

# LMH6628 Dual Wideband, Low Noise, Voltage Feedback Op Amp

Check for Samples: LMH6628

### **FEATURES**

Wide Unity Gain Bandwidth: 300MHz

Low Noise: 2nV/√hZ

Low Distortion: -65/-74dBc (10MHz)

Settling Time: 12ns to 0.1%

Wide Supply Voltage Range: ±2.5V to ±6V

High Output Current: ±85mA

Improved Replacement for CLC428

### **APPLICATIONS**

High Speed Dual Op Amp

· Low Noise Integrators

Low Noise Active Filters

Driver/receiver for Transmission Systems

High Speed Detectors

I/Q Channel Amplifiers

### DESCRIPTION

The Texas Instruments LMH6628 is a high speed dual op amp that offers a traditional voltage feedback topology featuring unity gain stability and slew enhanced circuitry. The LMH6628's low noise and very low harmonic distortion combine to form a wide dynamic range op amp that operates from a single (5V to 12V) or dual (±5V) power supply.

Each of the LMH6628's closely matched channels provides a 300MHz unity gain bandwidth and low input voltage noise density  $(2nV/\sqrt{hZ})$ . Low 2nd/3rd harmonic distortion (-65/-74dBc at 10MHz) make the LMH6628 a perfect wide dynamic range amplifier for matched I/Q channels.

With its fast and accurate settling (12ns to 0.1%), the LMH6628 is also an excellent choice for wide dynamic range, anti-aliasing filters to buffer the inputs of hi resolution analog-to-digital converters. Combining the LMH6628's two tightly matched amplifiers in a single 8-pin SOIC package reduces cost and board space for many composite amplifier applications such as active filters, differential line drivers/receivers, fast peak detectors and instrumentation amplifiers.

The LMH6628 is fabricated using Tl's VIP10<sup>™</sup> complimentary bipolar process.

To reduce design times and assist in board layout, the LMH6628 is supported by an evaluation board (CLC730036).

#### **Connection Diagram**

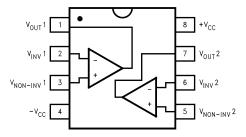


Figure 1. 8-Pin SOIC, Top View

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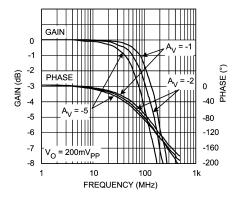


Figure 2. Inverting Frequency Response



These devices have limited built-in ESD protection. The leads should be shorted together or the device placed in conductive foam during storage or handling to prevent electrostatic damage to the MOS gates.

## **Absolute Maximum Ratings**(1)(2)

	<u> </u>								
	Human Body Model	2kV							
ESD Tolerance <sup>(3)</sup>	Machine Model	200V							
Supply Voltage		13.5							
Short Circuit Current		See <sup>(4)</sup>							
Common-Mode Input Voltage		V+ - V <sup>-</sup>							
Differential Input Voltage		V+ - V <sup>-</sup>							
Maximum Junction Temperature		+150°C							
Storage Temperature Range		−65°C to +150°C							
Lead Temperature (soldering 10 sec)		+300°C							

- (1) Absolute Maximum Ratings indicate limits beyond which damage to the device may occur. Operating Ratings indicate conditions for which the device is intended to be functional, but specific performance is not ensured. For ensured specifications, see the Electrical Characteristics tables.
- (2) If Military/Aerospace specified devices are required, please contact the Texas Instruments Sales Office/ Distributors for availability and specifications.
- (3) Human body model, 1.5kΩ in series with 100pF. Machine model, 0Ω In series with 200pF.
- (4) Output is short circuit protected to ground, however maximum reliability is obtained if output current does not exceed 160mA.

# Operating Ratings(1)

Thermal Resistance (2)		
Package	$(\theta_{ m JC})$	$(\theta_{JA})$
SOIC	65°C/W	145°C/W
Temperature Range	-40°C to +85°C	
Nominal Supply Voltage		±2.5V to ±6V

- (1) Absolute Maximum Ratings indicate limits beyond which damage to the device may occur. Operating Ratings indicate conditions for which the device is intended to be functional, but specific performance is not ensured. For ensured specifications, see the Electrical Characteristics tables.
- (2) The maximum power dissipation is a function of  $T_{J(MAX)}$ ,  $\theta_{JA}$  and  $T_A$ . The maximum allowable power dissipation at any ambient temperature is  $P_D = (T_{J(MAX)}, T_A) / \theta_{JA}$ . All numbers apply for packages soldered directly onto a PC board.



# Electrical Characteristics(1)

 $V_{CC}$  = ±5V,  $A_V$  = +2V/V,  $R_F$  = 100 $\Omega$ ,  $R_G$  = 100 $\Omega$ ,  $R_L$  = 100 $\Omega$ ; unless otherwise specified. **Boldface** limits apply at the temperature extremes.

Parameter	Conditions	Min	Тур	Max	Units
Domain Response	,		1		
Gain Bandwidth Product	$V_O < 0.5V_{PP}$		200		MHz
-3dB Bandwidth, A <sub>V</sub> = +1	$V_O < 0.5V_{PP}$	180	300		MHz
-3dB Bandwidth, A <sub>V</sub> = +2	V <sub>O</sub> < 0.5V <sub>PP</sub>		100		MHz
Gain Flatness					
Peaking	DC to 200MHz		0.0		dB
Rolloff	DC to 20MHz		.1		dB
Linear Phase Deviation	DC to 20MHz		.1		deg
ain Response					
Rise and Fall Time	1V Step		4		ns
Settling Time	2V Step to 0.1%		12		ns
Overshoot	1V Step		1		%
Slew Rate	4V Step	300	550		V/µs
And Noise Response					
2nd Harmonic Distortion	1V <sub>PP</sub> , 10MHz		-65		dBc
3rd Harmonic Distortion	1V <sub>PP</sub> , 10MHz		-74		dBc
Equivalent Input Noise					
Voltage	1MHz to 100MHz		2		nV/√ <del>Hz</del>
Current	1MHz to 100MHz		2		pA/√Hz
Crosstalk	Input Referred, 10MHz		-62		dB
Performance		·	•		·
Open-Loop Gain		56 <b>53</b>	63		dB
Input Offset Voltage			±.5	±2 <b>±2.6</b>	mV
Average Drift			5		μV/°C
Input Bias Current			±.7	±20 ±30	μA
Average Drift			150		nA/°C
Input Offset Current			0.3	±6	μA
Average Drift			5		nA/°C
Power Supply Rejection Ratio		60 <b>46</b>	70		dB
Common-Mode Rejection Ratio		57 <b>54</b>	62		dB
Supply Current	Per Channel, R <sub>L</sub> = ∞	7.5 <b>7.0</b>	9	12 <b>12.5</b>	mA
ous Performance					
Input Resistance	Common-Mode		500		kΩ
	Differential-Mode		200		kΩ
Input Capacitance	Common-Mode		1.5		pF
	Differential-Mode		1.5		pF
Output Resistance	Closed-Loop		.1		Ω
	Gain Bandwidth Product  -3dB Bandwidth, A <sub>V</sub> = +1  -3dB Bandwidth, A <sub>V</sub> = +2  Gain Flatness Peaking Rolloff Linear Phase Deviation  Ain Response Rise and Fall Time Settling Time Overshoot Slew Rate  And Noise Response  2nd Harmonic Distortion 3rd Harmonic Distortion Equivalent Input Noise Voltage Current Crosstalk  Performance  Open-Loop Gain Input Offset Voltage  Average Drift Input Bias Current  Average Drift Power Supply Rejection Ratio  Supply Current  Ous Performance Input Capacitance  Input Capacitance	Domain Response           Gain Bandwidth Product         V <sub>O</sub> < 0.5V <sub>PP</sub> -3dB Bandwidth, A <sub>V</sub> = +1         V <sub>O</sub> < 0.5V <sub>PP</sub> -3dB Bandwidth, A <sub>V</sub> = +2         V <sub>O</sub> < 0.5V <sub>PP</sub> Gain Flatness         V <sub>O</sub> < 0.5V <sub>PP</sub> Peaking         DC to 200MHz           Rolloff         DC to 20MHz           Linear Phase Deviation         DC to 20MHz           Linear Phase Deviation         DC to 20MHz           Linear Phase Deviation         1V Step           Settling Time         2V Step to 0.1%           Overshoot         1V Step           Settling Time         2V Step to 0.1%           Overshoot         1V Step           Slew Rate         4V Step           And Noise Response         2nd Harmonic Distortion         1V <sub>PP</sub> , 10MHz           3rd Harmonic Distortion         1V <sub>PP</sub> , 10MHz           4 Imput Required Input Noise         1MHz to 100MHz           Current         1MHz to 100MHz           Crosstalk         Input Referred, 10MHz           Performance         Open-Loop Gain           Input Offset Voltage         Average Drift           Input Offset Current         Average Drift           Power Supply Rejection Ratio         Per Channel, R <sub>L</sub> = ∞	Domain Response   Gain Bandwidth Product   V <sub>O</sub> < 0.5V <sub>PP</sub>   180    -3dB Bandwidth, A <sub>V</sub> = +1   V <sub>O</sub> < 0.5V <sub>PP</sub>   180    -3dB Bandwidth, A <sub>V</sub> = +2   V <sub>O</sub> < 0.5V <sub>PP</sub>   180    -3dB Bandwidth, A <sub>V</sub> = +2   V <sub>O</sub> < 0.5V <sub>PP</sub>   180    -3dB Bandwidth, A <sub>V</sub> = +2   V <sub>O</sub> < 0.5V <sub>PP</sub>   180    -3dB Bandwidth, A <sub>V</sub> = +2   V <sub>O</sub> < 0.5V <sub>PP</sub>   180    -3dB Bandwidth, A <sub>V</sub> = +2   V <sub>O</sub> < 0.5V <sub>PP</sub>   180    -3dB Bandwidth, A <sub>V</sub> = +2   V <sub>O</sub> < 0.5V <sub>PP</sub>   180    -3dB Bandwidth, A <sub>V</sub> = +2   V <sub>O</sub> < 0.5V <sub>PP</sub>   180    -3dB Bandwidth, A <sub>V</sub> = +2   V <sub>O</sub> < 0.5V <sub>PP</sub>   180    -3dB Bandwidth, A <sub>V</sub> = +2   V <sub>O</sub> < 0.5V <sub>PP</sub>   180    -3dB Bandwidth, A <sub>V</sub> = +2   V <sub>O</sub> < 0.5V <sub>PP</sub>   180    -3dB Bandwidth, A <sub>V</sub> = +2   V <sub>O</sub> < 0.5V <sub>PP</sub>   180    -3dB Bandwidth, A <sub>V</sub> = +2   V <sub>O</sub> < 0.5V <sub>PP</sub>   180    -3dB Bandwidth, A <sub>V</sub> = +2   V <sub>O</sub> < 0.5V <sub>PP</sub>   180    -3dB Bandwidth, A <sub>V</sub> = +2   V <sub>O</sub> < 0.5V <sub>PP</sub>   180    -3dB Bandwidth, A <sub>V</sub> = +2   V <sub>O</sub> < 0.5V <sub>PP</sub>   180    -3dB Bandwidth, A <sub>V</sub> = +2   V <sub>O</sub> < 0.5V <sub>PP</sub>   180    -3dB Bandwidth, A <sub>V</sub> = +2   V <sub>O</sub> < 0.5V <sub>PP</sub>   180    -3dB Bandwidth, A <sub>V</sub> = +2   V <sub>O</sub> < 0.5V <sub>PP</sub>   180    -3dB Bandwidth, A <sub>V</sub> = +2   V <sub>O</sub> < 0.5V <sub>PP</sub>   180    -3dB Bandwidth, A <sub>V</sub> = +2   V <sub>O</sub> < 0.5V <sub>PP</sub>   180    -3dB Bandwidth, A <sub>V</sub> = +2   V <sub>O</sub> < 0.5V <sub>PP</sub>   180    -3dB Bandwidth, A <sub>V</sub> = +2   V <sub>O</sub> < 0.5V <sub>PP</sub>   180    -3dB Bandwidth, A <sub>V</sub> = +2   V <sub>O</sub> < 0.5V <sub>PP</sub>   180    -3dB Bandwidth, A <sub>V</sub> = +2   V <sub>O</sub> < 0.5V <sub>PP</sub>   180    -3dB Bandwidth, A <sub>V</sub> = +2   V <sub>O</sub> < 0.5V <sub>PP</sub>   180    -3dB Bandwidth, A <sub>V</sub> = +2   V <sub>O</sub> < 0.5V <sub>PP</sub>   180    -3dB Bandwidth, A <sub>V</sub> = +2   V <sub>O</sub> < 0.5V <sub>PP</sub>   180    -3dB Bandwidth, A <sub>V</sub> = +2   V <sub>O</sub> < 0.5V <sub>PP</sub>   180    -3dB Bandwidth, A <sub>V</sub> = +2   V <sub>O</sub> < 0.5V <sub>PP</sub>   180    -3dB Bandwidth, A <sub>V</sub> = +2   V <sub>O</sub> < 0.5V <sub>PP</sub>   180    -3dB Bandwidth, A <sub>V</sub> = +2   V <sub>O</sub> < 0.5V <sub>P</sub>   180    -3dB Bandwidth, A <sub>V</sub> = +2   V <sub>O</sub> < 0.5V <sub>P</sub>   180    -3dB Bandwidth, A <sub>V</sub> = +2   V <sub>O</sub> < 0.5V <sub>P</sub>   180    -3dB Bandwidth, A <sub>V</sub> = +2   V <sub>O</sub> < 0.5V <sub>P</sub>   180    -3d Bandwidth, A <sub>V</sub> = +2   V <sub>O</sub> < 0.5V <sub>P</sub>   180    -3d Bandwidth, A <sub>V</sub> = +2   V <sub>O</sub> < 0.5V <sub>P</sub>   180    -3d Bandwidth, A <sub>V</sub> =	Domain Response   Gain Bandwidth Product   V <sub>O</sub> < 0.5V <sub>PP</sub>   200   3-3dB Bandwidth, A <sub>V</sub> = +1   V <sub>O</sub> < 0.5V <sub>PP</sub>   180   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300   300	Domain Response         Gain Bandwidth Product         V <sub>O</sub> < 0.5V <sub>PP</sub> 200           -3dB Bandwidth, A <sub>V</sub> = +1         V <sub>O</sub> < 0.5V <sub>PP</sub> 180         300           -3dB Bandwidth, A <sub>V</sub> = +2         V <sub>O</sub> < 0.5V <sub>PP</sub> 100           Gain Flatness         V <sub>O</sub> < 0.5V <sub>PP</sub> 100           Peaking         DC to 200MHz         0.0           Rolloff         DC to 200MHz         .1           Linear Phase Deviation         DC to 20MHz         .1           Linear Phase Deviation         1V Step         .4           Settling Time         2V Step to 0.1%         .1           Settling Time         2V Step to 0.1%         .12           Overshoot         1V Step         .1         .1           Siew Rate         4V Step         .300         .550           And Marmonic Distortion

<sup>(1)</sup> Electrical Table values apply only for factory testing conditions at the temperature indicated. Factory testing conditions result in very limited self-heating of the device such that T<sub>J</sub> = T<sub>A</sub>. No specification of parametric performance is indicated in the electrical tables under conditions of internal self heating where T<sub>J</sub> > T<sub>A</sub>. See Note 6 for information on temperature de-rating of this device." Min/Max ratings are based on product characterization and simulation. Individual parameters are tested as noted.



# Electrical Characteristics<sup>(1)</sup> (continued)

 $V_{CC}$  = ±5V,  $A_V$  = +2V/V,  $R_F$  = 100 $\Omega$ ,  $R_G$  = 100 $\Omega$ ,  $R_L$  = 100 $\Omega$ ; unless otherwise specified. **Boldface** limits apply at the temperature extremes.

Symbol	Parameter	Conditions	Min	Тур	Max	Units
Vo	Output Voltage Range	R <sub>L</sub> = ∞		±3.8		V
V <sub>OL</sub>		$R_L = 100\Omega$	±3.2 ± <b>3.1</b>	±3.5		V
CMIR	Input Voltage Range	Common- Mode		±3.7		V
Io	Output Current		±50	±85		mA



## **Typical Performance Characteristics**

(T<sub>A</sub> = +25°, A<sub>V</sub> = +2, V<sub>CC</sub> = ±5V, R<sub>f</sub> =100 $\Omega$ , R<sub>L</sub> = 100 $\Omega$ , unless specified)

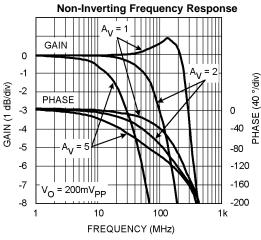
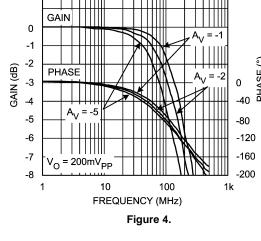
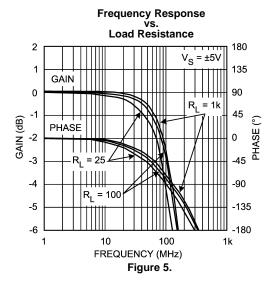
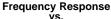


Figure 3.



**Inverting Frequency Response** 





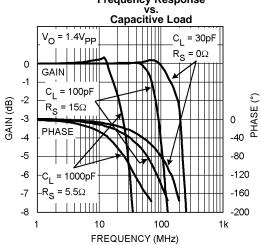
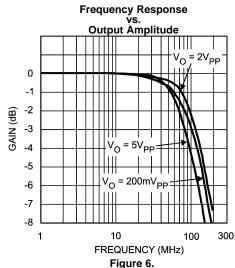
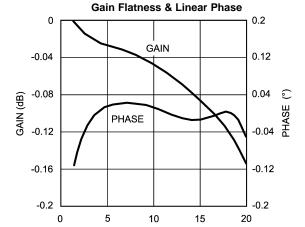


Figure 7.





FREQUENCY (MHz) Figure 8.



 $(T_A = +25^\circ, A_V = +2, V_{CC} = \pm 5V, R_f = 100\Omega, R_L = 100\Omega, unless specified)$ 

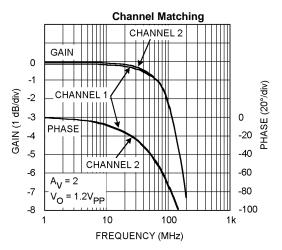
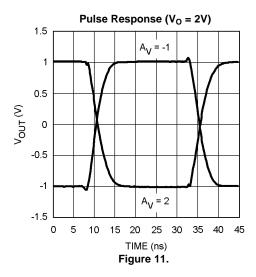
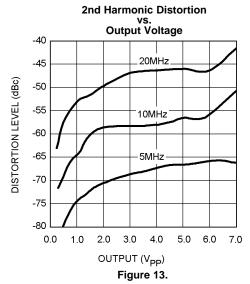


Figure 9.





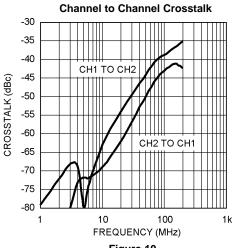
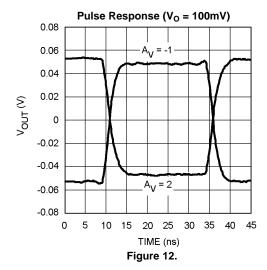


Figure 10.



**3rd Harmonic Distortion** 

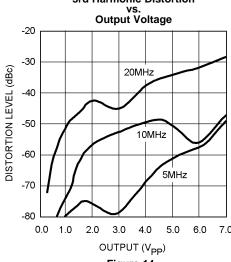
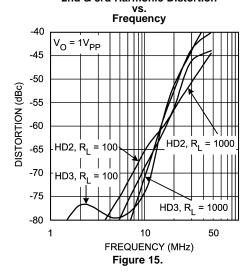


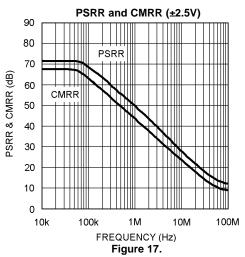
Figure 14.

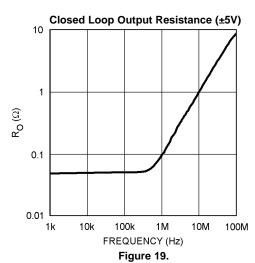
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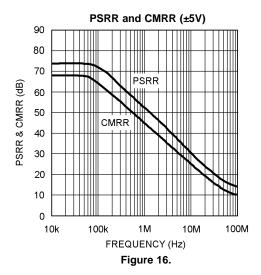


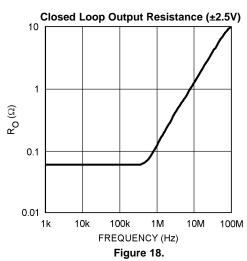
 $(T_A=+25^\circ,\,A_V=+2,\,V_{CC}=\pm5V,\,R_f=100\Omega,\,R_L=100\Omega,\,unless\,\,specified)$  2nd & 3rd Harmonic Distortion

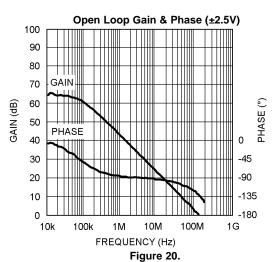












(T<sub>A</sub> = +25°, A<sub>V</sub> = +2, V<sub>CC</sub> =  $\pm$ 5V, R<sub>f</sub> =100 $\Omega$ , R<sub>L</sub> = 100 $\Omega$ , unless specified)

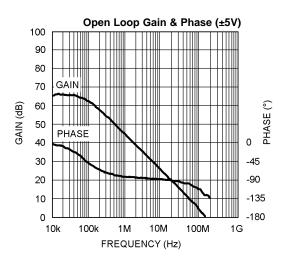
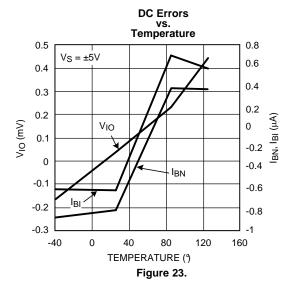


Figure 21.



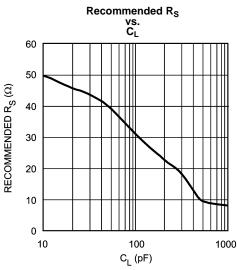


Figure 22.

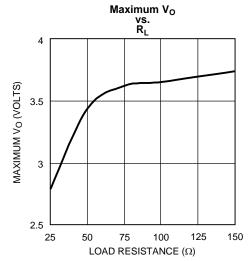


Figure 24.

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 $(T_A = +25^\circ, A_V = +2, V_{CC} = \pm 5V, R_f = 100\Omega, R_L = 100\Omega, unless specified)$ 

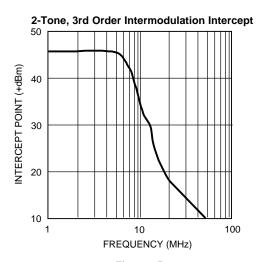


Figure 25.

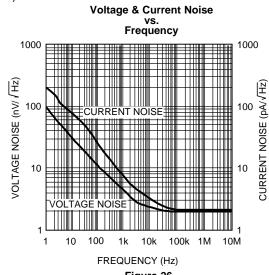
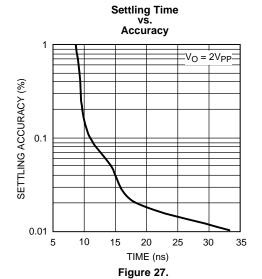


Figure 26.



Product Folder Links: LMH6628

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#### APPLICATION SECTION

#### LOW NOISE DESIGN

Ultimate low noise performance from circuit designs using the LMH6628 requires the proper selection of external resistors. By selecting appropriate low valued resistors for  $R_F$  and  $R_G$ , amplifier circuits using the LMH6628 can achieve output noise that is approximately the equivalent voltage input noise of  $2nV/\sqrt{\text{Hz}}$  multiplied by the desired gain  $(A_V)$ .

#### DC BIAS CURRENTS AND OFFSET VOLTAGES

Cancellation of the output offset voltage due to input bias currents is possible with the LMH6628. This is done by making the resistance seen from the inverting and non-inverting inputs equal. Once done, the residual output offset voltage will be the input offset voltage ( $V_{OS}$ ) multiplied by the desired gain ( $A_V$ ). Application Note OA-7 (SNOA365) offers several solutions to further reduce the output offset.

#### **OUTPUT AND SUPPLY CONSIDERATIONS**

With  $\pm 5V$  supplies, the LMH6628 is capable of a typical output swing of  $\pm 3.8V$  under a no-load condition. Additional output swing is possible with slightly higher supply voltages. For loads of less than  $50\Omega$ , the output swing will be limited by the LMH6628's output current capability, typically 85mA.

Output settling time when driving capacitive loads can be improved by the use of a series output resistor. See Figure 22.

#### LAYOUT

Proper power supply bypassing is critical to insure good high frequency performance and low noise. De-coupling capacitors of 0.1µF should be placed as close as possible to the power supply pins. The use of surface mounted capacitors is recommended due to their low series inductance.

A good high frequency layout will keep power supply and ground traces away from the inverting input and output pins. Parasitic capacitance from these nodes to ground causes frequency response peaking and possible circuit oscillation. See OA-15 (SNOA367) for more information. Texas Instruments suggests the CLC730036 (SOIC) dual op amp evaluation board as a guide for high frequency layout and as an aid in device evaluation.

### **ANALOG DELAY CIRCUIT (ALL-PASS NETWORK)**

The circuit in Figure 28 implements an all-pass network using the LMH6628. A wide bandwidth buffer (LM7121) drives the circuit and provides a high input impedance for the source. As shown in Figure 29, the circuit provides a 13.1ns delay (with R =  $40.2\Omega$ , C = 47pF).  $R_F$  and  $R_G$  should be of equal and low value for parasitic insensitive operation.

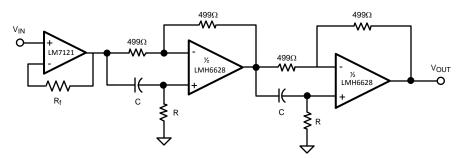


Figure 28. Circuit That Implements an All-pass Network Using the LMH6628



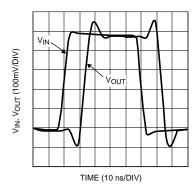


Figure 29. Delay Circuit Response to 0.5V Pulse

The circuit gain is +1 and the delay is determined by the following equations.

$$\tau_{\text{delay}} = 2(2RC + T_{\text{d}})$$
 (1)

$$T_{d} = \frac{1}{360} \frac{d\phi}{df}; \tag{2}$$

where  $T_d$  is the delay of the op amp at  $A_V = +1$ .

The LMH6628 provides a typical delay of 2.8ns at its -3dB point.

#### FULL DUPLEX DIGITAL OR ANALOG TRANSMISSION

Simultaneous transmission and reception of analog or digital signals over a single coaxial cable or twisted-pair line can reduce cabling requirements. The LMH6628's wide bandwidth and high common-mode rejection in a differential amplifier configuration allows full duplex transmission of video, telephone, control and audio signals.

In the circuit shown in Figure 30, one of the LMH6628's amps is used as a "driver" and the other as a difference "receiver" amplifier. The output impedance of the "driver" is essentially zero. The two R's are chosen to match the characteristic impedance of the transmission line. The "driver" op amp gain can be selected for unity or greater.

Receiver amplifier  $A_2$  ( $B_2$ ) is connected across R and forms differential amplifier for the signals transmitted by driver  $A_2$  ( $B_2$ ). If  $R_F$  equals  $R_G$ , receiver  $A_2$  ( $B_1$ ) will then reject the signals from driver  $A_1$  ( $B_1$ ) and pass the signals from driver  $B_1$  ( $A_1$ ).

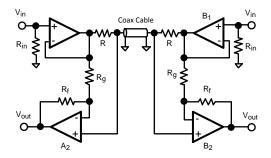


Figure 30. Full Duplex Transmit and Receive Using the LMH6628

The output of the receiver amplifier will be:

$$V_{\text{out}}_{A(B)} = \frac{1}{2} V_{\text{in}}_{A(B)} \left[ 1 - \frac{R_f}{R_g} \right] + \frac{1}{2} V_{\text{in}}_{B(A)} \left[ 1 + \frac{R_f}{R_g} \right]$$
(3)



Care must be given to layout and component placement to maintain a high frequency common-mode rejection. The plot of Figure 31 shows the simultaneous reception of signals transmitted at 1MHz and 10MHz.

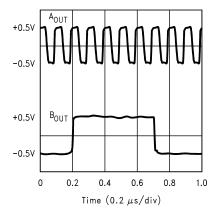


Figure 31. Simultaneous Reception of Signals Transmitted at 1MHz and 10MHz

#### POSITIVE PEAK DETECTOR

The LMH6628's dual amplifiers can be used to implement a unity-gain peak detector circuit as shown in Figure 32.

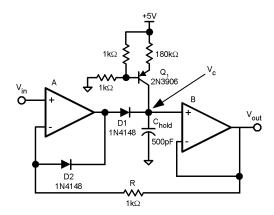


Figure 32. LMH6628's Dual Amplifiers Used to Implement a Unity-Gain Peak Detector Circuit

The acquisition speed of this circuit is limited by the dynamic resistance of the diode when charging  $C_{hold}$ . A plot of the circuit's performance is shown in Figure 33 with a 1MHz sinusoidal input.

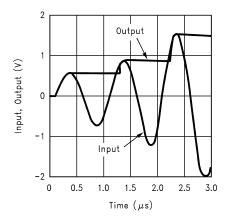


Figure 33. Circuit's Performance With a 1MHz Sinusoidal Input



A current source, built around Q1, provides the necessary bias current for the second amplifier and prevents saturation when power is applied. The resistor, R, closes the loop while diode D2 prevents negative saturation when  $V_{IN}$  is less than  $V_{C}$ . A MOS-type switch (not shown) can be used to reset the capacitor's voltage.

The maximum speed of detection is limited by the delay of the op amps and the diodes. The use of Schottky diodes will provide faster response.

#### ADJUSTABLE OR BANDPASS EQUALIZER

A "boost" equalizer can be made with the LMH6628 by summing a bandpass response with the input signal, as shown in Figure 34.

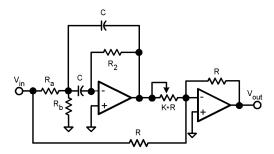


Figure 34. "Boost" Equalizer Made With the LMH6628 by Summing a Bandpass Response With the Input Signal

The overall transfer function is shown in Equation 4.

$$\frac{V_{\text{out}}}{V_{\text{in}}} = \left[\frac{R_b}{K(R_a + R_b)}\right] \frac{s2Q\omega_o}{s^2 + s\frac{\omega_o}{Q} + \omega_o^2} - 1$$
(4)

To build a boost circuit, use the design equations Equation 5 and Equation 6.

$$\frac{R_2^C}{2} = \frac{Q}{\omega_0} \tag{5}$$

$$2C (R_a || R_b) = \frac{1}{Q\omega_o}$$
(6)

Select  $R_2$  and C using Equation 5. Use reasonable values for high frequency circuits -  $R_2$  between  $10\Omega$  and  $5k\Omega$ , C between 10pF and 2000pF. Use Equation 6 to determine the parallel combination of  $R_a$  and  $R_b$ . Select  $R_a$  and  $R_b$  by either the  $10\Omega$  to  $5k\Omega$  criteria or by other requirements based on the impedance  $V_{in}$  is capable of driving. Finish the design by determining the value of K from Equation 7.

Peak Gain = 
$$\frac{V_{out}}{V_{in}} (\omega_o) = \frac{R_2}{2KR_a} - 1$$
 (7)

Figure 35 shows an example of the response of the circuit of Figure 34, where  $f_o$  is 2.3MHz. The component values are as follows:  $R_a$ =2.1k $\Omega$ ,  $R_b$  = 68.5 $\Omega$ ,  $R_2$  = 4.22k $\Omega$ , R = 500 $\Omega$ , KR = 50 $\Omega$ , C = 120pF.

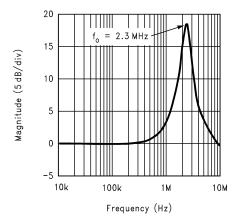


Figure 35. Example of Response of Circuit of Figure 34, Where fo is 2.3MHz



# **REVISION HISTORY**

Changes from Revision C (March 2013) to Revision D					
•	Changed layout of National Data Sheet to TI format	. 14			



# PACKAGE OPTION ADDENDUM

15-Sep-2016

#### **PACKAGING INFORMATION**

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Orderable Device	Status	Package Type	_	Pins	Package	Eco Plan	Lead/Ball Finish	MSL Peak Temp	Op Temp (°C)	Device Marking	Samples
	(1)		Drawing		Qty	(2)	(6)	(3)		(4/5)	
LMH6628MA	NRND	SOIC	D	8	95	TBD	Call TI	Call TI	-40 to 85	LMH66 28MA	
LMH6628MA/NOPB	ACTIVE	SOIC	D	8	95	Green (RoHS & no Sb/Br)	CU SN	Level-1-260C-UNLIM	-40 to 85	LMH66 28MA	Samples
LMH6628MAX/NOPB	ACTIVE	SOIC	D	8	2500	Green (RoHS & no Sb/Br)	CU SN	Level-1-260C-UNLIM	-40 to 85	LMH66 28MA	Samples

(1) The marketing status values are defined as follows:

ACTIVE: Product device recommended for new designs.

LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

NRND: Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

PREVIEW: Device has been announced but is not in production. Samples may or may not be available.

**OBSOLETE:** TI has discontinued the production of the device.

(2) Eco Plan - The planned eco-friendly classification: Pb-Free (RoHS), Pb-Free (RoHS Exempt), or Green (RoHS & no Sb/Br) - please check http://www.ti.com/productcontent for the latest availability information and additional product content details.

TBD: The Pb-Free/Green conversion plan has not been defined.

Pb-Free (RoHS): TI's terms "Lead-Free" or "Pb-Free" mean semiconductor products that are compatible with the current RoHS requirements for all 6 substances, including the requirement that lead not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, TI Pb-Free products are suitable for use in specified lead-free processes.

**Pb-Free (RoHS Exempt):** This component has a RoHS exemption for either 1) lead-based flip-chip solder bumps used between the die and package, or 2) lead-based die adhesive used between the die and leadframe. The component is otherwise considered Pb-Free (RoHS compatible) as defined above.

Green (RoHS & no Sb/Br): TI defines "Green" to mean Pb-Free (RoHS compatible), and free of Bromine (Br) and Antimony (Sb) based flame retardants (Br or Sb do not exceed 0.1% by weight in homogeneous material)

- (3) MSL, Peak Temp. The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.
- (4) There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.
- (5) Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "~" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.
- (6) Lead/Ball Finish Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead/Ball Finish values may wrap to two lines if the finish value exceeds the maximum column width.

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# **PACKAGE OPTION ADDENDUM**

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# PACKAGE MATERIALS INFORMATION

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# TAPE AND REEL INFORMATION





A0	<u> </u>
B0	Dimension designed to accommodate the component length
K0	Dimension designed to accommodate the component thickness
W	Overall width of the carrier tape
P1	Pitch between successive cavity centers

### QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE



### \*All dimensions are nominal

Device	Package Type	Package Drawing			Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
LMH6628MAX/NOPB	SOIC	D	8	2500	330.0	12.4	6.5	5.4	2.0	8.0	12.0	Q1

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#### \*All dimensions are nominal

Device	Package Type	Package Type Package Drawing		SPQ	Length (mm)	Width (mm)	Height (mm)	
LMH6628MAX/NOPB	SOIC	D	8	2500	367.0	367.0	35.0	

# D (R-PDSO-G8)

# PLASTIC SMALL OUTLINE



NOTES:

- A. All linear dimensions are in inches (millimeters).
- B. This drawing is subject to change without notice.
- Body length does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not exceed 0.006 (0,15) each side.
- Body width does not include interlead flash. Interlead flash shall not exceed 0.017 (0,43) each side.
- E. Reference JEDEC MS-012 variation AA.



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