masked so they are not included in the checksum.

Operands: None Bytes: 1

CSARAMX

Encoding: 1101 1000

Data Transfer Sequence:



Calculate the Checksum of Registers

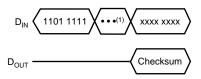
Description: Calculate the checksum of all the registers. The checksum is calculated as a sum of all the bytes with the carry ignored. The ID, $\overline{\mathsf{DRDY}}$ and DIO bits are masked so they are not included in the checksum.

Operands: None Bytes: 1

CSREG

Encoding: 1101 1111

Data Transfer Sequence:



CSRAM Calculate RAM Bank Checksum

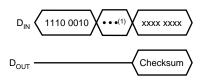
Description: Calculate the checksum of the selected RAM Bank. The checksum is calculated as a sum of all the bytes with the carry ignored. All bits are included in the checksum calculation, there is no masking of bits.

Operands: a Bytes: 1

Encoding: 1110 0aaa

Data Transfer Sequence:

Calculate Checksum for RAM Bank 2



NOTE: (1) For wait time, refer to timing specification.



Calculate Checksum

for all RAM Banks

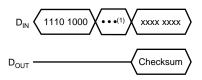
Gain Self Calibration

Description: Calculate the checksum of all RAM Banks. The checksum is calculated as a sum of all the bytes with the carry ignored. All bits are included in the checksum calculation, there is no masking of bits.

Operands: None Bytes:

CSARAM

1110 1000 **Encoding: Data Transfer Sequence:**



SELFCAL Offset and Gain Self Calibration

Description: Starts the process of self calibration. The Offset Control Register (OCR) and the Full-Scale Register (FSR) are updated with new values after this operation.

Operands: None Bytes: 1

Encoding: 1111 0000 **Data Transfer Sequence:**



SELFOCAL

Offset Self Calibration

Description: Starts the process of self-calibration for offset. The Offset Control Register (OCR) is updated after this operation.

Operands: None Bytes:

Encoding: 1111 0001 **Data Transfer Sequence:**



SELFGCAL

Description: Starts the process of self-calibration for gain. The Full-Scale Register (FSR) is updated with new values after this operation.

Operands: None Bytes: 1

Encoding: 1111 0010 **Data Transfer Sequence:**

SYSOCAL

System Offset Calibration

Description: Starts the system offset calibration process. For a system offset calibration the input should be set to 0V differential, and the ADS1217 computes the OCR register value that will compensate for offset errors. The Offset Control Register (OCR) is updated after this operation.

Operands: None Bytes:

Encoding: 1111 0011 **Data Transfer Sequence:**

SYSGCAL

System Gain Calibration

Description: Starts the system gain calibration process. For a system gain calibration, the differential input should be set to the reference voltage and the ADS1217 computes the FSR register value that will compensate for gain errors. The FSR is updated after this operation.

Operands: None **Bytes:**

1111 0100 **Encoding: Data Transfer Sequence:**



DSYNC

Sync DRDY

WAKEUP Wakeup From Sleep Mode

Description: Synchronizes the ADS1217 to the serial clock

edge.

Bytes:

Operands: None

Encoding: 1111 1100 **Data Transfer Sequence:**



 $\textbf{Description:} \ Use \ this \ command \ to \ wake \ up \ from \ sleep \ mode.$

Operands: None Bytes: 1

Encoding: 1111 1011

Data Transfer Sequence:



SLEEP

Sleep Mode

Description: Puts the ADS1217 into a low power sleep mode. SCLK must be inactive while in sleep mode. To exit this mode, issue the WAKEUP command.

Operands: None

Bytes: 1

Encoding: 1111 1101 **Data Transfer Sequence:**

D_{IN} (1111 1101)

RESET Reset to Power-Up Values

Description: Restore the registers to their power-up values. This command will also stop the Read Continuous mode. It does not affect the contents of RAM.

Operands: None

Bytes: 1

Encoding: 1111 1110

Data Transfer Sequence:

D_{IN} (1111 1110)

	LSB															
MSB	0000	0001	0010	0011	0100	0101	0110	0111	1000	1001	1010	1011	1100	1101	1110	1111
0000	х	rdata	х	rdatac	х	х	Х	х	х	х	Х	х	Х	Х	х	stopc
0001	rreg 0	rreg 1	rreg 2	rreg 3	rreg 4	rreg 5	rreg 6	rreg 7	rreg 8	rreg 9	rreg A	rreg B	rreg C	rreg D	rreg E	rreg F
0010	rram 0	rram 1	rram 2	rram 3	rram 4	rram 5	rram 6	rram 7	х	х	Х	х	х	х	х	х
0011	х	х	х	х	х	х	х	х	х	х	х	х	х	х	х	х
0100	creg 0	creg 1	creg 2	creg 3	creg 4	creg 5	creg 6	creg 7	crega	х	Х	х	х	х	х	х
0101	wreg 0	wreg 1	wreg 2	wreg 3	wreg 4	wreg 5	wreg 6	wreg 7	wreg 8	wreg 9	wreg A	wreg B	wreg C	wreg D	wreg E	wreg F
0110	wram 0	wram 1	wram 2	wram 3	wram 4	wram 5	wram 6	wram 7	х	х	х	х	х	х	х	х
0111	х	х	х	х	х	х	х	х	Х	х	х	х	Х	х	х	х
1000	х	х	х	х	х	х	х	х	х	х	х	х	х	х	х	х
1001	х	х	х	х	х	х	х	х	х	х	х	х	х	х	х	х
1010	х	х	х	х	х	х	х	х	х	х	х	х	х	х	х	х
1011	х	х	х	х	х	х	х	х	Х	х	х	х	х	х	х	х
1100	cram 0	cram 1	cram 2	cram 3	cram 4	cram 5	cram 6	cram 7	х	x	х	х	х	х	х	х
1101	csramx 0	csramx 1	csramx 2	csramx 3	csramx 4	csramx 5	csramx 6	csramx 7	csa ramx	Х	х	х	Х	Х	х	csreg
1110	cs ram 0	cs ram 1	cs ram2	cs ram 3	cs ram 4	cs ram 5	cs ram 6	cs ram 7	csa ram	х	х	х	х	х	х	х
1111	self cal	self ocal	self gcal	sys ocal	sys gcal	х	х	х	х	х	х	wakeup	dsync	sleep	reset	х

TABLE IV. Command Map.

DEFINITION OF TERMS

Analog Input Voltage—the voltage at any one analog input relative to AGND.

Analog Input Differential Voltage—given by the following equation: $(A_{IN+}) - (A_{IN-})$. Thus, a positive digital output is produced whenever the analog input differential voltage is positive, while a negative digital output is produced whenever the differential is negative.

For example, when the converter is configured with a 2.5V reference and placed in a gain setting of 1, the positive full-scale output is produced when the analog input differential is 2 • 2.5V. The negative full-scale output is produced when the differential is 2 • (-2.5V). In each case, the actual input voltages must remain within the AGND to AV_{DD} range.

Conversion Cycle—the term *conversion cycle* usually refers to a discrete A/D conversion operation, such as that performed by a successive approximation converter. As used here, a conversion cycle refers to the t_{DATA} time period. However, each digital output is actually based on the modulator results from several t_{DATA} time periods.

FILTER SETTING	MODULATOR RESULTS
Fast Settling	1 t _{DATA} Time Period
Sinc ²	2 t _{DATA} Time Period
Sinc ³	3 t _{DATA} Time Period

Data Rate—the rate at which conversions are completed. See definition for f_{DATA} .

Decimation Ratio—defines the ratio between the output of the modulator and the output Data Rate. Valid values for the Decimation Ratio are from 20 to 2047. Larger Decimation Ratios will have lower noise.

Effective Resolution—the effective resolution of the ADS1217 in a particular configuration can be expressed in two different units: bits rms (referenced to output) and Vrms (referenced to input). Computed directly from the converter's output data, each is a statistical calculation. The conversion from one to the other is shown below.

Effective number of bits (ENOB) or effective resolution is commonly used to define the usable resolution of the A/D converter. It is calculated from empirical data taken directly from the device. It is typically determined by applying a fixed known signal source to the analog input and computing the standard deviation of the data sample set. The rms noise defines the $\pm \sigma$ interval about the sample mean.

The data from the A/D converter is output as codes, which then can be easily converted to other units, such as ppm or volts. The equations and table below show the relationship between bits or codes, ppm, and volts.

$$ENOB = \frac{-20 \log(ppm)}{6.02}$$

BITS rms	BIPOLAR Vrms	UNIPOLAR Vrms
	$\frac{\left(\frac{4V_{REF}}{PGA}\right)}{10^{\left(\frac{6.02 \cdot ENOB}{20}\right)}}$	$\frac{\left(\frac{2V_{REF}}{PGA}\right)}{10^{\left(\frac{6.02 \cdot ENOB}{20}\right)}}$
24	596nV	298nV
22	2.38μV	1.19μV
20	9.54μV	4.77μV
18	38.1μV	19.1μV
16	153μV	76.4μV
14	610μV	305μV
12	2.44mV	1.22mV

 f_{DATA} —the frequency of the digital output data produced by the ADS1217, f_{DATA} is also referred to as the Data Rate.

$$f_{DATA} = \left(\frac{f_{MOD}}{\text{Decimation Ratio}}\right) = \left(\frac{f_{OSC}}{\text{mfactor} \bullet \text{Decimation Ratio}}\right)$$

f_{MOD}—the frequency or speed at which the modulator of the ADS1217 is running. This depends on the SPEED bit as shown below:

SPEED BIT	f _{MOD}
0	f _{OSC} /128
1	f _{OSC} /256

 f_{OSC} —the frequency of the crystal input signal at the X_{IN} input of the ADS1217.

 $\mathbf{f}_{\mathsf{SAMP}}$ —the frequency, or switching speed, of the input sampling capacitor. The value is given by one of the following equations:

PGA SETTING	SAMPLING FREQUENCY
1, 2, 4, 8	$f_{SAMP} = \frac{f_{OSC}}{mfactor}$
8	$f_{SAMP} = \frac{2f_{OSC}}{mfactor}$
16	$f_{SAMP} = \frac{8f_{OSC}}{mfactor}$
32	$f_{SAMP} = \frac{16f_{OSC}}{mfactor}$
64, 128	$f_{SAMP} = \frac{16f_{OSC}}{mfactor}$

Filter Selection—the ADS1217 uses a (sinx/x) filter or *sinc* filter. There are three different sinc filters that can be selected. A fast settling filter will settle in one t_{DATA} cycle. The sinc² filter will settle in two cycles and have lower noise. The sinc³ will achieve lowest noise and higher number of effective bits, but requires three cycles to settle. The ADS1217 will operate with any one of these filters, or it can operate in an auto mode, where it will first select the fast settling filter after a new channel is selected and will then switch to sinc² for one reading, followed by sinc³ from then on.



Full-Scale Range (FSR)—as with most A/D converters, the full-scale range of the ADS1217 is defined as the "input", which produces the positive full-scale digital output minus the "input", which produces the negative full-scale digital output. The full-scale range changes with gain setting, see Table V.

For example, when the converter is configured with a 2.5V reference and is placed in a gain setting of 2, the full-scale range is: $2 \cdot [1.25V$ (positive full-scale) minus -1.25V (negative full-scale)] = 5V.

Least Significant Bit (LSB) Weight—this is the theoretical amount of voltage that the differential voltage at the analog input would have to change in order to observe a change in the output data of one least significant bit. It is computed as follows:

$$LSB\ Weight = \frac{Full - Scale\ Range}{2^{N}}$$

where N is the number of bits in the digital output.

 \mathbf{t}_{DATA} —the inverse of \mathbf{f}_{DATA} , or the period between each data output.

	5V \$	SUPPLY ANALOG INPL	GENERAL EQUATIONS				
GAIN SETTING	FULL-SCALE RANGE	DIFFERENTIAL INPUT VOLTAGES ⁽²⁾	PGA OFFSET RANGE	FULL-SCALE RANGE	DIFFERENTIAL INPUT VOLTAGES ⁽²⁾	PGA SHIFT RANGE	
1	10V	±5V	±2.5	4V _{REF}	±2V _{REF}	±V _{REF}	
2	5V	±2.5V	±1.25V	PGA	PGA	PGA	
4	2.5V	±1.25V	±0.625V				
8	1.25V	±0.625V	±312.5mV				
16	0.625V	±312.5mV	±156.25mV				
32	312.5mV	±156.25mV	±78.125mV				
64	156.25mV	±78.125mV	±39.0625mV				
128	78.125mV	±39.0625mV	±19.531mV				

NOTES: (1) With a 2.5V reference. (2) The ADS1217 allows common-mode voltage as long as the absolute input voltage on A_{IN-} or A_{IN-} does not go below AGND or above AV_{DD} .

TABLE V. Full-Scale Range versus PGA Setting.

Revision History

DATE	REVISION	PAGE	SECTION	CTION DESCRIPTION						
2/07	С	2,4	Electrical Characteristics	Changed Gain Error condition from "Before Calibration" to "After Calibration"						

NOTE: Page numbers for previous revisions may differ from page numbers in the current version.





PACKAGE OPTION ADDENDUM

10-Jun-2014

PACKAGING INFORMATION

www.ti.com

Orderable Device	Status	Package Type	Package	Pins	Package	Eco Plan	Lead/Ball Finish	MSL Peak Temp	Op Temp (°C)	Device Marking	Samples
	(1)		Drawing		Qty	(2)	(6)	(3)		(4/5)	
ADS1217IPFBR	ACTIVE	TQFP	PFB	48	2000	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-2-260C-1 YEAR	-40 to 85	ADS1217	Samples
ADS1217IPFBT	ACTIVE	TQFP	PFB	48	250	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-2-260C-1 YEAR	-40 to 85	ADS1217	Samples
ADS1217IPFBTG4	ACTIVE	TQFP	PFB	48	250	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-2-260C-1 YEAR	-40 to 85	ADS1217	Samples

(1) The marketing status values are defined as follows:

ACTIVE: Product device recommended for new designs.

LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

NRND: Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

PREVIEW: Device has been announced but is not in production. Samples may or may not be available.

OBSOLETE: TI has discontinued the production of the device.

(2) Eco Plan - The planned eco-friendly classification: Pb-Free (RoHS), Pb-Free (RoHS Exempt), or Green (RoHS & no Sb/Br) - please check http://www.ti.com/productcontent for the latest availability information and additional product content details.

TBD: The Pb-Free/Green conversion plan has not been defined.

Pb-Free (RoHS): TI's terms "Lead-Free" or "Pb-Free" mean semiconductor products that are compatible with the current RoHS requirements for all 6 substances, including the requirement that lead not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, TI Pb-Free products are suitable for use in specified lead-free processes.

Pb-Free (RoHS Exempt): This component has a RoHS exemption for either 1) lead-based flip-chip solder bumps used between the die and package, or 2) lead-based die adhesive used between the die and leadframe. The component is otherwise considered Pb-Free (RoHS compatible) as defined above.

Green (RoHS & no Sb/Br): TI defines "Green" to mean Pb-Free (RoHS compatible), and free of Bromine (Br) and Antimony (Sb) based flame retardants (Br or Sb do not exceed 0.1% by weight in homogeneous material)

- (3) MSL, Peak Temp. The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.
- (4) There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.
- (5) Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "~" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.
- (6) Lead/Ball Finish Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead/Ball Finish values may wrap to two lines if the finish value exceeds the maximum column width.

Important Information and Disclaimer: The information provided on this page represents TI's knowledge and belief as of the date that it is provided. TI bases its knowledge and belief on information provided by third parties, and makes no representation or warranty as to the accuracy of such information. Efforts are underway to better integrate information from third parties. TI has taken and



PACKAGE OPTION ADDENDUM

10-Jun-2014

continues to take reasonable steps to provide representative and accurate information but may not have conducted destructive testing or chemical analysis on incoming materials and chemicals. TI and TI suppliers consider certain information to be proprietary, and thus CAS numbers and other limited information may not be available for release.

In no event shall TI's liability arising out of such information exceed the total purchase price of the TI part(s) at issue in this document sold by TI to Customer on an annual basis.

PACKAGE MATERIALS INFORMATION

www.ti.com 7-Feb-2015

TAPE AND REEL INFORMATION





	Dimension designed to accommodate the component width
	Dimension designed to accommodate the component length
K0	Dimension designed to accommodate the component thickness
W	Overall width of the carrier tape
P1	Pitch between successive cavity centers

QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE



*All dimensions are nominal

Device	Package Type	Package Drawing		SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
ADS1217IPFBR	TQFP	PFB	48	2000	330.0	16.4	9.6	9.6	1.5	12.0	16.0	Q2
ADS1217IPFBT	TQFP	PFB	48	250	180.0	16.4	9.6	9.6	1.5	12.0	16.0	Q2

www.ti.com 7-Feb-2015



*All dimensions are nominal

Device	Device Package Type		Pins	SPQ	Length (mm)	Width (mm)	Height (mm)	
ADS1217IPFBR	TQFP	PFB	48	2000	367.0	367.0	38.0	
ADS1217IPFBT	TQFP	PFB	48	250	213.0	191.0	55.0	

PFB (S-PQFP-G48)

PLASTIC QUAD FLATPACK



NOTES: A. All linear dimensions are in millimeters.

B. This drawing is subject to change without notice.

C. Falls within JEDEC MS-026

PFB (S-PQFP-G48)



NOTES: A. All linear dimensions are in millimeters.

- B. This drawing is subject to change without notice.
- C. Publication IPC-7351 is recommended for alternate designs.
- D. Laser cutting apertures with trapezoidal walls and also rounding corners will offer better paste release. Customers should contact their board assembly site for stencil design recommendations. Refer to IPC-7525.
- E. Customers should contact their board fabrication site for solder mask tolerances between and around signal pads.



IMPORTANT NOTICE

Texas Instruments Incorporated and its subsidiaries (TI) reserve the right to make corrections, enhancements, improvements and other changes to its semiconductor products and services per JESD46, latest issue, and to discontinue any product or service per JESD48, latest issue. Buyers should obtain the latest relevant information before placing orders and should verify that such information is current and complete. All semiconductor products (also referred to herein as "components") are sold subject to TI's terms and conditions of sale supplied at the time of order acknowledgment.

TI warrants performance of its components to the specifications applicable at the time of sale, in accordance with the warranty in TI's terms and conditions of sale of semiconductor products. Testing and other quality control techniques are used to the extent TI deems necessary to support this warranty. Except where mandated by applicable law, testing of all parameters of each component is not necessarily performed.

TI assumes no liability for applications assistance or the design of Buyers' products. Buyers are responsible for their products and applications using TI components. To minimize the risks associated with Buyers' products and applications, Buyers should provide adequate design and operating safeguards.

TI does not warrant or represent that any license, either express or implied, is granted under any patent right, copyright, mask work right, or other intellectual property right relating to any combination, machine, or process in which TI components or services are used. Information published by TI regarding third-party products or services does not constitute a license to use such products or services or a warranty or endorsement thereof. Use of such information may require a license from a third party under the patents or other intellectual property of the third party, or a license from TI under the patents or other intellectual property of TI.

Reproduction of significant portions of TI information in TI data books or data sheets is permissible only if reproduction is without alteration and is accompanied by all associated warranties, conditions, limitations, and notices. TI is not responsible or liable for such altered documentation. Information of third parties may be subject to additional restrictions.

Resale of TI components or services with statements different from or beyond the parameters stated by TI for that component or service voids all express and any implied warranties for the associated TI component or service and is an unfair and deceptive business practice. TI is not responsible or liable for any such statements.

Buyer acknowledges and agrees that it is solely responsible for compliance with all legal, regulatory and safety-related requirements concerning its products, and any use of TI components in its applications, notwithstanding any applications-related information or support that may be provided by TI. Buyer represents and agrees that it has all the necessary expertise to create and implement safeguards which anticipate dangerous consequences of failures, monitor failures and their consequences, lessen the likelihood of failures that might cause harm and take appropriate remedial actions. Buyer will fully indemnify TI and its representatives against any damages arising out of the use of any TI components in safety-critical applications.

In some cases, TI components may be promoted specifically to facilitate safety-related applications. With such components, TI's goal is to help enable customers to design and create their own end-product solutions that meet applicable functional safety standards and requirements. Nonetheless, such components are subject to these terms.

No TI components are authorized for use in FDA Class III (or similar life-critical medical equipment) unless authorized officers of the parties have executed a special agreement specifically governing such use.

Only those TI components which TI has specifically designated as military grade or "enhanced plastic" are designed and intended for use in military/aerospace applications or environments. Buyer acknowledges and agrees that any military or aerospace use of TI components which have *not* been so designated is solely at the Buyer's risk, and that Buyer is solely responsible for compliance with all legal and regulatory requirements in connection with such use.

TI has specifically designated certain components as meeting ISO/TS16949 requirements, mainly for automotive use. In any case of use of non-designated products, TI will not be responsible for any failure to meet ISO/TS16949.

Products Applications

Audio www.ti.com/audio Automotive and Transportation www.ti.com/automotive **Amplifiers** amplifier.ti.com Communications and Telecom www.ti.com/communications **Data Converters** dataconverter.ti.com Computers and Peripherals www.ti.com/computers **DLP® Products** www.dlp.com Consumer Electronics www.ti.com/consumer-apps DSP dsp.ti.com **Energy and Lighting** www.ti.com/energy Clocks and Timers www.ti.com/clocks Industrial www.ti.com/industrial Interface interface.ti.com Medical www.ti.com/medical Logic Security www.ti.com/security logic.ti.com

Power Mgmt power.ti.com Space, Avionics and Defense www.ti.com/space-avionics-defense

Microcontrollers microcontroller.ti.com Video and Imaging www.ti.com/video

RFID www.ti-rfid.com

OMAP Applications Processors www.ti.com/omap TI E2E Community e2e.ti.com

Wireless Connectivity www.ti.com/wirelessconnectivity