

www.ti.com

SLAS917B-DECEMBER 2012-REVISED JANUARY 2014

## Dual Channel 12-Bit 500Msps Receiver and Feedback IC

Check for Samples: ADS54T04

### FEATURES

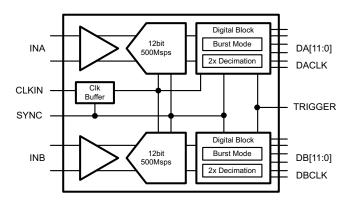
- Dual Channel
- 12-Bit Resolution
- Maximum Clock Rate: 500 Msps
- Low Swing Fullscale Input: 1.0 Vpp
- Analog Input Buffer with High Impedance Input
- Input Bandwidth (3dB): >1.2GHz
- Data Output Interface: DDR LVDS
- 196-Pin BGA Package (12x12mm)
- Power Dissipation: 800mW/ch
- Performance at f<sub>in</sub> = 230 MHz IF
  - SNR: 60.6 dBFS
  - SFDR: 77 dBc
- Performance at f<sub>in</sub> = 700 MHz IF
  - SNR: 59.4 dBFS
  - SFDR: 70 dBc
- Receive Mode: 2x Decimation with Low Pass or High Pass Filter
- Feedback Mode: Burst Mode Output for Full Bandwidth DPD Feedback

## **APPLICATIONS**

- Telecommunications Receiver
- Power Amplifier Linearization

### DESCRIPTION

The ADS54T04 is a high linearity dual channel 12-bit, 500 MSPS analog-to-digital converter (ADC) easing front end filter design for wide bandwidth receivers. The analog input buffer isolates the internal switching of the on-chip track-and-hold from disturbing the signal source as well as providing a high-impedance input. Two output modes are available for the output data - it can be decimated by two or the data can be output in burst mode. The burst mode output is designed specifically for DPD feedback applications where high resolution output data is available for a short period of time. Designed for high SFDR, the ADC has low-noise performance and outstanding spurious-free dynamic range over a large inputfrequency range. The device is available in a 196pin BGA package and is specified over the full industrial temperature range (-40°C to 85°C).



Device Part No.	Number of Channels	Speed Grade
ADS54T02	2	750Msps
ADS54T01	1	750Msps
ADS54T04	2	500Msps



Please be aware that an important notice concerning availability, standard warranty, and use in critical applications of Texas Instruments semiconductor products and disclaimers thereto appears at the end of this data sheet.



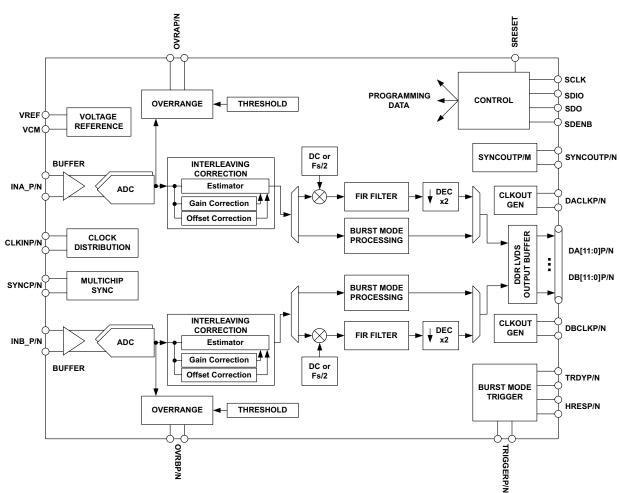
#### SLAS917B-DECEMBER 2012-REVISED JANUARY 2014

www.ti.com



This integrated circuit can be damaged by ESD. Texas Instruments recommends that all integrated circuits be handled with appropriate precautions. Failure to observe proper handling and installation procedures can cause damage.

ESD damage can range from subtle performance degradation to complete device failure. Precision integrated circuits may be more susceptible to damage because very small parametric changes could cause the device not to meet its published specifications.



DETAILED BLOCK DIAGRAM

Figure 1. Detailed Block Diagram



TEXAS INSTRUMENTS

www.ti.com

SLAS917B-DECEMBER 2012-REVISED JANUARY 2014

	A	В	С	D	Е	F	G	н	J	к	L	М	Ν	Ρ	
14	VREF	VCM	GND	INB_N	INB_P	GND	AVDDC	AVDDC	GND	INA_P	INA_N	GND	GND	CLKINP	14
13	SDENB	TEST MODE	GND	GND	GND	GND	GND	GND	GND	GND	GND	GND	GND	CLKINN	13
12	SCLK	SRESET	GND	AVDD33	AVDD33	AVDD33	AVDD33	AVDD33	AVDD33	AVDD33	AVDD33	GND	AVDD33	AVDD33	12
11	SDIO	ENABLE	GND	AVDD18	AVDD18	AVDD18	AVDD18	AVDD18	AVDD18	AVDD18	AVDD18	GND	AVDD18	AVDD18	11
10	SDO	IOVDD	GND	AVDD18	GND	GND	GND	GND	GND	GND	AVDD18	GND	TRIGGER N	TRIGGER P	10
9	DVDD	DVDD	GND	GND	GND	GND	GND	GND	GND	GND	GND	GND	SYNCN	SYNCP	9
8	DVDD	DVDD	DVDD	DVDD	GND	GND	GND	GND	GND	GND	DVDD	DVDD	DVDD	DVDD	8
7	DB0N	DB0P	DVDD LVDS	DVDD LVDS	GND	GND	GND	GND	GND	GND	DVDD LVDS	DVDD LVDS	TRDYN	TRDYP	7
6	DB1N	DB1P	DVDD LVDS	DVDD LVDS	GND	GND	GND	GND	GND	GND	DVDD LVDS	DVDD LVDS	HRESN	HRESP	6
5	DB2N	DB2P	OVRBN	OVRBP	GND	GND	GND	GND	GND	GND	OVRAN	OVRAP	SYNC OUTN	SYNC OUTP	5
4	DB3N	DB3P	DB8P	DB10P	NC	HRESP	TRDYP	DA0P	DA2P	DA4P	DA6P	DA8P	NC	NC	4
3	DB4N	DB4P	DB8N	DB10N	NC	HRESN	TRDYN	DA0N	DA2N	DA4N	DA6N	DA8N	DA11N	DA11P	3
2	DB5N	DB5P	DB7P	DB9P	DB11P	SYNC OUTP	DBCLKP	DACLKP	DA1P	DA3P	DA5P	DA7P	DA10N	DA10P	2
1	DB6N	DB6P	DB7N	DB9N	DB11N	SYNC OUTN	DBCLKN	DACLKN	DA1N	DA3N	DA5N	DA7N	DA9N	DA9P	1
	А	В	С	D	Е	F	G	н	J	к	L	М	Ν	Р	

#### **PINOUT INFORMATION**

Figure 2. Pinout in DDR output mode (top down view)

#### **PIN ASSIGNMENTS**

P	PIN	1/0	DESCRIPTION
NAME	NUMBER	I/O	DESCRIPTION
INPUT/REFEREN	ICE		
INA_P/N	K14, L14	I	Analog ADC A differential input signal.
INB_P/N	E14, D14	I	Analog ADC B differential input signal.
VCM B14 O		0	Output of the analog input common mode (nominally 1.9V). A $0.1\mu\text{F}$ capacitor to AGND is recommended.
VREF	A14	I	Reference voltage input. A 0.1µF capacitor to AGND is recommended, but not required.
CLOCK/SYNC			
CLKINP/N	P14, P13	I	Differential input clock
SYNCP/N P9, N9 I		I	Synchronization input. Inactive if logic low. When clocked in a high state initially, this is used for resetting internal clocks and digital logic and starting the SYNCOUT signal. Internal $100\Omega$ termination.
CONTROL/SERI	AL		
SRESET	B12	I	Serial interface reset input. Active low. Initialized internal registers during high to low transition. Asynchronous. Internal $50k\Omega$ pull up resistor to IOVDD.

#### www.ti.com

NSTRUMENTS

Texas

### **PIN ASSIGNMENTS (continued)**

I	PIN	1/0	DECODIDITION
NAME	NUMBER	I/O	DESCRIPTION
ENABLE	B11	I	Chip enable – active high. Power down function can be controlled through SPI register assignment. Internal $50k\Omega$ pull up resistor to IOVDD.
SCLK	A12	I	Serial interface clock. Internal 50k $\Omega$ pull-down resistor.
SDIO	A11	I/O	Bi-directional serial data in 3 pin mode (default). In 4-pin interface mode (register x00, D16), the SDIO pin in an input only. Internal $50k\Omega$ pull-down.
SDENB	A13	I	Serial interface enable. Internal $50k\Omega$ pull-down resistor.
SDO	A10	0	Uni-directional serial interface data in 4 pin mode (register x00, D16). The SDO pin is tri- stated in 3-pin interface mode (default). Internal $50k\Omega$ pull-down resistor.
TESTMODE	B13	-	Factory internal test, do not connect
DATA INTERFA	CE		
DA[11:0]P/N	P3, N3, P2, N2, P1, N1, M4, M3, M2, M1, L4, L3, L2, L1, K4, K3, K2, K1, J4, J3, J2, J1, H4, H3	0	ADC A Data Bits 11 (MSB) to 0 (LSB) in DDR output mode. Standard LVDS output.
DB[11:0]P/N	E2, E1, D4, D3, D2, D1, C4, C3, C2, C1, B1, A1, B2, A2, B3, A3, B4, A4, B5, A5, B6, A6, B7, A7	0	ADC B Data Bits 11 (MSB) to 0 (LSB) in DDR output mode. Standard LVDS output.
DACLKP/N	H2, H1	0	DDR differential output data clock for Bus A. Register programmable to provide either rising or falling edge to center of stable data nominal timing.
DBCLKP/N	G2, G1	0	DDR differential output data clock for Bus B. Register programmable to provide either rising or falling edge to center of stable data nominal timing. Optionally Bus B can be latched with DACLKP/N.
SYNCOUTP/N	F2, F1, P5, N5	0	Synchronization output signal for synchronizing multiple ADCs. Can be disabled via SPI.
OVRAP/N	M5, L5	0	Bus A, Overrange indicator, LVDS output. A logic high signals an analog input in excess of the full-scale range. Optional SYNC output.
OVRBP/N	D5, C5	0	Bus B, Overrange indicator, LVDS output. A logic high signals an analog input in excess of the full-scale range. Optional SYNC output.
TRIGGERP/N	P10, N10	I	Trigger used for High resolution output data in feedback mode. Internal $100\Omega$ termination
TRDYP/N	G4, G3, P7, N7	0	Trigger ready output indicator. Outputs for chA and chB are identical and one output can be shared for both channels.
HRESP/N	F4, F3, P6, N6	0	Indicator for high resolution output data– logic high signals 12bit output data. Outputs for chA and chB are identical and one output can be shared for both channels.
NC	E3, E4, N4, P4	-	Don't connect to pin
POWER SUPPL	Y	1	1
AVDD33	D12, E12, F12, G12, H12, J12, K12, L12, N12, P12	I	3.3V analog supply
AVDDC	G14, H14	I	1.8V supply for clock input
AVDD18	D10, D11, E11, F11, G11, H11, J11, K11, L10, L11, N11, P11	I	1.8V analog supply
DVDD	A8, A9, B8, B9, C8, D8, L8, M8, N8, P8	I	1.8V supply for digital block
DVDDLVDS	C6, C7, D6, D7, L6, L7, M6, M7	I	1.8V supply for LVDS outputs
IOVDD	B10	I	1.8V for digital I/Os
GND		I	Ground



www.ti.com

SLAS917B-DECEMBER 2012-REVISED JANUARY 2014

	PACKAGE/ORDERING INFORMATION										
PRODUCT	PACKAGE- LEAD	PACKAGE DESIGNATOR	SPECIFIED TEMPERATURE RANGE	ECO PLAN <sup>(2)</sup>	LEAD/ BALL FINISH	PACKAGE MARKING	ORDERING NUMBER	TRANSPORT MEDIA, QUANTITY			
				GREEN			ADS54T04IZAY	Tray			
ADS54T04	196-BGA	ZAY	-40C to 85C	(RoHS & no Sb/Br)		ADS54T04I	ADS54T04IZAYR	Tape and Reel			

### **ABSOLUTE MAXIMUM RATINGS**

over operating free-air temperature range (unless otherwise noted)

		VA	ALUE	
		MIN	MAX	UNIT
Supply voltage range, AVDD3	3	-0.5	4	V
Supply voltage range, AVDDC	-0.5	2.3	V	
Supply voltage range, AVDD18		-0.5	2.3	V
Supply voltage range, DVDD		-0.5	2.3	V
Supply voltage range, DVDDLVDS		-0.5	2.3	V
Supply voltage range, IOVDD		-0.5	4	V
	INA/B_P, INA/B_N	-0.5	AVDD33 + 0.5	V
	CLKINP, CLKINN	-0.5	AVDDC + 0.5	V
Voltage applied to input pins	SYNCP, SYNCN	-0.5	AVDD33 + 0.5	V
	SRESET, SDENB, SCLK, SDIO, SDO, ENABLE	-0.5	IOVDD + 0.5	V
Operating free-air temperature	e range, T <sub>A</sub>	-40	85	°C
Operating junction temperature range, T <sub>J</sub>			150	°C
Storage temperature range		-65	150	°C
ESD, Human Body Model			2	kV

#### THERMAL INFORMATION

	THERMAL METRIC <sup>(1)</sup>	ADS54T04	
		nFBGA (196-PIN)	UNITS
$\theta_{JA}$	Junction-to-ambient thermal resistance <sup>(2)</sup>	37.6	
θ <sub>JCtop</sub>	Junction-to-case (top) thermal resistance <sup>(3)</sup>	6.8	
$\theta_{JB}$	Junction-to-board thermal resistance <sup>(4)</sup>	16.8	°C/W
Ψ <sub>JT</sub>	Junction-to-top characterization parameter <sup>(5)</sup>	0.2	
ΨJB	Junction-to-board characterization parameter <sup>(6)</sup>	16.4	

(1) For more information about traditional and new thermal metrics, see the *IC Package Thermal Metrics* application report, SPRA953.

(2) The junction-to-ambient thermal resistance under natural convection is obtained in a simulation on a JEDEC-standard, high-K board, as specified in JESD51-7, in an environment described in JESD51-2a.

(3) The junction-to-case (top) thermal resistance is obtained by simulating a cold plate test on the package top. No specific JEDECstandard test exists, but a close description can be found in the ANSI SEMI standard G30-88.

(4) The junction-to-board thermal resistance is obtained by simulating in an environment with a ring cold plate fixture to control the PCB temperature, as described in JESD51-8.

(5) The junction-to-top characterization parameter,  $\psi_{JT}$ , estimates the junction temperature of a device in a real system and is extracted from the simulation data for obtaining  $\theta_{JA}$ , using a procedure described in JESD51-2a (sections 6 and 7).

(6) The junction-to-board characterization parameter,  $\psi_{JB}$ , estimates the junction temperature of a device in a real system and is extracted from the simulation data for obtaining  $\theta_{JA}$ , using a procedure described in JESD51-2a (sections 6 and 7).

### **RECOMMENDED OPERATING CONDITIONS**

over operating free-air temperature range (unless otherwise noted)

		MIN	NOM	MAX	UNIT
-	Recommended operating junction temperature			105	°C
IJ	Maximum rated operating junction temperature <sup>(1)</sup>	125			
T <sub>A</sub>	Recommended free-air temperature	-40	25	85	°C

(1) Prolonged use at this junction temperature may increase the device failure-in-time (FIT) rate.

## ELECTRICAL CHARACTERISTICS

Typical values at  $T_A = 25^{\circ}$ C, full temperature range is  $T_{MIN} = -40^{\circ}$ C to  $T_{MAX} = 85^{\circ}$ C, ADC sampling rate = 500Msps, 50% clock duty cycle, AVDD33 = 3.3V, AVDDC/AVDD18/DVDD/DVDDLVDS/IOVDD = 1.8V, -1dBFS differential input (unless otherwise noted).

	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNITS
ADC Clock	Frequency		40		500	MSPS
Resolution	1		12			Bits
SUPPLY						
AVDD33			3.15	3.3	3.45	V
AVDDC, AV	VDD18, DVDD, DVDDLVDS		1.7	1.8	1.9	V
IOVDD			1.7	1.8	3.45	V
POWER S	UPPLY					
I <sub>AVDD33</sub>	3.3V Analog supply current			297	330	mA
I <sub>AVDD18</sub>	1.8V Analog supply current			84	100	mA
IAVDDC	1.8V Clock supply current			26	45	mA
I <sub>DVDD</sub>	1.8V Digital supply current	Auto Correction Enabled		230	260	mA
I <sub>DVDD</sub>	1.8V Digital supply current	Auto Correction Disabled		106		mA
I <sub>DVDD</sub>	1.8V Digital supply current	Auto Correction Disabled, decimation filter enabled		135		mA
IDVDDLVDS	1.8V LVDS supply current			120	150	mA
IIOVDD	1.8V I/O Voltage supply current			1	2	mA
P <sub>dis</sub>	Total power dissipation	Auto Correction Enabled, decimation filter disabled		1.78	2.3	W
P <sub>dis</sub>	Total power dissipation	Auto Correction Disabled, decimation filter disabled		1.6		W
PSRR		250kHz to 500MHz	40			dB
Shut-down	power dissipation			7		mW
Shut-down	wake up time			2.5		ms
Standby po	ower dissipation			7		mW
Standby wa	ake up time			100		μs
Doop alast	mode newer discinction	Auto correction disabled		282		mW
Deep-sieep	mode power dissipation	Auto correction enabled		370		mW
Deep-sleep	o mode wakeup time			20		μs
light place	made nower discipation	Auto correction disabled		549		mW
Lignt-sieep	mode power dissipation	Auto correction enabled		650		mW
Light-sleep	mode wakeup time			2		μs

www.ti.com

STRUMENTS

EXAS



www.ti.com

### **ELECTRICAL CHARACTERISTICS**

Typical values at  $T_A = 25^{\circ}$ C, full temperature range is  $T_{MIN} = -40^{\circ}$ C to  $T_{MAX} = 85^{\circ}$ C, ADC sampling rate = 500Msps, 50% clock duty cycle, AVDD3V = 3.3V, AVDD/DRVDD/IOVDD = 1.8V, -1dBFS differential input (unless otherwise noted).

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNITS
ANALOG INPUTS		i.			
Differential input full-scale			1.0	1.25	Vpp
Input common mode voltage			1.9	±0.1	V
Input resistance	Differential at DC		1		kΩ
Input capacitance	Each input to GND		2		pF
VCM common mode voltage output			1.9		V
Analog input bandwidth (3dB)			1200		MHz
DYNAMIC ACCURACY					
Offset Error	Auto Correction Disabled	-20	-7.5	20	mV
Oliset Elloi	Auto Correction Enabled	-1	0	1	mV
Offset temperature coefficient			-611		µV/°C
Gain error		-5		5	%FS
Gain temperature coefficient			0.005		%FS/°C
Differential nonlinearity	f <sub>IN</sub> = 230 MHz	-1	±0.9	2	LSB
Integral nonlinearity	f <sub>IN</sub> = 230 MHz	-5	±1.5	5	LSB
CLOCK INPUT		·			
Input clock frequency		40		500	MHz
Input clock amplitude			2		Vpp
Input clock duty cycle		40%	50%	60%	
Internal clock biasing			0.9		V



www.ti.com

## ELECTRICAL CHARACTERISTICS

Typical values at  $T_A = 25^{\circ}$ C, full temperature range is  $T_{MIN} = -40^{\circ}$ C to  $T_{MAX} = 85^{\circ}$ C, ADC sampling rate = 500Msps, 50% clock duty cycle, AVDD33 = 3.3V, AVDDC/AVDD18/DVDD/DVDDLVDS/IOVDD = 1.8V, -1dBFS differential input (unless otherwise noted).

	PARAMETER	TEST CONDITIONS	MIN	TYP MAX	MIN TYP MAX	UNITS
Auto Co				Enabled	Disabled	Vpp
DYNAMI	C AC CHARACTERISTICS <sup>(1)</sup> –	Burst Mode Enabled: 12bit High	Resolution	Output Data		
		f <sub>IN</sub> = 10 MHz		60.8	60.8	
		f <sub>IN</sub> = 100 MHz		60.7	60.8	
SNR	Signal to Noise Ratio	f <sub>IN</sub> = 230 MHz	59	60.6	60.7	dBFS
		f <sub>IN</sub> = 450 MHz		60.2	60.6	
		f <sub>IN</sub> = 700 MHz		59.4	60.1	
		f <sub>IN</sub> = 10 MHz		84	86	
		f <sub>IN</sub> = 100 MHz		84	82	
HD2,3	Second and third harmonic distortion	f <sub>IN</sub> = 230 MHz	70	80	83	dBc
	distortion	f <sub>IN</sub> = 450 MHz		82	84	
		f <sub>IN</sub> = 700 MHz		76	74	
		f <sub>IN</sub> = 10 MHz		77	78	
	Spur Free Dynamic Range	f <sub>IN</sub> = 100 MHz		77	78	
Non HD2,3	(excluding second and third	f <sub>IN</sub> = 230 MHz	70	77	77	dBc
102,5	harmonic distortion)	f <sub>IN</sub> = 450 MHz		74	75	
		f <sub>IN</sub> = 700 MHz		70	71	
		f <sub>IN</sub> = 10 MHz		92	80	
		f <sub>IN</sub> = 100 MHz		83	79	
IL	Fs/2-Fin interleaving spur	f <sub>IN</sub> = 230 MHz	70	83	79	dBc
		f <sub>IN</sub> = 450 MHz		79	76	
		f <sub>IN</sub> = 700 MHz		75	73	
		f <sub>IN</sub> = 10 MHz		60.6	60.7	
		f <sub>IN</sub> = 100 MHz		60.6	60.7	
SINAD	Signal to noise and distortion ratio	f <sub>IN</sub> = 230 MHz	57.5	60.5	60.7	dBc
	1410	f <sub>IN</sub> = 450 MHz		60.1	60.5	
		f <sub>IN</sub> = 700 MHz		59.3	60	
		f <sub>IN</sub> = 10 MHz		76.3	79.0	
		f <sub>IN</sub> = 100 MHz		76.5	77.6	
THD	Total Harmonic Distortion	f <sub>IN</sub> = 230 MHz	68	77.4	78.1	dBc
		f <sub>IN</sub> = 450 MHz		76.3	77.9	
		f <sub>IN</sub> = 700 MHz		73.4	72.9	
IMD3	Inter modulation distortion	F <sub>in</sub> = 129.5 and 130.5MHz, - 7dBFS		82	82	dBFS
SUN	Inter modulation distortion	F <sub>in</sub> = 349.5 and 350.5MHz, - 7dBFS		80	80	UDFO
	Crosstalk			90	90	dB
ENOB	Effective number of bits	f <sub>IN</sub> = 230 MHz		9.8	9.8	LSB

(1) SFDR and SNR calculations do not include the DC or Fs/2 bins when Auto Correction is disabled.



www.ti.com

### **ELECTRICAL CHARACTERISTICS**

Typical values at  $T_A = 25^{\circ}$ C, full temperature range is  $T_{MIN} = -40^{\circ}$ C to  $T_{MAX} = 85^{\circ}$ C, ADC sampling rate = 500Msps, 50% clock duty cycle, AVDD33 = 3.3V, AVDDC/AVDD18/DVDD/DVDDLVDS/IOVDD = 1.8V, -1dBFS differential input (unless otherwise noted).

	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNITS
OVER	-DRIVE RECOVERY ERROR	2				
	Input overload recovery	Recovery to within 5% (of final value) for 6dB overload with sine wave input		2		ns
SAMP	LE TIMING CHARACTERIS	TICS			,	
rms	Aperture Jitter	Sample uncertainty		100		fs rms
		ADC sample to digital output, auto correction disabled		38		Clock
		ADC sample to digital output, auto correction enabled		50		Cycles
	Data Latency	ADC sample to digital output, Decimation filter enabled, Auto correction disabled		74		Sampling clock Cycles
	Over-range Latency	ADC sample to over-range output		12		Clock Cycles

### **ELECTRICAL CHARACTERISTICS**

The DC specifications refer to the condition where the digital outputs are not switching, but are permanently at a valid logic level 0 or 1. AVDD33 = 3.3V, AVDDC/AVDD18/DVDD/DVDDLVDS/IOVDD = 1.8V

	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNITS
DIGITA	L INPUTS – SRESET, SCLK, SDE	NB, SDIO, ENABLE			1	
	High-level input voltage	All digital inputs support 1.8V and 3.3V logic	0.7 x IOVDD			V
	Low-level input voltage	levels.			0.3 x IOVDD	V
	High-level input current		-50		200	μA
	Low-level input current		-50		50	μA
	Input capacitance			5		pF
DIGITA	L OUTPUTS – SDO					
	High-level output voltage	lload = -100uA	IOVDD – 0.2			V
	nigh-level output voltage	lload = -2mA	0.8 x IOVDD			v
		Iload = 100uA			0.2	
	Low-level output voltage	lload = 2mA			0.22 x IOVDD	V
DIGITA	L INPUTS – SYNCP/N, TRIGGERI	P/N				
V <sub>ID</sub>	Differential input voltage		250	350	450	mV
V <sub>CM</sub>	Input common mode voltage		1.125	1.2	1.375	V
t <sub>SU</sub>			500			ps
DIGITA	L OUTPUTS – DA[11:0]P/N, DACI	LKP/N, OVRAP/N, SYNCOUTP/N, TRDYP/N, HF	RESP/N, DB[11:0	)]P/N, DBC	LKP/N, O	/RBP/N,
V <sub>OD</sub>	Output differential voltage	lout = 3.5mA	250	350	450	mV
V <sub>OCM</sub>	Output common mode voltage	lout = 3.5mA	1.125	1.25	1.375	V
t <sub>suA</sub>		$F_s$ = 500Msps, Data valid to zero-crossing of DACLK	600	800		ps
t <sub>hA</sub>		$F_s$ = 500Msps, Zero-crossing of DACLK to data becoming invalid	600	790		ps
t <sub>suB</sub>		$F_s = 500Msps$ , Data valid to zero-crossing of DBCLK	700	900		ps
t <sub>hB</sub>		$F_s = 500Msps$ , Zero-crossing of DBCLK to data becoming invalid	500	600		ps

#### Texas Instruments

www.ti.com

### **ELECTRICAL CHARACTERISTICS (continued)**

The DC specifications refer to the condition where the digital outputs are not switching, but are permanently at a valid logic level 0 or 1. AVDD33 = 3.3V, AVDDC/AVDD18/DVDD/DVDDLVDS/IOVDD = 1.8V

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNITS
t <sub>PD</sub>	F <sub>s</sub> = 500Msps, CLKIN falling edge to DACLK, DBCLK rising edge	3.28	3.48	3.74	ns
t <sub>RISE</sub>	10% - 90%	100	150	200	ps
t <sub>FALL</sub>	90% - 10%	100	150	200	ps

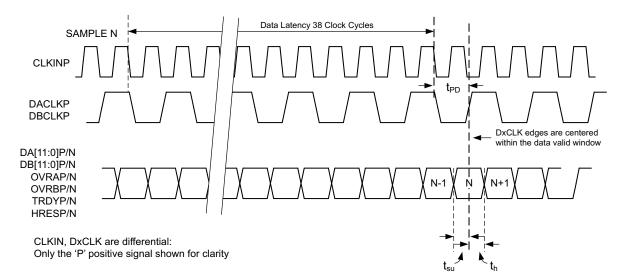


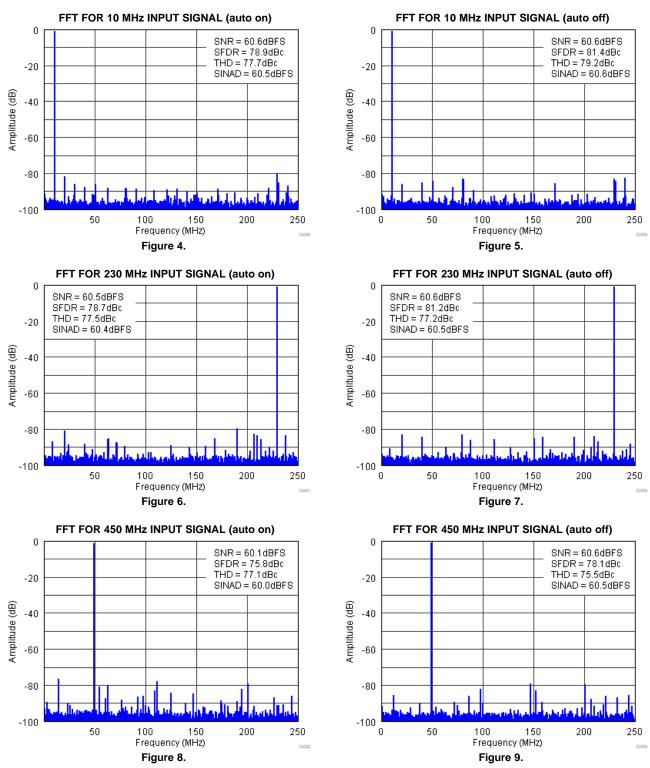
Figure 3. Timing Diagram for 12-bit DDR Output



SLAS917B-DECEMBER 2012-REVISED JANUARY 2014

#### www.ti.com

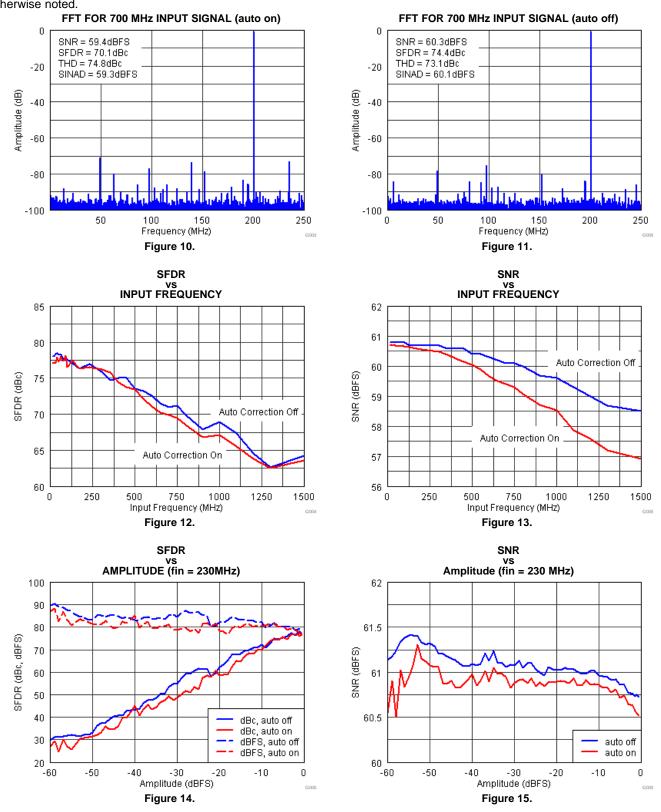
#### **TYPICAL CHARACTERISTICS**





www.ti.com

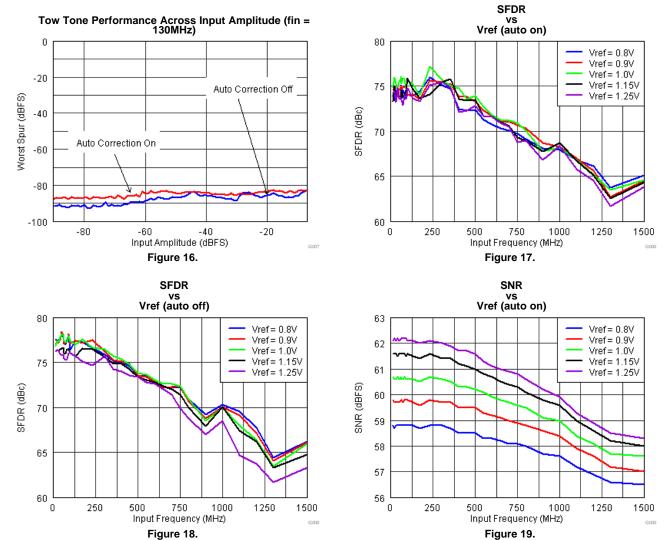
#### **TYPICAL CHARACTERISTICS (continued)**





#### www.ti.com

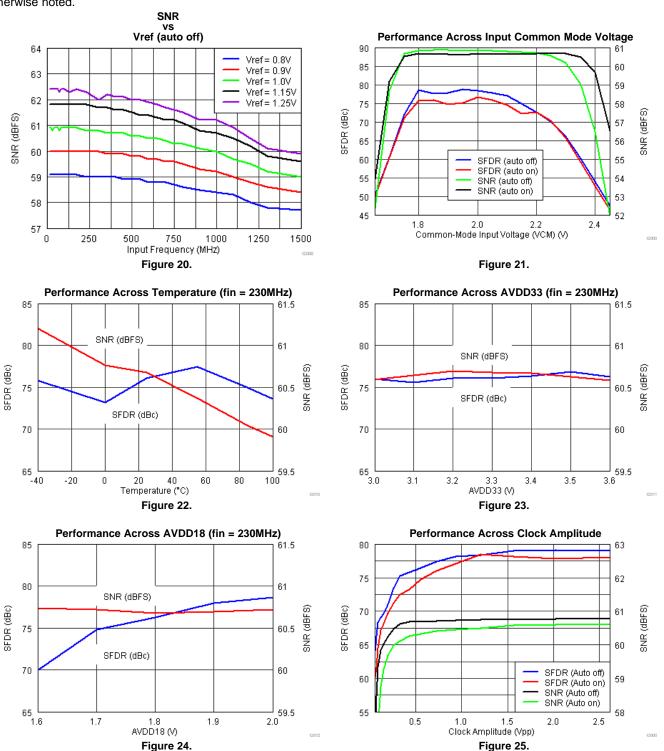
#### **TYPICAL CHARACTERISTICS (continued)**



TEXAS INSTRUMENTS

www.ti.com

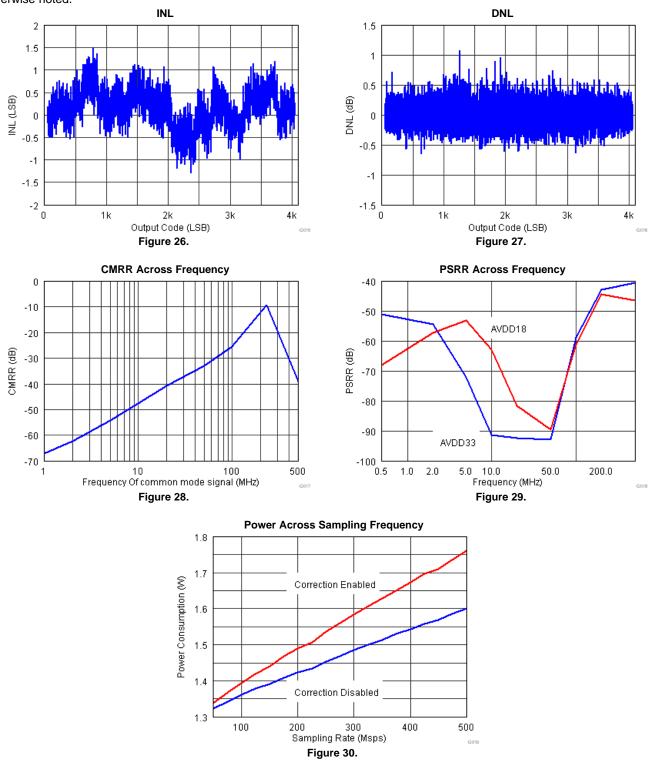






#### www.ti.com

#### **TYPICAL CHARACTERISTICS (continued)**



www.ti.com

NSTRUMENTS

EXAS

#### **TYPICAL CHARACTERISTICS (continued)**

Typical values at TA = +25°C, full temperature range is  $T_{MIN}$  = -40°C to  $T_{MAX}$  = +85°C, ADC sampling rate = 500Msps, 50% clock duty cycle, AVDD33 = 3.3V, AVDDC/AVDD18/DVDD/DVDDLVDS/IOVDD = 1.8V, -1dBFS differential input, unless otherwise noted.

SFDR Across Input and Sampling Frequencies (auto on)

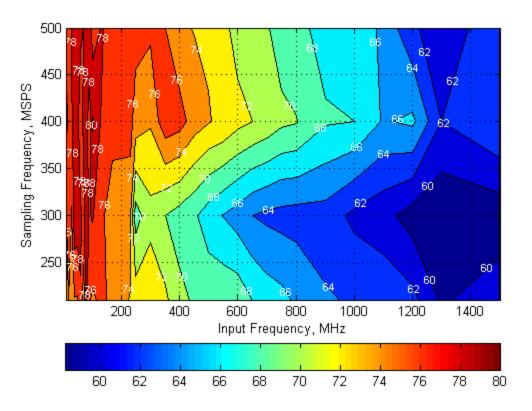


Figure 31.

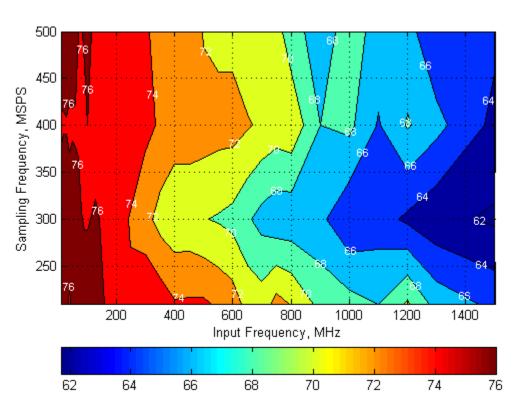


SLAS917B-DECEMBER 2012-REVISED JANUARY 2014

www.ti.com

#### **TYPICAL CHARACTERISTICS (continued)**

Typical values at TA = +25°C, full temperature range is  $T_{MIN}$  = -40°C to  $T_{MAX}$  = +85°C, ADC sampling rate = 500Msps, 50% clock duty cycle, AVDD33 = 3.3V, AVDDC/AVDD18/DVDD/DVDDLVDS/IOVDD = 1.8V, -1dBFS differential input, unless otherwise noted.



SFDR Across Input and Sampling Frequencies (auto off)

Figure 32.

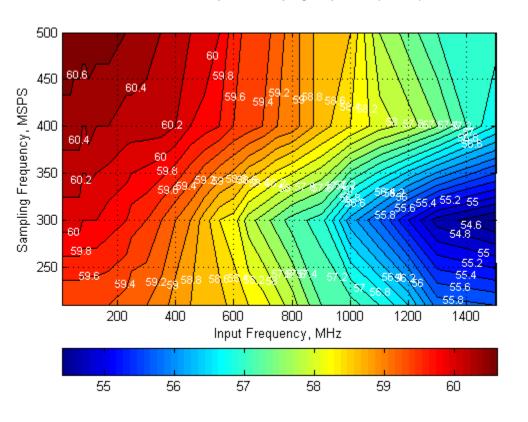
www.ti.com

**ISTRUMENTS** 

EXAS

#### **TYPICAL CHARACTERISTICS (continued)**

Typical values at TA = +25°C, full temperature range is  $T_{MIN}$  = -40°C to  $T_{MAX}$  = +85°C, ADC sampling rate = 500Msps, 50% clock duty cycle, AVDD33 = 3.3V, AVDDC/AVDD18/DVDD/DVDDLVDS/IOVDD = 1.8V, -1dBFS differential input, unless otherwise noted.



SNR Across Input and Sampling Frequencies (auto on)

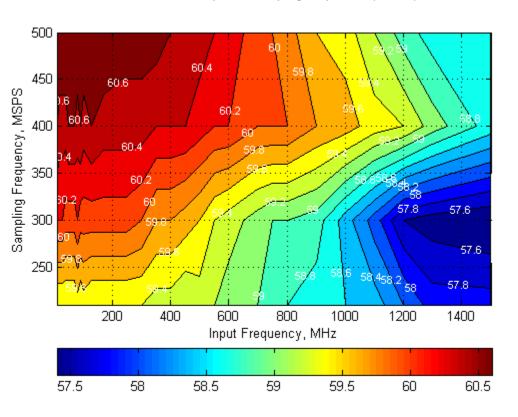
Figure 33.



www.ti.com

#### **TYPICAL CHARACTERISTICS (continued)**

Typical values at TA = +25°C, full temperature range is  $T_{MIN}$  = -40°C to  $T_{MAX}$  = +85°C, ADC sampling rate = 500Msps, 50% clock duty cycle, AVDD33 = 3.3V, AVDDC/AVDD18/DVDD/DVDDLVDS/IOVDD = 1.8V, -1dBFS differential input, unless otherwise noted.



SNR Across Input and Sampling Frequencies (auto on)

Figure 34.



www.ti.com

### FEATURES

#### **POWER DOWN MODES**

The ADS54T04 can be configured via SPI write (address x37) to a stand-by, light or deep sleep power mode which is controlled by the ENABLE pin. The sleep modes are active when the ENABLE pin goes low. Different internal functions stay powered up which results in different power consumption and wake up time between the two sleep modes.

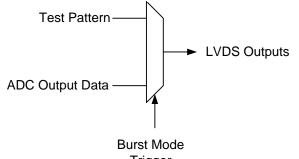
Sleep mode	Wake up time	Power Consumption Auto correction disabled	Power Consumption Auto correction enabled
Complete Shut Down	2.5 ms	7mW	7mW
Stand-by	100µs	7mW	7mW
Deep Sleep	20µs	282mW	370mW
Light Sleep	2µs	549mW	650mW

#### **TEST PATTERN OUTPUT**

The ADS54T04 can be configured to output different test patterns that can be used to verify the digital interface is connected and working properly. To enable the test pattern mode, the high performance mode 1 has to be disabled first via SPI register write. Then different test patterns can be selected by configuring registers x3C, x3D and x3E. All three registers must be configured for the test pattern to work properly.

First set HP1 = 0 (Addr 0x01, D01)

Internally the test pattern replaces the sampled data from the ADC. However at the LVDS outputs the output data is still subject to burst mode operation. In low resolution output the LSBs of the test pattern are replaced with 0s.



Register Address	All 0s	All 1s	Toggle (0xAAA => 0x555)	Toggle (0xFFF => 0x000)
0x3C	0x8000	0xBFFC	0x9554	0xBFFC
0x3D	0x0000	0x3FFC	0x2AA8	0x0000
0x3E	0x0000	0x3FFC	0x1554	0x3FFC

Register Address		Custom Pattern														
	D15	D14	D13	D12	D11	D10	D9	D8	D7	D6	D5	D4	D3	D2	D1	D0
x3C	1	0													0	0
x3D	0	0	D11	D10	D9	D8	D7	D6	D5	D4	D3	D2	D1	D0	0	0
x3E	0	0													0	0

For normal operation, set HP1 = 1 (Addr 0x01, D01) and 0x3C, 0x3D, 0x3E all to 0.



#### www.ti.com

#### **CLOCK INPUT**

The ADS54T04 clock input can be driven differentially with a sine wave, LVPECL or LVDS source with little or no difference in performance. The common mode voltage of the clock input is set to 0.9V using internal  $2k\Omega$  resistors. This allows for AC coupling of the clock inputs. The termination resistors should be placed as close as possible to the clock inputs in order to minimize signal reflections and jitter degradation.

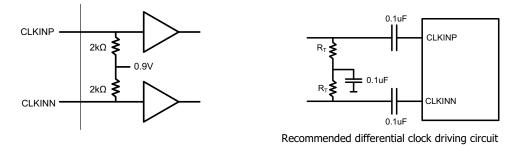


Figure 35. Recommended Differential Clock Driving Circuit

#### SNR AND CLOCK JITTER

The signal to noise ratio of the ADC is limited by three different factors: the quantization noise is typically not noticeable in pipeline converters and is 72dB for a 12bit ADC. The thermal noise limits the SNR at low input frequencies while the clock jitter sets the SNR for higher input frequencies.

$$SNR_{ADC}[dBc] = -20 \times \log \sqrt{\left(10 - \frac{SNR_{Quantization}Noise}{20}\right)^2 + \left(10 - \frac{SNR_{ThermalNoise}}{20}\right)^2 + \left(10 - \frac{SNR_{Jitter}}{20}\right)^2}$$
(1)

The SNR limitation due to sample clock jitter can be calculated as following:

$$SNR_{Jitter} [dBc] = -20 \times log(2\pi \times f_{IN} \times t_{Jitter})$$

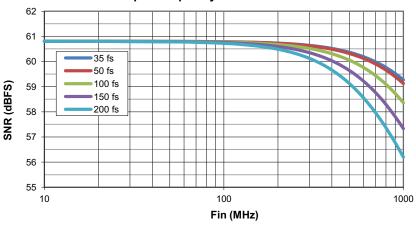
The total clock jitter (TJitter) has three components – the internal aperture jitter (100fs for ADS54T04) which is set by the noise of the clock input buffer, the external clock jitter and the jitter from the analog input signal. It can be calculated as following:

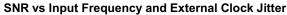
$$T_{\text{Jitter}} = \sqrt{\left(T_{\text{Jitter,Ext.Clock_Input}}\right)^2 + \left(T_{\text{Aperture_ADC}}\right)^2}$$

(3)

External clock jitter can be minimized by using high quality clock sources and jitter cleaners as well as bandpass filters at the clock input while a faster clock slew rate improves the ADC aperture jitter.

The ADS54T04 has a thermal noise of 60.8 dBFS and internal aperture jitter of 100fs. The SNR depending on amount of external jitter for different input frequencies is shown in the following figure.



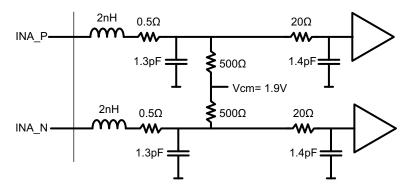




#### ANALOG INPUTS

The ADS54T04 analog signal inputs are designed to be driven differentially. The analog input pins have internal analog buffers that drive the sampling circuit. As a result of the analog buffer, the input pins present a high impedance input across a very wide frequency range to the external driving source which enables great flexibility in the external analog filter design as well as excellent  $50\Omega$  matching for RF applications. The buffer also helps to isolate the external driving circuit from the internal switching currents of the sampling circuit which results in a more constant SFDR performance across input frequencies.

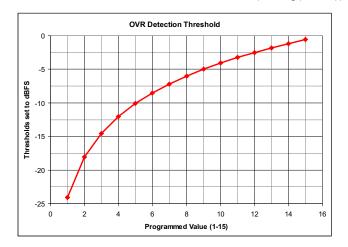
The common-mode voltage of the signal inputs is internally biased to 1.9V using  $500\Omega$  resistors which allows for AC coupling of the input drive network. Each input pin (INP, INM) must swing symmetrically between (VCM + 0.25V) and (VCM – 0.25V), resulting in a 1.0Vpp (default) differential input swing. The input sampling circuit has a 3dB bandwidth that extends up to 1.2GHz.



### **OVER-RANGE INDICATION**

The ADS54T04 provides a fast over-range indication on the OVRA/B pins. The fast OVR is triggered if the input voltage exceeds the programmable overrange threshold and it gets presented after just 12 clock cycles enabling a quicker reaction to an overrange event. The OVR threshold can be configured using SPI register writes.

The input voltage level at which the overload is detected is referred to as the threshold and is programmable using the Over-range threshold bits. The threshold at which fast OVR is triggered is (full-scale  $\times$  [the decimal value of the FAST OVR THRESH bits] /16). After reset, the default value of the over-range threshold is set to 15 (decimal) which corresponds to a threshold of 0.56dB below full scale (20\*log(15/16)).

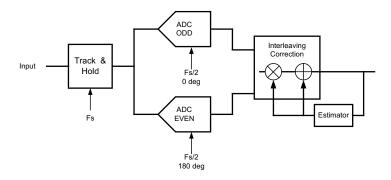




#### www.ti.com

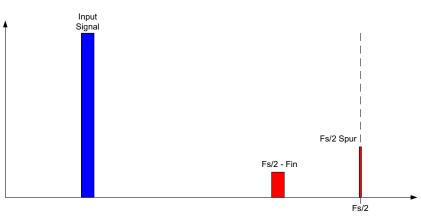
#### INTERLEAVING CORRECTION

Each of the two data converter channels consists of two interleaved ADCs each operating at half of the ADC sampling rate but 180° out of phase from each other. The front end track and hold circuitry is operating at the full ADC sampling rate which minimizes the timing mismatch between the two interleaved ADCs. In addition the ADS54T04 is equipped with internal interleaving correction logic that can be enabled via SPI register write.



The interleaving operation creates 2 distinct and interleaving products:

- Fs/2 Fin: this spur is created by gain timing mismatch between the ADCs. Since internally the front end track and hold is operated at the full sampling rate, this component is greatly improved and mostly dependent on gain mismatch.
- Fs/2 Spur: due to offset mismatch between ADCs



The auto correction loop can be enabled via SPI register write in address 0x01. By default it is disabled for lowest possible power consumption. The DC correction function can be enabled in 0x03 & 0x1A for chA and chB respectively. The default settings for the auto correction function should work for most applications. However please contact Texas Instruments if further fine tuning of the algorithm is required.

The auto correction function yields best performance for input frequencies below 250MHz.

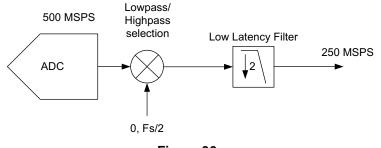
TEXAS INSTRUMENTS

SLAS917B-DECEMBER 2012-REVISED JANUARY 2014

www.ti.com

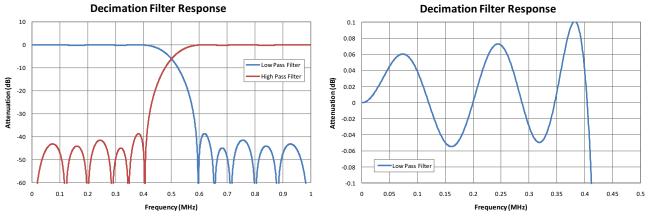
#### **RECEIVE MODE: DECIMATION FILTER**

Each channel has a digital filter in the data path as shown in Figure 36. The filter can be programmed as a low-pass or a high-pass filter and the normalized frequency response of both filters is shown in Figure 37.





The decimation filter response has a 0.1dB pass band ripple with approximately 41% pass-band bandwidth. The stop-band attenuation is approximately 40dB.







www.ti.com

#### FEEDBACK MODE: BURST MODE

In burst mode the output data is alternated between a high resolution 12bit output of 2N samples and a low resolution 9 or 11bit output of 2<sup>N+3</sup> samples. Burst mode is enabled through SPI register write and there are two basic operating modes available – a manual trigger mode where the high resolution output is initiated through external trigger and an auto trigger mode where the internal logic transitions to high resolution output immediately after transmitting the last low resolution sample. Upon enabling burst mode through a SPI register write, the ADS54T04 transmits 2<sup>13</sup> low resolution samples and the trigger command is locked out until completion.

The parameter N can be changed via SPI at any time. It will go in effect with the next output cycle starting with transmission of low resolution samples. The default value for N after reset is N=10.

N limit	10 (minimum)	25 (maximum)
Number of low resolution samples per cycle (2 <sup>N+3</sup> )	8,192	268,435,456
Number of high resolution samples per cycle (2 <sup>N</sup> )	1,024	33,554,432
Total amount of samples per cycle	9,216	301,989,888
Maximum number of high resolution (12-bit) samples per 1 second	55.6M	55.6M

### Manual Trigger Mode

The control of the high resolution output is shown below along with the two output flags (TRDY and HRES).

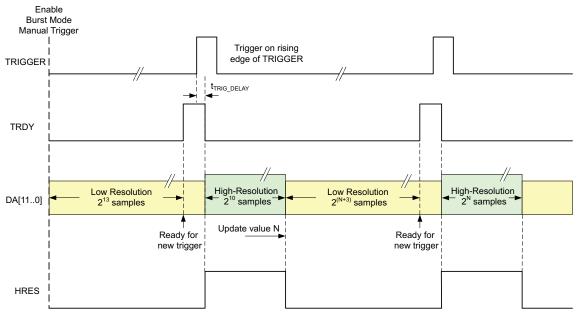


Figure 38. Triggering High Resolution Mode and Lockout Time

After enabling burst mode, the output data DA[11..0] and DB[11..0] are forced to low resolution mode for 2<sup>13</sup> samples. During that period any trigger signal is ignored. The completion of the low resolution sample cycle is signaled by a logic high on the TRDY output pins indicating that a high resolution (12-bit) data output burst can be triggered by a low to high transition on the TRIGGER input. The ADC monitors the TRIGGER input at each rising edge of the input clock.

The high resolution output data starts with a delay of  $t_{TRIG_DELAY} = 1-2$  DA/BCLK clock cycles and is indicated through the HRES data flag which stays high for all 2<sup>N</sup> high resolution samples. At completion the register value for N is verified and transmission of 2<sup>(N+3)</sup> low resolution data immediately follows. Once the last low resolution sample is output on the output data bus, the flag TRDY is asserted high again indicating the end of the lockout period and the next 2<sup>N</sup> high resolution samples can be triggered again.

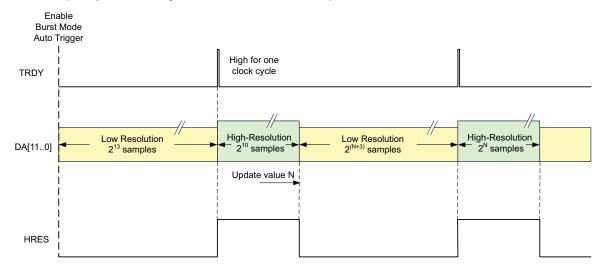
Copyright © 2012–2014, Texas Instruments Incorporated



#### Auto Trigger Mode

This mode is enabled by setting the auto trigger bit via SPI register write and the DA/DB data outputs start in low resolution for 2<sup>13</sup> samples. Immediately following completion of transmission of the last low resolution sample, the outputs automatically start transmitting 2<sup>10</sup> high resolution samples without the need for external trigger ensuring maximum efficiency. Any input signal on the TRIGGER pins is ignored and the TRDY flag will go high only for one clock cycle with the start of the high resolution data.

The output flag HRES is aligned with the 2<sup>N</sup> high resolution output samples and the parameter N can be changed until the next output cycle starts again with low resolution output data.



#### High Resolution Output Data

After trigger, the data outputs DA[11..0]/DB[11..0] are 12-bit resolution for  $2^{N}$  samples, where N is a programmable register with a range 10  $\leq$ N $\leq$ 25 (corresponding to 1024 to 33554432 samples).

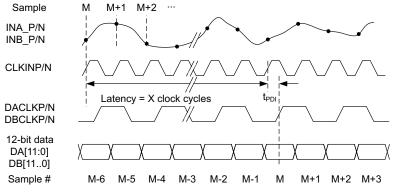


Figure 39. High Resolution Data Output Timing

After the high resolution data, the data output returns to low resolution mode, the logic level of the HRES flag returns low and the trigger is locked out for  $2^{(N+3)}$  samples. N is the sample integer resulting in a maximum output duty cycle of 1/9. During the trigger lockout time, a low to high transition on TRIGGERP/N will be ignored. After the  $2^{N+3}$  low resolution samples, the TRIGGERP/N is re-enabled for the next valid data burst.

#### Low Resolution Output Data

There are two different options for the low resolution output data and the selection is made through SPI register control. The data can either be output at full speed (ADC sampling rate) with the output resolution limited to 9bit (9 MSBs). Alternatively the output resolution can be selected to 11bit (11 MSBs) but at a reduced effective data rate where every 4th sample gets repeated four times.



#### Full Speed – 9bit

www.ti.com

The output data rate and timing is exactly the same as the high resolution data – only the output resolution is limited to the 9 MSBs.

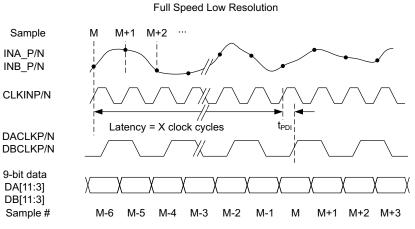


Figure 40. Full Rate Low Resolution Output Data Timing

#### **Decimated Low Resolution Output Data**

In decimated low resolution mode the output data is limited to 11-bits and every sample is repeated four times so the effective data rate is 1/4 of ADC sampling rate. The latency of the ADC sample to output sample is exactly the same as for high resolution data – there is no uncertainty in which conversion sample results in the valid output data. This is because the output continues to run at the ADC sample rate – only the resolution is changed and three out of four samples are deleted.

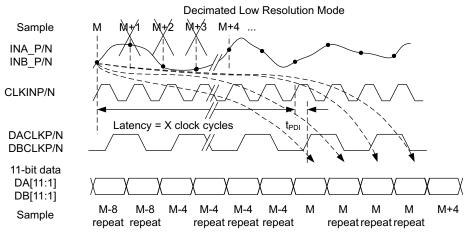
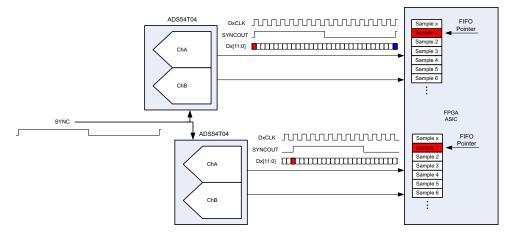


Figure 41. Decimated Low Resolution Output Data Timing Diagram



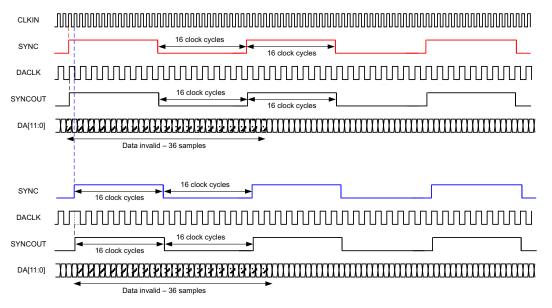
#### **MULTI DEVICE SYNCHRONIZATION**

The ADS54T04 simplifies the synchronization of data from multiple ADCs in one common receiver. Upon receiving the initial SYNC input signal, the ADS54T04 resets all the internal clocks and digital logic while also starting a SYNCOUT signal which operates on a 5bit counter (32 clock cycles). Therefore by providing a common SYNC signal to multiple ADCs their output data can be synchronized as the SYNCOUT signal marks a specific sample with the same latency in all ADCs. The SYNCOUT signal then can be used in the receiving device to synchronize the FIFO pointers across the different input data streams. Thus the output data of multiple ADCs can be aligned properly even if there are different trace lengths between the different ADCs.



The SYNC input signal should be a one time pulse to trigger the periodic 5-bit counter for SYNCOUT or a periodic signal repeating every 32 CLKIN clock cycles. It gets registered on the rising edge of the ADC input clock (CLKIN). Upon registering the initial rising edge of the SYNC signal, the internal clocks and logic get reset which results in invalid output data for 36 samples (1 complete sync cycle and 4 additional samples). The SYNCOUT signal starts with the next output clock (DACLK) rising edge and operates on a 5-bit counter. If a SYNCIN rising edge gets registered at a new position, the counter gets reset and SYNCOUT starts from the new position.

Since the ADS54T04 output interface operates with a DDR clock, the synchronization can happen on the rising edge or falling edge sample. Synchronization on the falling edge sample will result in a half cycle clock stretch of DA/BCLK. For convenience the SYNCOUT signal is available on the ChA/B output LVDS bus. When using decimation the SYNCOUT signal still operates on 32 clock cycles of CLKIN but since the output data is decimated by 2, only the first 18 samples should be discarded.





www.ti.com

#### **PROGRAMMING INTERFACE**

The serial interface (SIF) included in the ADS54T04 is a simple 3 or 4 pin interface. In normal mode, 3 pins are used to communicate with the device. There is an enable (SDENB), a clock (SCLK) and a bi-directional IO port (SDIO). If the user would like to use the 4 pin interface one write must be implemented in the 3 pin mode to enable 4 pin communications. In this mode, the SDO pin becomes the dedicated output. The serial interface has an 8-bit address word and a 16-bit data word. The first rising edge of SCLK after SDENB goes low will latch the read/write bit. If a high is registered then a read is requested, if it is low then a write is requested. SDENB must be brought high again before another transfer can be requested. The signal diagram is shown below:

#### **Device Initialization**

After power up, it is recommended to initialize the device through a hardware reset by applying a logic low pulse on the SRESETb pin (of width greater than 20ns), as shown in Figure 42. This resets all internal digital blocks (including SPI registers) to their default condition.

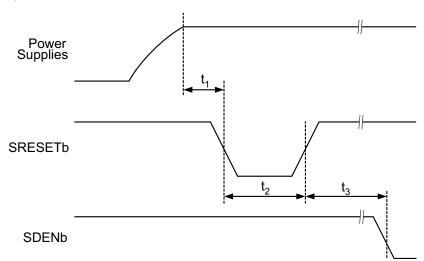


Figure 42. Device Initialization Timing Diagram

	PARAMETER	CONDITIONS	MIN	TYP	MAX	UNIT
t <sub>1</sub>	Power-on delay	Delay from power up to active low RESET pulse	3			ms
t <sub>2</sub>	Reset pulse width	Active low RESET pulse width	20			ns
t <sub>3</sub>	Register write delay	Delay from RESET disable to SDENb active	100			ns

Recommended Device Initialization Sequence:

- 1. Power up
- 2. Reset ADS54T04 using hardware reset.
- 3. Apply clock and input signal.
- 4. Set register 0x01 bit D15 to "1" (ChA Corr EN) and bit D9 to "1" (ChB Corr EN) to enable gain/offset correction circuit and other desired registers.
- 5. Set register 0x03 and 0x1A bit D14 to "1" (Start Auto Corr ChA/B). This clears and resets the accumulator values in the DC and gain correction loop.
- 6. Set register 0x03 and 0x1A bit D14 to "0" (Start Auto Corr ChA/B). This starts the DC and gain autocorrection loop.

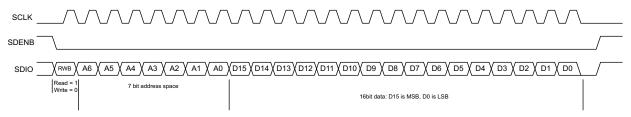


www.ti.com

### Serial Register Write

The internal register of the ADS54T04 can be programmed following these steps:

- 1. Drive SDENB pin low
- 2. Set the R/W bit to '0' (bit A7 of the 8 bit address)
- 3. Initiate a serial interface cycle specifying the address of the register (A6 to A0) whose content has to be written
- 4. Write 16bit data which is latched on the rising edge of SCLK



## Figure 43. Serial Register Write Timing Diagram

	PARAMETER	MIN	TYP <sup>(1)</sup>	MAX	UNIT
f <sub>SCLK</sub>	SCLK frequency (equal to 1/tSCLK)	>DC		20	MHz
t <sub>SLOADS</sub>	SDENB to SCLK setup time	25			ns
t <sub>SLOADH</sub>	SCLK to SDENB hold time	25			ns
t <sub>DSU</sub>	SDIO setup time	25			ns
t <sub>DH</sub>	SDIO hold time	25			ns

(1) Typical values at +25°C; minimum and maximum values across the full temperature range: TMIN = -40°C to TMAX = +85°C, AVDD3V = 3.3V, AVDD, DRVDD = 1.9V, unless otherwise noted.

### Serial Register Readout

The device includes a mode where the contents of the internal registers can be read back using the SDO/SDIO pins. This read-back mode may be useful as a diagnostic check to verify the serial interface communication between the external controller and the ADC.

- 1. Drive SDENB pin low
- 2. Set the RW bit (A7) to '1'. This setting disables any further writes to the registers
- 3. Initiate a serial interface cycle specifying the address of the register (A6 to A0) whose content has to be read.
- 4. The device outputs the contents (D15 to D0) of the selected register on the SDO/SDIO pin
- 5. The external controller can latch the contents at the SCLK rising edge.
- 6. To enable register writes, reset the RW register bit to '0'.

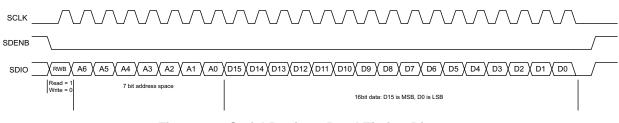


Figure 44. Serial Register Read Timing Diagram



www.ti.com

#### SERIAL REGISTER MAP<sup>(2)</sup>

Register Address								Regist	er Data							
A7–A0 IN HEX	D15	D14	D13	D12	D11	D10	D9	D8	D7	D6	D5	D4	D3	D2	D1	D0
0	3/4 Wire SPI	DecFil/ Burst	0	ChA High/ Low Pass	0	0	ChB High/ Low Pass	0	0	0	Burst rate	0	0	Auto Trigger	0	0
1	ChA Corr EN	0	0	0	0	0	ChB Corr EN	0	0	0	0	0	Data Format	0	Hp Mode1	0
2	0	1	0	0	0		Over-range	e threshold		0	0	0	0	0	0	0
3	0	DC Offset Corr ChA	0	0	1	0	1	1	0	0	0	1	1	0	0	0
Е	Sync Select									0	0					
F	Sync Select 0 0 0 0 VREF Set 0							0	0	0						
1A	0	DC Offset Corr ChB	0	0	1	0	1	1	0	0	0	1	1	0	0	0
2B	0	0	0	0	0	0	0				Т	emp Sense	or	Į.		
2C								Re	set							
34	0	0		Burst M	/lode N		0	0	0	0	0	0	0	0	0	0
37			Sleep	Modes			0	0	0	0	0	0	0	0	0	0
38					HP Mode2					BIAS EN	SYNC EN	TRIGEN	1	1	1	1
ЗA	LVDS Current Strength LVDS SW Internal LVDS 0 0 0 0 DACLK EN							DBCLK EN	0	OVRA EN	OVRB EN					
66				·		·	L	VDS Outp	ut Bus A E	N			·	·		
67							L	VDS Outp	ut Bus B E	N						

(2) Multiple functions in a register can be programmed in a single write operation.

#### DESCRIPTION OF SERIAL INTERFACE REGISTERS

Register Address		Register Data														
A7-A0 in hex	D15	D14	D13	D12	D11	D10	D9	D8	D7	D6	D5	D4	D3	D2	D1	D0
0	3/4 Wire SPI	Dec Fil/ Burst	0	ChA High/ Low Pass	0	0	ChB High/ Low Pass	0	0	0	Burst rate	0	0	Auto Trigger	0	0

D15 **3/4 Wire SPI** Enables 4-bit serial interface when set

Default 0

- 0 3 wire SPI is used with SDIO pin operating as bi-directional I/O port
- 1 4 wire SPI is used with SDIO pin operating as data input and SDO pin as data output port.
- D14 **DecFil/ Burst** 2x decimation filter (Receive Mode) is enabled when bit is set Default 0
- 0 Burst mode enable
- 1 2x decimation filter enabled
- D12 **ChA High/Low** (Decimation filter must be enabled first: set bit D14) **Pass** Default 0
- 0 Low Pass
- 1 High Pass

SLAS917B-DECEMBER 2012-REVISED JANUARY 2014

www.ti.com

- D9 ChB High/Low (Decimation filter must be enabled first: set bit D14) Pass Default 0
- Low Pass
- 0 Low Pass
- 1 High Pass
- D5 **Burst Rate** Low resolution output data rate in burst mode Default 0
- 0 Low resolution (9bit) full output rate
- 1 Decimated low resolution output (4x decimation, 11bit resolution)
- D2 **Auto Trigger** Enables auto trigger mode in burst mode without the need to control the trigger pin. Default 0
- 0 Manual trigger mode using the external trigger input pin
- 1 Auto trigger mode enabled

Register Address								Regis	ter Dat	а						
A7-A0 in hex	D15	D14	D13	D12	D11	D10	D9	D8	D7	D6	D5	D4	D3	D2	D1	D0
1	ChA Corr EN	0	0	0	0	0	ChB Corr EN	0	0	0	0	0	Data Format	0	HP Mode1	0

- D15 **ChA Corr EN (should be enabled for maximum performance)** Default 0
- 0 auto gain correction disabled
- 1 auto gain correction enabled
- D9 ChB Corr EN (should be enabled for maximum performance) Default 0
- 0 auto gain correction disabled
- 1 auto gain correction enabled

#### D3 Data Format

Default 0

- 0 Two's complement
- 1 Offset Binary
- D1 HP Mode 1

Default 0

1 Must be set to 1 for optimum performance



www.ti.com

#### SLAS917B-DECEMBER 2012-REVISED JANUARY 2014

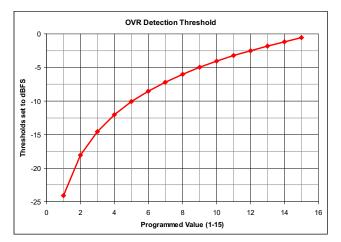
Register Address								Regist	er Data							
A7-A0 in hex	D15	D14	D13	D12	D11	D10	D9	D8	D7	D6	D5	D4	D3	D2	D1	D0
2	0	1	0	0	0	Ov	er-range	e thresh	old	0	0	0	0	0	0	0

#### D14 Read back 1.

#### D10-D7 Over-range threshold

The over-range detection is triggered 12 output clock cycles after the overload condition occurs. The threshold at which the OVR is triggered =  $1.0V \times [\text{decimal value of <Over-range threshold>]/16}.$  After power up or reset, the default value is 15 (decimal) which corresponds to a OVR threshold of 0.56dB below fullscale (20\*log(15/16)). This OVR threshold is applicable to both channels.

#### Default 1111



Register Address								Regist	er Data							
A7-A0 in hex	D15	D14	D13	D12	D11	D10	D9	D8	D7	D6	D5	D4	D3	D2	D1	D0
3	0	DC Offset Coff ChA	0	0	1	0	1	1	0	0	0	1	1	0	0	0

D14 DC Offset Corr ChA Starts DC offset correction loop for ChA

Default 1

0 Starts offset correction loop for ChA

1 DC offset correction loop is cleared

D11, 9, 8, 4, 3 Must be set to 1 for maximum performance Default 1



www.ti.com

#### SLAS917B-DECEMBER 2012-REVISED JANUARY 2014

Register Address								Regist	er Data							
A7-A0 in hex	D15	D14	D13	D12	D11	D10	D9	D8	D7	D6	D5	D4	D3	D2	D1	D0
Е		Sync Select													0	0

D15-D2	<b>Sync Select</b> Default 1010 1010 1010 10	Sync selection for the clock generator block (also need to see address 0x0F)
0000 0000 0000 00	Sync is disabled	
0101 0101 0101 01	Sync is set to one sho	t (one time synchronization only)
1010 1010 1010 10	Sync is derived from S	SYNC input pins
1111 1111 1111 11	not supported	

Register Address								Regist	er Data							
A7-A0 in hex	D15	D14	D13	D12	D11	D10	D9	D8	D7	D6	D5	D4	D3	D2	D1	D0
F		Sync Select				0	0	0	0	\	/REF Se	el	0	0	0	0

block

D15-D12	Sync Select Default 1010	Sync selection for the clock generator
0000	Sync is disabled	
0101	Sync is set to one shot	(one time synchronization only)
1010	Sync is derived from SY	NC input pins
1111	not supported	
D6-D4	VREF SEL Default 000	Internal voltage reference selection
000	1.0V	
001	1.25V	
010	0.9V	
011	0.8V	
100	1.15V	
Others	external reference	

Register Address								Regist	er Data							
A7-A0 in hex	D15	D14	D13	D12	D11	D10	D9	D8	D7	D6	D5	D4	D3	D2	D1	D0
1A	0	DC Offset Corr ChB	0	0	1	0	1	1	0	0	0	1	1	0	0	0

D14	DC Offset Corr ChB Default 1	Starts DC offset correction loop for ChB
0 1	Starts offset correction loop for DC offset correction loop is cl	
D11, 9, 8, 4, 3	Must be set to 1 for maximum Default 1	

### www.ti.com

KAS

STRUMENTS

#### SLAS917B-DECEMBER 2012-REVISED JANUARY 2014

Register Address								Registe	er Data									
A7-A0 in hex	D15	D14	D13	D12	D11	D10	D9	D8	D7	D6	D5	D4	D3	D2	D1	D0		
2B	0	0	0	0	0	0	0	) Temp Sensor										

D8-D0 Ten

Temp Sensor

Internal temperature sensor value – read only

Register Address								Regist	er Data							
A7-A0 in hex	D15	D14	D13	D12	D11	D10	D9	D8	D7	D6	D5	D4	D3	D2	D1	D0
2C		Reset														

D15-D0 Reset Default 0000

This is a software reset to reset all SPI registers to their default value. Self clears to 0.

1101001011110000

Perform software reset

Register Address								Regist	er Data							
A7-A0 in hex	D15	D14	D13	D12	D11	D10	D9	D8	D7	D6	D5	D4	D3	D2	D1	D0
34	0	0		Burst Mode N				0	0	0	0	0	0	0	0	0

D13-D10	Burst Mode N Default 0000	This is the parameter that sets the amount of high samples in burst mode
0000	N = 10	
0001	N = 11	
1111	N = 25	

Register Address								Regist	er Data							
A7-A0 in hex	D15	D14	D13	D12	D11	D10	D9	D8	D7	D6	D5	D4	D3	D2	D1	D0
37			Sleep	Modes			0	0	0	0	0	0	0	0	0	0

D15-D14	Sleep Modes Default 00	Sleep mode selection ENABLE pin goes low
000000	Complete shut down	Wake up time 2.5 ms
100000	Stand-by mode	Wake up time 100 $\mu s$
110000	Deep sleep mode	Wake up time 20 µs
110101	Light sleep mode	Wake up time 2 µs

leep mode selection which is controlled by the ENABLE pin. Sleep modes are active when NABLE pin goes low.

resolution



#### SLAS917B-DECEMBER 2012-REVISED JANUARY 2014

www.ti.com

Register Address				Register Data														
A7-A0 in hex	D15	D14	D13	D12	D11	D10	D9	D8	D7	D6	D5	D4	D3	D2	D1	D0		
38				Н	P Mode	2	Bias EN	SYNC EN	TRIG EN	1	1	1	1					

D15-D7	<b>HP Mode 2</b> Default 111111111	
1	Set to 1 for normal operation	on
D6	BIAS EN Default 1	Enables internal fuse bias voltages – can be disabled after power up to save power.
0	Internal bias powered down	
1	Internal bias enabled	
D5	SYNC EN Default 1	Enables the SYNC input buffer.
0	SYNC input buffer disabled	
1	SYNC input bffer enabled	
D4	<b>TRIG EN</b> Default 1	Enables the TRIGGER input buffer.
0	TRIGGER input buffer disabled	
1	TRIGGER input bffer enabled	
D3-D0	Read back 1	



www.ti.com

## ADS54T04

#### SLAS917B-DECEMBER 2012-REVISED JANUARY 2014

Registe Address								Re	egister	Data						
A7-A0 in h	nex D15	D14	D13	D12	D11	D10	D9	D8	D7	D6	D5	D4	D3	D2	D1	D0
3A		DS Cur Strengt		LVDS	S SW	LV	ernal DS ination	0	0	0	0	DACLK EN	DBCLK EN	0	OVRA EN	OVRB EN
D15-D13	LVDS Cu Strength Default 00		L	VDS ou	tput cu	rrent sti	rength.									
000	2 mA	1	00 3	8 mA												
001	2.25 mA	1	01 3	8.25 mA												
010	2.5 mA	1	10 3	8.5 mA												
011	2.75 mA	1	11 3	8.75 mA												
D12-D11	LVDS SV Default 0 <sup>7</sup>	<b>DS SW</b> LVDS driver internal switch setting – correct range must be set for setting in D15-D13														
01	2 mA to 2	mA to 2.75 mA nA to 3.75mA														
11	3mA to 3.															
D10-D9	Internal I Terminat Default 00	ion	h	nternal t	ermina	tion										
00	2 kΩ															
01	200 Ω															
10	200 Ω															
11	100 Ω															
D4	DACLK E Default 1	EN	E	Enable D	ACLK	output l	ouffer									
0	DACLK o	utput b	uffer po	wered o	lown											
1	DACLK o	•	•													
D3	DBCLK E Default 1	EN	E	Enable D	BCLK	output l	ouffer									
0	DBCLK o	utput b	uffer po	wered o	lown											
1	DBCLK o	•	•													
D1	OVRA EN Default 1	N E	nable (	OVRA o	utput b	uffer										
0	OVRA ou	tout but	ffer pov	vered do	own											
1	OVRA ou	•	•													
D0	OVRB EN Default 1															
0	OVRB ou	tput but	ffer pov	vered do	own											
1			ffer ena													



www.ti.com

#### SLAS917B-DECEMBER 2012-REVISED JANUARY 2014

Register Address								Regist	er Data							
A7-A0 in hex	D15	D14	D13	D12	D11	D10	D9	D8	D7	D6	D5	D4	D3	D2	D1	D0
66	LVDS Output Bus A EN															

D15-D0 LVDS Output Bus A EN Individual LVDS output pin power down for channel A Default FFFF 0 Output is powered down 1 Output is enabled D15 corresponds to TRDYP/N (pins N7, P7) D14 corresponds to HRESP/N (pins N6, P6) SYNCOUTP/N (pins N5, P5) D13 D12 Pins N4, P4 (no connect pins) which are not used and should be powered down for power savings

D11-D0 corresponds to DA11-DA0

Register Address								Regist	er Data							
A7-A0 in hex	D15	D14	D13	D12	D11	D10	D9	D8	D7	D6	D5	D4	D3	D2	D1	D0
67		LVDS Output Bus B EN														

D15-D0	LVDS Output Bus B EN Default FFFF	Individual LVDS output pin power down for channel B
0	Output is powered down	
1	Output is enabled	
D15	corresponds to TRDYP/N (pina	s G3, G4)
D14	corresponds to HRESP/N (pin	s F3, F4)
D13	SYNCOUTP/N (pins F1, F2)	
D12	Pins E3, E4 (no connect pins) power savings	which are not used and should be powered down for
D11-D0	corresponds to DB11-DB0	

Submit Documentation Feedback

39

# **REVISION HISTORY**

С	hanges from Revision A (August 2013) to Revision B	Page
•	Added text to TRDYP/N description	4
•	Added text to HRESP/N description	4
•	Changed package from QFN to nFBGA in THERMAL INFORMATION	5
•	Added text and figure to TEST PATTERN OUTPUT section	20
•	Deleted from last paragraph in INTERLEAVING CORRECTION section	23
•	Changed second paragraph in MULTI DEVICE SYNCHRONIZATION section	28
•	Deleted Register Initialization section and added Device Initialization section	29
•	Changed Register Address E Bits D1 and D0 to 0 in SERIAL REGISTER MAP	31
•	Changed Register Address 38 Bits D3 to D0 from 0 to 1 in SERIAL REGISTER MAP	31
•	Changed Register Address 1 Bit D14 from 1 to 0	
•		
•	Changed Register Address 38 Bits D3 to D0 from 0 to 1 and add D3 to D0 Read back 1	
•		
•		

### Changes from Original (Decmber 2012) to Revision A

Copyright © 2012–2014, Texas Instruments Incorporated

•	Changed D15-10 in register 66 From: Individual LVDS output pin power down for channel B To: Individual LVDS output pin power down for channel A	38
•	Changed D15 in register 66 From: corresponds to TRDYP/N (pins G3, G4) To: corresponds to TRDYP/N (pins N7, P7)	38
•	Changed D14 in register 66 From: corresponds to HRESP/N (pins F3, F4) To: corresponds to HRESP/N (pins N6, P6)	38
•	Changed D13 in Register 66 From: SYNCOUTP/N (pins F1, F2) To: SYNCOUTP/N (pins N5, P5)	38
•	Changed D12 in Register 66 From: "Pins E3, E4" To: "Pins N4, P4"	38
•	Changed D11-D10 - corresponds to DB11-DB0 in Register 66 To: D11-D0 - corresponds to DA11-D0	38
•	Changed D11-D10 - corresponds to DB11-DB0 in Register 67 To: D11-D0 - corresponds to DB11-DB0	38



www.ti.com

Page



19-Dec-2013

## PACKAGING INFORMATION

Orderable Device	Status	Package Type	Package Drawing	Pins	Package Qty	Eco Plan (2)	Lead/Ball Finish	MSL Peak Temp	Op Temp (°C)	Device Marking (4/5)	Samples
ADS54T04IZAY	ACTIVE	NFBGA	ZAY	196	160	Green (RoHS & no Sb/Br)	SNAGCU	Level-3-260C-168 HR	-40 to 85	ADS54T04I	Samples
ADS54T04IZAYR	ACTIVE	NFBGA	ZAY	196	1000	Green (RoHS & no Sb/Br)	SNAGCU	Level-3-260C-168 HR	-40 to 85	ADS54T04I	Samples

<sup>(1)</sup> The marketing status values are defined as follows:

ACTIVE: Product device recommended for new designs.

LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

**NRND:** Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

**PREVIEW**: Device has been announced but is not in production. Samples may or may not be available.

**OBSOLETE:** TI has discontinued the production of the device.

(2) Eco Plan - The planned eco-friendly classification: Pb-Free (RoHS), Pb-Free (RoHS Exempt), or Green (RoHS & no Sb/Br) - please check http://www.ti.com/productcontent for the latest availability information and additional product content details.

**TBD:** The Pb-Free/Green conversion plan has not been defined.

**Pb-Free (RoHS):** TI's terms "Lead-Free" or "Pb-Free" mean semiconductor products that are compatible with the current RoHS requirements for all 6 substances, including the requirement that lead not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, TI Pb-Free products are suitable for use in specified lead-free processes. **Pb-Free (RoHS Exempt):** This component has a RoHS exemption for either 1) lead-based flip-chip solder bumps used between the die and package, or 2) lead-based die adhesive used between

the die and leadframe. The component is otherwise considered Pb-Free (RoHS compatible) as defined above.

Green (RoHS & no Sb/Br): TI defines "Green" to mean Pb-Free (RoHS compatible), and free of Bromine (Br) and Antimony (Sb) based flame retardants (Br or Sb do not exceed 0.1% by weight in homogeneous material)

<sup>(3)</sup> MSL, Peak Temp. - The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

<sup>(4)</sup> There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.

<sup>(5)</sup> Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "~" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.

(6) Lead/Ball Finish - Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead/Ball Finish values may wrap to two lines if the finish value exceeds the maximum column width.

Important Information and Disclaimer: The information provided on this page represents TI's knowledge and belief as of the date that it is provided. TI bases its knowledge and belief on information provided by third parties, and makes no representation or warranty as to the accuracy of such information. Efforts are underway to better integrate information from third parties. TI has taken and continues to take reasonable steps to provide representative and accurate information but may not have conducted destructive testing or chemical analysis on incoming materials and chemicals. TI and TI suppliers consider certain information to be proprietary, and thus CAS numbers and other limited information may not be available for release.



## PACKAGE OPTION ADDENDUM

19-Dec-2013

In no event shall TI's liability arising out of such information exceed the total purchase price of the TI part(s) at issue in this document sold by TI to Customer on an annual basis.

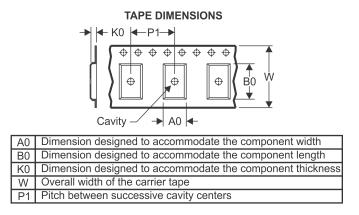
# PACKAGE MATERIALS INFORMATION

www.ti.com

Texas Instruments

#### TAPE AND REEL INFORMATION





## QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE



Device	Package Type	Package Drawing		SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
ADS54T04IZAYR	NFBGA	ZAY	196	1000	330.0	24.4	12.3	12.3	2.3	16.0	24.0	Q1

TEXAS INSTRUMENTS

www.ti.com

# PACKAGE MATERIALS INFORMATION

19-Dec-2013



\*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
ADS54T04IZAYR	NFBGA	ZAY	196	1000	336.6	336.6	31.8

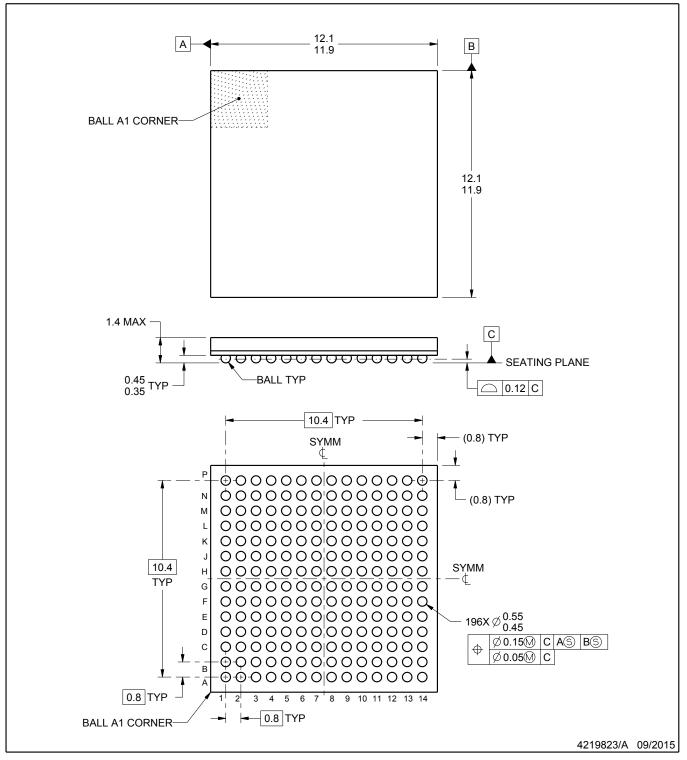
# ZAY0196A



# **PACKAGE OUTLINE**

## NFBGA - 1.4 mm max height

PLASTIC BALL GRID ARRAY



NOTES:

- 1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.
- 2. This drawing is subject to change without notice.

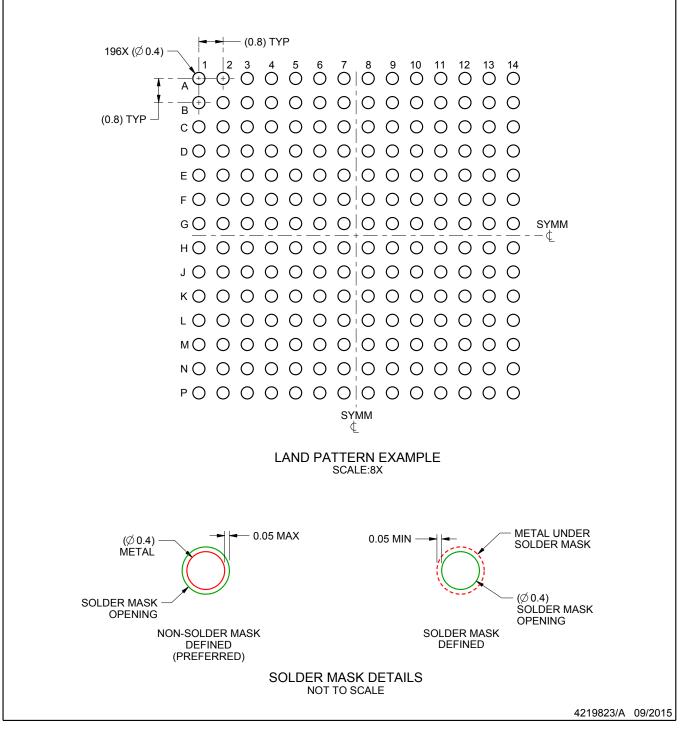


# ZAY0196A

# **EXAMPLE BOARD LAYOUT**

### NFBGA - 1.4 mm max height

PLASTIC BALL GRID ARRAY



NOTES: (continued)

3. Final dimensions may vary due to manufacturing tolerance considerations and also routing constraints. For information, see Texas Instruments literature number SPRAA99 (www.ti.com/lit/spraa99).

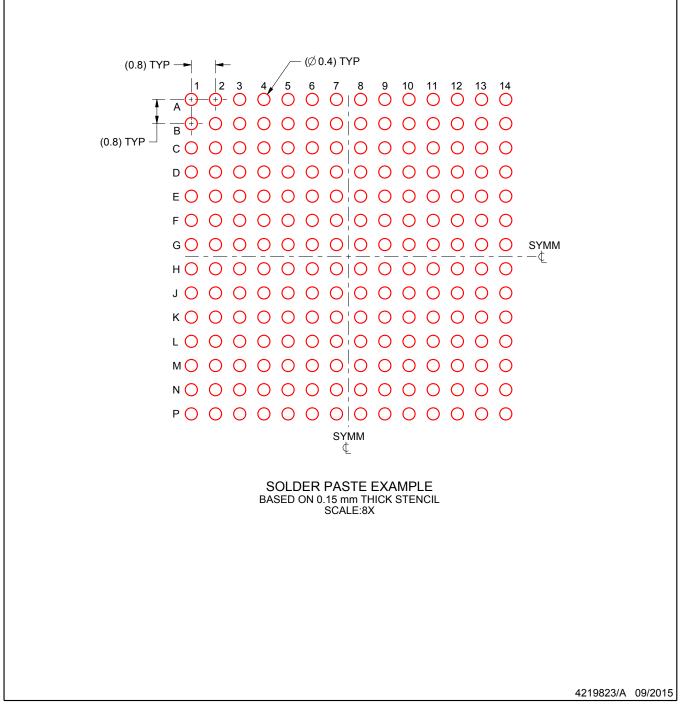


# ZAY0196A

# **EXAMPLE STENCIL DESIGN**

## NFBGA - 1.4 mm max height

PLASTIC BALL GRID ARRAY



NOTES: (continued)

4. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release.



#### **IMPORTANT NOTICE**

Texas Instruments Incorporated and its subsidiaries (TI) reserve the right to make corrections, enhancements, improvements and other changes to its semiconductor products and services per JESD46, latest issue, and to discontinue any product or service per JESD48, latest issue. Buyers should obtain the latest relevant information before placing orders and should verify that such information is current and complete. All semiconductor products (also referred to herein as "components") are sold subject to TI's terms and conditions of sale supplied at the time of order acknowledgment.

TI warrants performance of its components to the specifications applicable at the time of sale, in accordance with the warranty in TI's terms and conditions of sale of semiconductor products. Testing and other quality control techniques are used to the extent TI deems necessary to support this warranty. Except where mandated by applicable law, testing of all parameters of each component is not necessarily performed.

TI assumes no liability for applications assistance or the design of Buyers' products. Buyers are responsible for their products and applications using TI components. To minimize the risks associated with Buyers' products and applications, Buyers should provide adequate design and operating safeguards.

TI does not warrant or represent that any license, either express or implied, is granted under any patent right, copyright, mask work right, or other intellectual property right relating to any combination, machine, or process in which TI components or services are used. Information published by TI regarding third-party products or services does not constitute a license to use such products or services or a warranty or endorsement thereof. Use of such information may require a license from a third party under the patents or other intellectual property of the third party, or a license from TI under the patents or other intellectual property of TI.

Reproduction of significant portions of TI information in TI data books or data sheets is permissible only if reproduction is without alteration and is accompanied by all associated warranties, conditions, limitations, and notices. TI is not responsible or liable for such altered documentation. Information of third parties may be subject to additional restrictions.

Resale of TI components or services with statements different from or beyond the parameters stated by TI for that component or service voids all express and any implied warranties for the associated TI component or service and is an unfair and deceptive business practice. TI is not responsible or liable for any such statements.

Buyer acknowledges and agrees that it is solely responsible for compliance with all legal, regulatory and safety-related requirements concerning its products, and any use of TI components in its applications, notwithstanding any applications-related information or support that may be provided by TI. Buyer represents and agrees that it has all the necessary expertise to create and implement safeguards which anticipate dangerous consequences of failures, monitor failures and their consequences, lessen the likelihood of failures that might cause harm and take appropriate remedial actions. Buyer will fully indemnify TI and its representatives against any damages arising out of the use of any TI components in safety-critical applications.

In some cases, TI components may be promoted specifically to facilitate safety-related applications. With such components, TI's goal is to help enable customers to design and create their own end-product solutions that meet applicable functional safety standards and requirements. Nonetheless, such components are subject to these terms.

No TI components are authorized for use in FDA Class III (or similar life-critical medical equipment) unless authorized officers of the parties have executed a special agreement specifically governing such use.

Only those TI components which TI has specifically designated as military grade or "enhanced plastic" are designed and intended for use in military/aerospace applications or environments. Buyer acknowledges and agrees that any military or aerospace use of TI components which have *not* been so designated is solely at the Buyer's risk, and that Buyer is solely responsible for compliance with all legal and regulatory requirements in connection with such use.

TI has specifically designated certain components as meeting ISO/TS16949 requirements, mainly for automotive use. In any case of use of non-designated products, TI will not be responsible for any failure to meet ISO/TS16949.

Products		Applications				
Audio	www.ti.com/audio	Automotive and Transportation	www.ti.com/automotive			
Amplifiers	amplifier.ti.com	Communications and Telecom	www.ti.com/communications			
Data Converters	dataconverter.ti.com	Computers and Peripherals	www.ti.com/computers			
DLP® Products	www.dlp.com	Consumer Electronics	www.ti.com/consumer-apps			
DSP	dsp.ti.com	Energy and Lighting	www.ti.com/energy			
Clocks and Timers	www.ti.com/clocks	Industrial	www.ti.com/industrial			
Interface	interface.ti.com	Medical	www.ti.com/medical			
Logic	logic.ti.com	Security	www.ti.com/security			
Power Mgmt	power.ti.com	Space, Avionics and Defense	www.ti.com/space-avionics-defense			
Microcontrollers	microcontroller.ti.com	Video and Imaging	www.ti.com/video			
RFID	www.ti-rfid.com					
OMAP Applications Processors	www.ti.com/omap	TI E2E Community	e2e.ti.com			
Wireless Connectivity	www.ti.com/wirelessconnectivity					

Mailing Address: Texas Instruments, Post Office Box 655303, Dallas, Texas 75265 Copyright © 2015, Texas Instruments Incorporated