

SN65HVD1050-EP

SLLS772A - DECEMBER 2006 - REVISED OCTOBER 2009

EMC OPTIMIZED CAN TRANSCEIVER

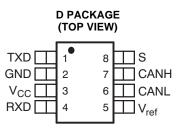
Check for Samples :SN65HVD1050-EP

FEATURES

- Controlled Baseline
 - One Assembly/Test Site, One Fabrication Site
- **Enhanced Diminishing Manufacturing Sources** • (DMS) Support
- **Enhanced Product-Change Notification**
- **Qualification Pedigree**⁽¹⁾ •
- Improved Replacement for the TJA1050
- High Electromagnetic Immunity (EMI)
- Very Low Electromagnetic Emissions (EME)
- Meets or Exceeds the Requirements of ISO 11898-2
- Bus-Fault Protection of -27 V to 40 V
- **Dominant Time-Out Function**
- **Thermal Shutdown Protection**
- Power-Up/Down Glitch-Free Bus Inputs and Outputs
 - High Input Impedance With Low V_{CC}
 - Monotonic Outputs During Power Cycling

APPLICATIONS

- **Industrial Automation**
 - DeviceNET[™] Data Buses (Vendor ID #806)
- SAE J2284 High-Speed CAN for Automotive Applications
- SAE J1939 Standard Data Bus Interface
- ISO 11783 Standard Data Bus Interface
- NMEA 2000 Standard Data Bus Interface
- Component gualification in accordance with JEDEC and (1)industry standards to ensure reliable operation over an extended temperature range. This includes, but is not limited to, Highly Accelerated Stress Test (HAST) or biased 85/85, temperature cycle, autoclave or unbiased HAST, electromigration, bond intermetallic life, and mold compound life. Such qualification testing should not be viewed as justifying use of this component beyond specified performance and environmental limits.



DESCRIPTION/ ORDERING INFORMATION

SN65HVD1050 meets The or exceeds the specifications of the ISO 11898 standard for use in applications employing a controller area network (CAN). The device is also gualified for use in automotive applications in accordance with AEC-Q100.⁽²⁾

As a CAN transceiver, this device provides differential transmit capability to the bus and differential receive capability to a CAN controller at signaling rates up to 1 megabit per second (Mbps)⁽³⁾.

Designed operation for in especially harsh environments, SN65HVD1050 the features cross-wire, overvoltage, and loss of ground protection from -27 V to 40 V, overtemperature protection, a -12-V to 12-V common-mode range, and withstands voltage transients from -200 V to 200 V, according to ISO 7637.

Pin 8 provides for two different modes of operation: high-speed or silent mode. The high-speed mode of operation is selected by connecting S (pin 8) to ground.

- The device is available with Q100 gualification as the (2)SN65HVD1050Q (Product Preview).
- The signaling rate of a line is the number of voltage (3)transitions that are made, per second, expressed in the units bps (bits per second).

ORDERING INFORMATION

| PART NUMBER | PACKAGE | MARKED AS | ORDERING NUMBER |
|--------------|---------|-----------|-------------------------|
| SN65HVD1050M | SOIC-8 | 1050EP | SN65HVD1050MDREP (reel) |



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This integrated circuit can be damaged by ESD. Texas Instruments recommends that all integrated circuits be handled with appropriate precautions. Failure to observe proper handling and installation procedures can cause damage.

ESD damage can range from subtle performance degradation to complete device failure. Precision integrated circuits may be more susceptible to damage because very small parametric changes could cause the device not to meet its published specifications.

DESCRIPTION/ORDERING INFORMATION (CONTINUED)

If a high logic level is applied to the S pin of the SN65HVD1050, the device enters a listen-only silent mode, during which the driver is switched off while the receiver remains fully functional.

In silent mode, all bus activity is passed by the receiver output to the local protocol controller. When data transmission is required, the local protocol controller reverses this low-current silent mode by placing a logic low on the S pin to resume full operation.

A dominant-time-out circuit in the SN65HVD1050 prevents the driver from blocking network communication with a hardware or software failure. The time-out circuit is triggered by a falling edge on TXD (pin 1). If no rising edge is seen before the time-out constant of the circuit expires, the driver is disabled. The circuit is then reset by the next rising edge on TXD.

 V_{ref} (pin 5) is available as a $V_{CC}/2$ voltage reference.

The SN65HVD1050M is characterized for operation from -55°C to 125°C.

⁸- s Silent Mode Vcc Vcc 3 **30 μA** 5_ V_{ref} Dominant Temperature V_{CC}/2 Time-Out Protection 30 μA 7 CANH 1 TXD Driver 6 CANL th. RXD Π

FUNCTION BLOCK DIAGRAM

Absolute Maximum Ratings⁽¹⁾

| | | UNIT |
|-----------------|---|-----------------|
| V _{CC} | Supply voltage ⁽²⁾ | –0.3 V to 7 V |
| | Voltage range at any bus terminal (CANH, CANL, V _{ref}) | –27 V to 40 V |
| I _O | Receiver output current | 20 mA |
| VI | Voltage input, transient pulse ⁽³⁾ (CANH, CANL) | –200 V to 200 V |
| VI | Voltage input range (TXD, S) | –0.5 V to 6 V |
| TJ | Junction temperature | –55°C to 170°C |

(1) Stresses beyond those listed under "absolute maximum ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under "recommended operating conditions" is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

(2) All voltage values, except differential I/O bus voltages, are with respect to network ground terminal.

(3) Tested in accordance with ISO 7637, test pulses 1, 2, 3a, 3b, 5, 6, and 7



Electrostatic Discharge Protection

over operating free-air temperature range (unless otherwise noted)

| PARAMETER | | TEST CONDITIONS | | |
|--|-------------------------------------|-----------------------|---------|--|
| | Lluman Dady Madal ⁽²⁾ | Bus terminals and GND | ±8 kV | |
| Electrostatia discharge (1) | Human-Body Model ⁽²⁾ | All pins | ±4 kV | |
| Electrostatic discharge ⁽¹⁾ | Charged-Device Model ⁽³⁾ | All pins | ±1.5 kV | |
| | Machine Model | | ±200 V | |

All typical values at 25°C (1)

Tested in accordance with JEDEC Standard 22, Test Method A114-A Tested in accordance with JEDEC Standard 22, Test Method C101 (2) (3)

Recommended Operating Conditions

| | | | MIN | MAX | UNIT | |
|--|-----------------------------------|---|--------|------|------|----|
| V _{CC} | Supply voltage | | 4.75 | 5.25 | V | |
| $V_{\text{I}} \text{ or } V_{\text{IC}}$ | Voltage at any bus terminal | /oltage at any bus terminal (separately or common mode) | | 12 | V | |
| V _{IH} | High-level input voltage | TXD, S | 2 | 5.25 | V | |
| V _{IL} | Low-level input voltage | TXD, S | 0 | 0.8 | V | |
| V _{ID} | Differential input voltage | | -6 | 6 | V | |
| | I Pale la cal a charal a come a t | Lieb level evitevit evinent | Driver | -70 | | mA |
| ЮН | High-level output current | Receiver | -2 | | ША | |
| | Low lovel output ourrest | Driver | | 70 | ~^^ | |
| IOL | Low-level output current | Receiver | | 2 | mA | |
| TJ | Junction temperature | See Thermal Characteristics table, 1-Mbps minimum signaling rate with $R_L = 54 \Omega$ | | 150 | °C | |

Supply Current

over recommended operating conditions (unless otherwise noted)

| | PARAMETER | | TEST CONDITIONS | MIN | TYP | MAX | UNIT |
|-----------------|--------------------|-------------|---|-----|-----|-----|------|
| | | Silent mode | S at V_{CC} , $V_I = V_{CC}$ | | 6 | 10 | |
| I _{CC} | 5-V supply current | Dominant | $V_I = 0 V$, 60- Ω load, S at 0 V | | 50 | 70 | mA |
| 00 | | Recessive | $V_I = V_{CC}$, No load, S at 0 V | | 6 | 10 | |

Device Switching Characteristics

over operating free-air temperature range (unless otherwise noted)

| | PARAMETER | TEST CONDITIONS | MIN | MAX | UNIT |
|-----------------------|---|------------------------|-----|-----|------|
| t _{d(LOOP1)} | Total loop delay, driver input to receiver output, recessive to dominant | | 90 | 230 | 20 |
| t _{d(LOOP2)} | Total loop delay, driver input to receiver output, dominant to recessive | S at 0 V, See Figure 9 | 90 | 230 | ns |

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INSTRUMENTS

EXAS

Driver Electrical Characteristics

over recommended operating conditions (unless otherwise noted)

| | PARAMETER | | TEST CONDITIONS | MIN | TYP (1) | MAX | UNIT |
|---|---|-------------|---|--------|-------------------|-------|------|
| M | | CANH | $V_1 = 0 V$, S at 0 V, $R_1 = 60 \Omega$, | 2.9 | 3.4 | 4.5 | V |
| V _{O(D)} | Bus output voltage (dominant) | CANL | See Figure 1 and Figure 2 | | | 1.5 | V |
| V _{O(R)} | Bus output voltage (recessive) | | $V_I = 3 V$, S at 0 V, $R_L = 60 \Omega$, See Figure 1 and Figure 2 | 2 | 2.3 | 3 | V |
| M | Differential output voltage (domi | a ant) | $V_I = 0 V$, $R_L = 60 \Omega$, S at 0 V, See Figure 1, Figure 2, and Figure 3 | 1.5 | | 3 | V |
| V _{OD(D)} Differential output voltage (dominant) | | iant) | $V_I = 0 V$, $R_L = 45 \Omega$, S at 0 V, See Figure 1, Figure 2, and Figure 3 | 1.4 | | 3 | v |
| V _{OD(R)} | | | V _I = 3 V, S at 0 V, See Figure 1 and Figure 2 | -0.012 | | 0.012 | V |
| - () | | • | $V_1 = 3 V$, S at 0 V, No load | -0.5 | | 0.05 | |
| V _{OC(ss)} | Steady-state common-mode out | put voltage | | 2 | 2.3 | 3 | V |
| $\Delta V_{OC(ss)}$ | Change in steady-state common output voltage | -mode | S at 0 V, See Figure 8 | | 30 | | mV |
| I _{IH} | High-level input current, TXD inp | out | V _I at V _{CC} | -2 | | 2 | |
| IIL | Low-level input current, TXD inp | ut | V _I at 0 V | -50 | | -10 | μA |
| I _{O(off)} | Power-off TXD output current | | V _{CC} at 0 V, TXD at 5 V | | | 1 | |
| | | | V _{CANH} = -12 V, CANL open, See Figure 11 | -105 | -72 | | |
| | Chart aircuit atopdy atota autout | ourroat | V _{CANH} = 12 V, CANL open, SeeFigure 11 | | 0.36 | 1 | ~ ^ |
| I _{OS(ss)} | Short-circuit steady-state output current | | V _{CANL} = -12 V, CANH open, See Figure 11 | -1 | -0.5 | | mA |
| | | | V _{CANL} = 12 V, CANH open, See Figure 11 | | 71 | 105 | |
| Co | Output capacitance | | See receiver input capacitance | | | | |

(1) All typical values are at 25°C, with a 5-V supply.

Driver Switching Characteristics

over recommended operating conditions (unless otherwise noted)

| | PARAMETER | TEST CONDITIONS | MIN | TYP | MAX | UNIT |
|--------------------|---|---------------------------------|-----|-----|-----|------|
| t _{PLH} | Propagation delay time, low- to high-level output | | 25 | 65 | 120 | |
| t _{PHL} | Propagation delay time, high- to low-level output | S at 0 V, See Figure 4 | 25 | 45 | 120 | ns |
| t _r | Differential output signal rise time | S at 0 V, See Figure 4 | | 25 | | |
| t _f | Differential output signal fall time | | | 50 | | ns |
| t _{en} | Enable time from silent mode to dominant | See Figure 7 | | | 1 | μs |
| t _(dom) | Dominant time-out | ↓V _I , See Figure 10 | 300 | 450 | 700 | μs |



Receiver Electrical Characteristics

over recommended operating conditions (unless otherwise noted)

| | PARAMETER | TEST CONDITIONS | MIN | TYP ⁽¹⁾ | MAX | UNIT |
|---------------------|---|--|-----|--------------------|-----|------|
| V_{IT+} | Positive-going input threshold voltage | S at 0 V, See Table 3 | | 800 | 900 | mV |
| V _{IT-} | Negative-going input threshold voltage | S at 0 V, See Table 3 | 500 | 650 | | mV |
| V _{hys} | Hysteresis voltage (V _{IT+} – V _{IT}) | | 100 | 125 | | mV |
| V _{OH} | High-level output voltage | $I_0 = -2$ mA, See Figure 6 | 4 | 4.6 | | V |
| V _{OL} | Low-level output voltage | I _O = 2 mA, See Figure 6 | | 0.2 | 0.4 | V |
| I _{I(off)} | Power-off bus input current | CANH or CANL = 5 V, Other pin at 0 V, V _{CC} at 0 V, TXD at 0 V | | 165 | 250 | μA |
| I _{O(off)} | Power-off RXD leakage current | V _{CC} at 0 V, RXD at 5 V | | | 20 | μA |
| CI | Input capacitance to ground (CANH or CANL) | TXD at 3 V, V _I = 0.4 sin (4E6πt) + 2.5 V | | 13 | | pF |
| C _{ID} | Differential input capacitance | TXD at 3 V, $V_I = 0.4 \sin (4E6\pi t)$ | | 5 | | pF |
| R _{ID} | Differential input resistance | TXD at 3 V, S at 0 V | 30 | | 80 | kΩ |
| R _{IN} | Input resistance (CANH or CANL) | TXD at 3 V, S at 0 V | 15 | 30 | 40 | kΩ |
| R _{I(m)} | Input resistance matching [1 – (R _{IN (CANH)} / R _{IN (CANL)})] ×100% | $V_{O(CANH)} = V_{O(CANL)}$ | -3% | 0% | 3% | |

(1) All typical values are at 25 C with a 5-V supply.

Receiver Switching Characteristics

over recommended operating conditions (unless otherwise noted)

| | PARAMETER | TEST CONDITIONS | MIN | TYP | MAX | UNIT |
|------------------|---|--|-----|-----|-----|------|
| t _{PLH} | Propagation delay time, low- to high-level output | | 60 | 100 | 130 | ~~ |
| t _{PHL} | Propagation delay time, high- to low-level output | S at 0 V or V _{CC} , See Figure 6 | | 70 | 130 | ns |
| t _r | Output signal rise time | S at 0 V or V _{CC} , See Figure 6 | | 8 | | 20 |
| t _f | Output signal fall time | S at 0 v or v _{CC} , see Figure 6 | | 8 | | ns |

S-Pin Characteristics

over recommended operating conditions (unless otherwise noted)

| | PARAMETER | TEST CONDITIONS | MIN | TYP | MAX | UNIT |
|-----------------|--------------------------|-----------------|-----|-----|-----|------|
| I _{IH} | High-level input current | S at 2 V | 20 | 40 | 70 | μA |
| I_{IL} | Low-level input current | S at 0.8 V | 5 | 20 | 30 | μA |

V_{ref}-PIN Characteristics

over operating free-air temperature range (unless otherwise noted)

| | PARAMETER | TEST CONDITIONS | MIN | TYP | MAX | UNIT |
|---------|--------------------------|---------------------------------|--------------|--------------|--------------|------|
| V_{O} | Reference output voltage | –50 μA < I _O < 50 μA | $0.4 V_{CC}$ | $0.5 V_{CC}$ | $0.6 V_{CC}$ | V |

Thermal Characteristics

over operating free-air temperature range (unless otherwise noted)

| | PARAMETER | TEST CONDITIONS | MIN | TYP | MAX | UNIT |
|----------------------|--------------------------------------|---|-----|-----|-----|------|
| θ _{JA} Jun | Junction to Air | Low-K thermal resistance ⁽¹⁾ | 211 | | | °C/W |
| | Junction to All | High-K thermal resistance | 131 | | C/W | |
| θ_{JB} | Junction-to-board thermal resistance | | | 53 | | °C/W |
| θ_{JC} | Junction-to-case thermal resistance | | | 79 | | °C/W |

(1) Tested in accordance with the Low-K or High-K thermal metric definitions of EIA/JESD51-3 for leaded surface-mount packages

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Thermal Characteristics (continued)

over operating free-air temperature range (unless otherwise noted)

| | PARAMETER | TEST CONDITIONS | MIN | TYP | MAX | UNIT |
|----------------|------------------------------|--|-----|-------|-----|------|
| P _D | | V_{CC} = 5 V, T_J = 27°C, R_L = 60 $\Omega,$ S at 0 V, Input to TXD a 500-kHz, 50% duty-cycle square wave, C_L at RXD = 15 pF | | 112 | | mW |
| | Average power dissipation | V_{CC} = 5.5 V, T_j = 130°C, R_L = 45 $\Omega,$ S at 0 V, Input to TXD a 500-kHz, 50% duty-cycle square wave, C_L at RXD = 15 pF | | TTIVV | | |
| | Thermal shutdown temperature | | | 190 | | °C |

FUNCTION TABLES

Table 1. DRIVER

| INF | UTS | OUTF | | |
|--------------------|------------------|---------------------|---------------------|-----------|
| TXD ⁽¹⁾ | S ⁽¹⁾ | CANH ⁽¹⁾ | CANL ⁽¹⁾ | BUS STATE |
| L | L or Open | Н | L | Dominant |
| н | Х | Z | Z | Recessive |
| Open | Х | Z | Z | Recessive |
| Х | н | Z | Z | Recessive |

(1) H = high level, L = low level, X = irrelevant, Z = high impedance

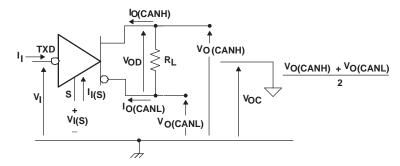
Table 2. RECEIVER

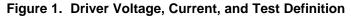
| $\begin{array}{ c c c } \hline DIFFERENTIAL INPUTS \\ V_{ID} = V_{(CANH)} - V_{(CANL)} \end{array}$ | OUTPUT RXD ⁽¹⁾ | BUS STATE |
|---|---------------------------|-----------|
| $V_{ID} \ge 0.9 V$ | L | Dominant |
| 0.5 V < V _{ID} < 0.9 V | ? | ? |
| $V_{ID} \le 0.5 V$ | н | Recessive |
| Open | Н | Recessive |

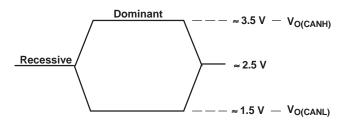
(1) H = high level, L = low level, X = irrelevant, ? = indeterminate



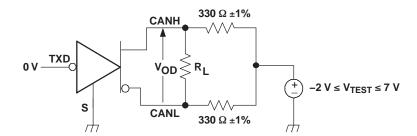
PARAMETER MEASUREMENT INFORMATION













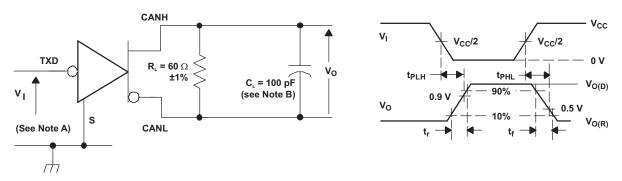


Figure 4. Driver Test Circuit and Voltage Waveforms



PARAMETER MEASUREMENT INFORMATION (continued)

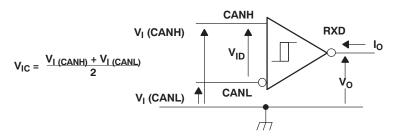
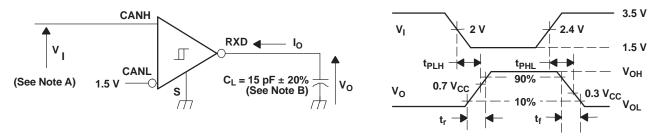


Figure 5. Receiver Voltage and Current Definitions



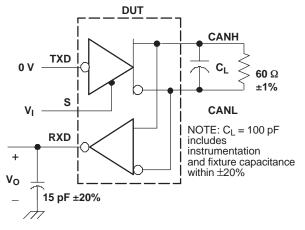
- A. The input pulse is supplied by a generator having the following characteristics: PRR \leq 125 kHz, 50% duty cycle, $t_r \leq 6$ ns, $t_f \leq 6$ ns, $Z_O = 50 \Omega$.
- B. C_L includes instrumentation and fixture capacitance within ±20%.

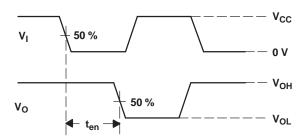
Figure 6. Receiver Test Circuit and Voltage Waveforms

| | INPUT | | | | | | | | |
|-------------------|--------|-----------------|---|-----------------|--|--|--|--|--|
| V _{CANH} | VCANL | V _{ID} | R | | | | | | |
| –11.1 V | –12 V | 900 mV | L | | | | | | |
| 12 V | 11.1 V | 900 mV | L | V | | | | | |
| -6 V | –12 V | 6 V | L | V _{OL} | | | | | |
| 12 V | 6 V | 6 V | L | | | | | | |
| –11.5 V | –12 V | 500 mV | Н | | | | | | |
| 12 V | 11.5 V | 500 mV | Н | | | | | | |
| –12 V | -6 V | 6 V | Н | V _{OH} | | | | | |
| 6 V | 12 V | 6 V | Н | 1 | | | | | |
| Open | Open | Х | Н | | | | | | |

Table 3. Differential Input Voltage Threshold Test

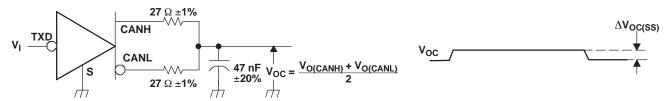




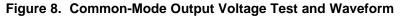


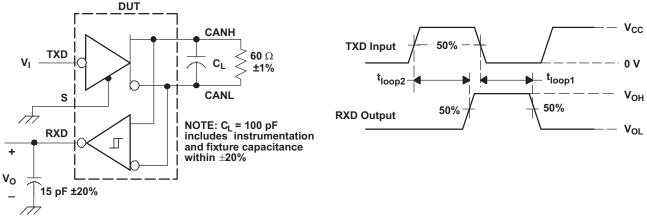
NOTE: All V_I input pulses are supplied by a generator having the following characteristics: t_r or $t_f \le 6$ ns, Pulse Repetition Rate (PRR) = 25 kHz, 50% duty cycle





NOTE: All V_I input pulses are from 0 V to V_{CC} and supplied by a generator having the following characteristics: t_r or $t_f \le 6$ ns. Pulse Repetition Rate (PRR) = 125 kHz, 50% duty cycle.

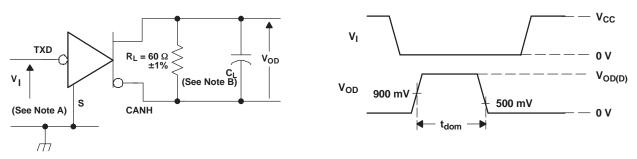




A. All V₁ input pulses are from 0 V to V_{CC} and supplied by a generator having the following characteristics: t_r or $t_f \le 6$ ns. Pulse Repetition Rate (PRR) = 125 kHz, 50% duty cycle.

Figure 9. t_(LOOP) Test Circuit and Waveform





- A. All V₁ input pulses are from 0 V to V_{CC} and supplied by a generator having the following characteristics: t_r or $t_f \le 6$ ns. Pulse Repetition Rate (PRR) = 500 Hz, 50% duty cycle.
- B. $C_L = 100 \text{ pF}$ includes instrumentation and fixture capacitance within ±20%.

Figure 10. Dominant Time-Out Test Circuit and Waveforms

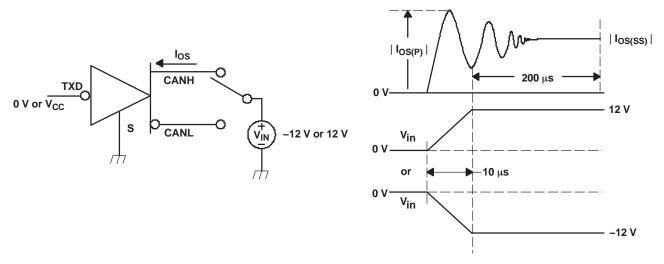


Figure 11. Driver Short-Circuit Current Test and Waveforms



DEVICE INFORMATION

| TJA1050 ⁽¹⁾ | PARAMETER | HVD1050 |
|-----------------------------|---|--|
| Transmitter S | Section | |
| V _{IH} | High-level input voltage | Recommended VIH |
| V _{IL} | Low-level input voltage | Recommended VIL |
| I _{IH} | High-level input current | Driver I _{IH} |
| IIL | Low-level input current | Driver I _{IL} |
| Bus Section | | |
| ILI | Power-off bus input current | Receiver I _{I(off)} |
| I _{O(SC)} | Short-circuit output current | Driver I _{OS(SS)} |
| V _{O(dom)} | Dominant output voltage | Driver V _{O(D)} |
| V _{i(dif)(th)} | Differential input voltage | Receiver VIT and recommended VID |
| V _{i(dif)(hys)} | Differential input hysteresis | Receiver V _{hys} |
| V _{O(reces)} | Recessive output voltage | Driver V _{O(R)} |
| V _{O(dif)(bus)} | Differential bus voltage | Driver V _{OD(D)} and V _{OD(R)} |
| R _{i(cm)} | CANH, CANL input resistance | Receiver R _{IN} |
| R _{i(dif)} | Differential input resistance | Receiver R _{ID} |
| R _{i(cm) (m)} | Input resistance matching | Receiver R _{I (m)} |
| CI | Input capacitance to ground | Receiver C _I |
| C _{i(dif)} | Differential input capacitance | Receiver C _{ID} |
| Receiver Sec | tion | · · |
| I _{OH} | High-level output current | Recommended I _{OH} |
| I _{OL} | Low-level output current | Recommended I _{OL} |
| V _{ref} -Pin Secti | on | · · |
| V _{ref} | Reference output voltage | Vo |
| Timing Section | on and a second s | · · |
| t _{d(TXD-BUSon)} | Delay TXD to bus active | Driver t _{PLH} |
| t _{d(TXD-BUSoff)} | Delay TXD to bus inactive | Driver t _{PHL} |
| t _{d(BUSon-RXD)} | Delay bus active to RXD | Receiver t _{PHL} |
| t _{d(BUSoff-RXD)} | Delay bus inactive to RXD | Receiver t _{PLH} |
| | $t_{d(TXD-BUSon)} + t_{d(BUSon-RXD)}$ | Device t _{LOOP1} |
| | $t_{d(TXD-BUSoff)} + t_{d(BUSoff-RXD)}$ | Device t _{LOOP2} |
| t _{dom(TXD)} | Dominant time-out | Driver t _(dom) |
| S-Pin Section | I | |
| V _{IH} | High-level input voltage | Recommended VIH |
| V _{IL} | Low-level input voltage | Recommended V _{IL} |
| I _{IH} | High-level input current | Ін |
| IIL | Low-level input current | IIL |

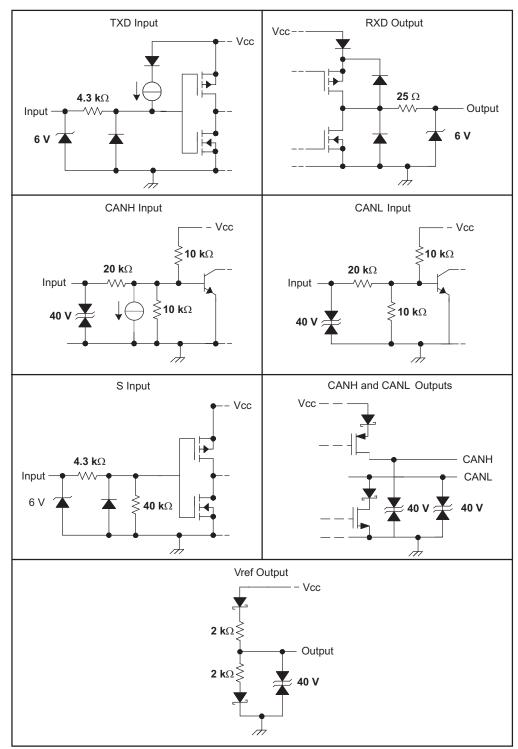
Table 4. Parametric Cross-Reference With the TJA1050

(1) From TJA1050 Product Specification, Philips Semiconductors, 2002 May 16

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Equivalent Input and Output Schematic Diagrams

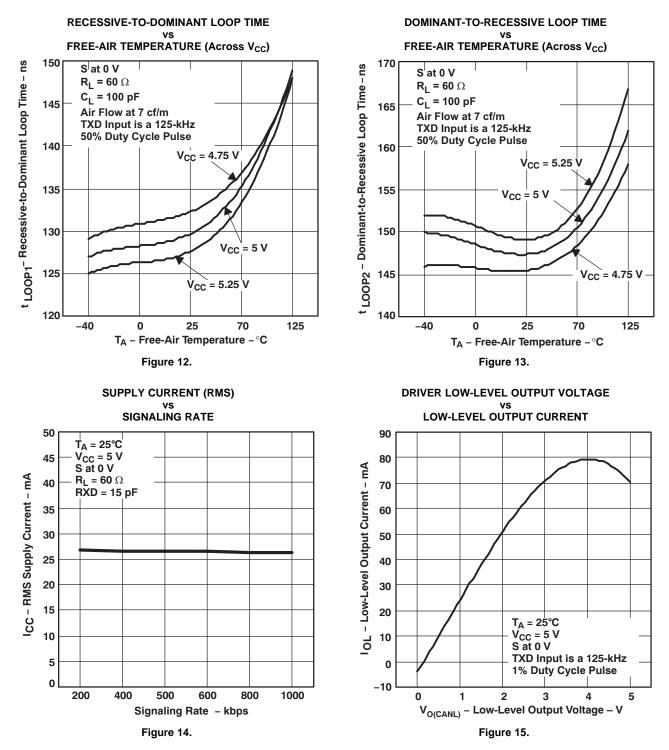




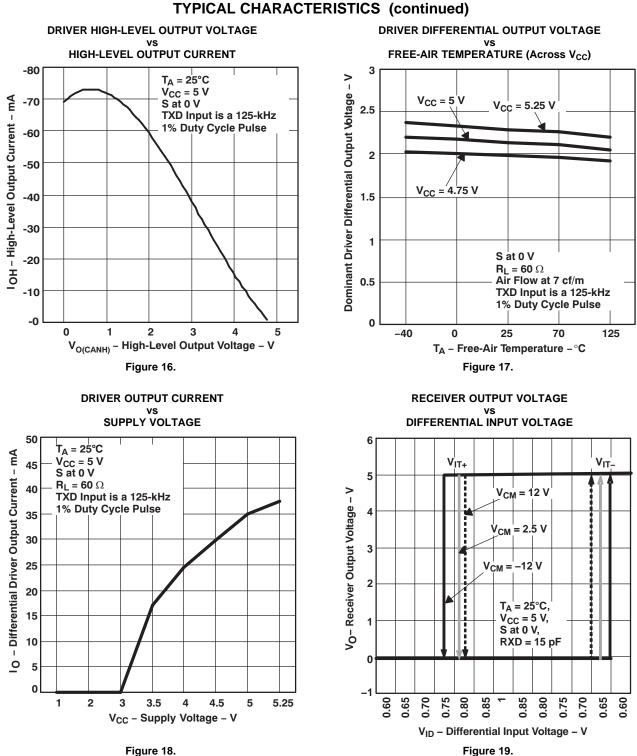
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TYPICAL CHARACTERISTICS









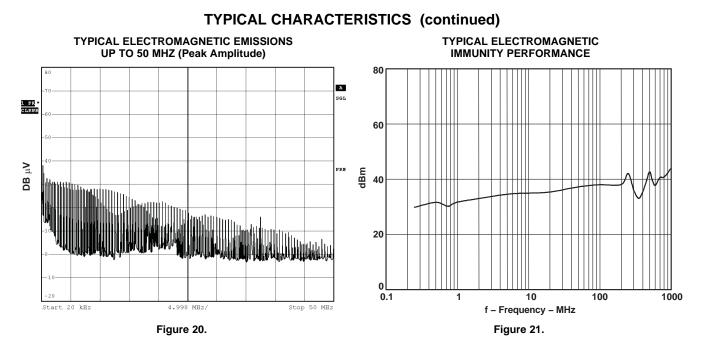
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SN65HVD1050-EP

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11-Apr-2013

PACKAGING INFORMATION

| Orderable Device | Status | Package Type | • | Pins | Package | Eco Plan | Lead/Ball Finish | MSL Peak Temp | Op Temp (°C) | Top-Side Markings | Samples |
|--------------------|--------|--------------|---------|------|---------|----------------------------|------------------|--------------------|--------------|-------------------|---------|
| | (1) | | Drawing | | Qty | (2) | | (3) | | (4) | |
| SN65HVD1050MDREP | ACTIVE | SOIC | D | 8 | 2500 | Green (RoHS & no Sb/Br) | CU NIPDAU | Level-1-260C-UNLIM | -55 to 125 | 1050EP | Samples |
| SN65HVD1050MDREPG4 | ACTIVE | SOIC | D | 8 | 2500 | Green (RoHS & no Sb/Br) | CU NIPDAU | Level-1-260C-UNLIM | -55 to 125 | 1050EP | Samples |
| V62/07608-01XE | ACTIVE | SOIC | D | 8 | 2500 | Green (RoHS & no Sb/Br) | CU NIPDAU | Level-1-260C-UNLIM | -55 to 125 | 1050EP | Samples |

⁽¹⁾ The marketing status values are defined as follows:

ACTIVE: Product device recommended for new designs.

LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

NRND: Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

PREVIEW: Device has been announced but is not in production. Samples may or may not be available.

OBSOLETE: TI has discontinued the production of the device.

⁽²⁾ Eco Plan - The planned eco-friendly classification: Pb-Free (RoHS), Pb-Free (RoHS Exempt), or Green (RoHS & no Sb/Br) - please check http://www.ti.com/productcontent for the latest availability information and additional product content details.

TBD: The Pb-Free/Green conversion plan has not been defined.

Pb-Free (RoHS): TI's terms "Lead-Free" or "Pb-Free" mean semiconductor products that are compatible with the current RoHS requirements for all 6 substances, including the requirement that lead not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, TI Pb-Free products are suitable for use in specified lead-free processes.

Pb-Free (RoHS Exempt): This component has a RoHS exemption for either 1) lead-based flip-chip solder bumps used between the die and package, or 2) lead-based die adhesive used between the die and leadframe. The component is otherwise considered Pb-Free (RoHS compatible) as defined above.

Green (RoHS & no Sb/Br): TI defines "Green" to mean Pb-Free (RoHS compatible), and free of Bromine (Br) and Antimony (Sb) based flame retardants (Br or Sb do not exceed 0.1% by weight in homogeneous material)

⁽³⁾ MSL, Peak Temp. -- The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

(4) Multiple Top-Side Markings will be inside parentheses. Only one Top-Side Marking contained in parentheses and separated by a "~" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Top-Side Marking for that device.

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PACKAGE OPTION ADDENDUM

11-Apr-2013

OTHER QUALIFIED VERSIONS OF SN65HVD1050-EP :

• Catalog: SN65HVD1050

• Automotive: SN65HVD1050-Q1

NOTE: Qualified Version Definitions:

- Catalog TI's standard catalog product
- Automotive Q100 devices qualified for high-reliability automotive applications targeting zero defects

PACKAGE MATERIALS INFORMATION

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TAPE AND REEL INFORMATION





QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE



| *All dimensions are nominal | | | | | | | | | | | | |
|-----------------------------|-----------------|--------------------|---|------|--------------------------|--------------------------|------------|------------|------------|------------|-----------|------------------|
| Device | Package Type | Package Drawing | | SPQ | Reel Diameter (mm) | Reel Width W1 (mm) | A0 (mm) | B0 (mm) | K0 (mm) | P1 (mm) | W (mm) | Pin1 Quadrant |
| SN65HVD1050MDREP | SOIC | D | 8 | 2500 | 330.0 | 12.4 | 6.4 | 5.2 | 2.1 | 8.0 | 12.0 | Q1 |

TEXAS INSTRUMENTS

www.ti.com

PACKAGE MATERIALS INFORMATION

17-Feb-2016



*All dimensions are nominal

| Device | Package Type | Package Drawing | Pins | SPQ | Length (mm) | Width (mm) | Height (mm) |
|------------------|--------------|-----------------|------|------|-------------|------------|-------------|
| SN65HVD1050MDREP | SOIC | D | 8 | 2500 | 367.0 | 367.0 | 38.0 |

D (R-PDSO-G8)

PLASTIC SMALL OUTLINE



NOTES: A. All linear dimensions are in inches (millimeters).

- B. This drawing is subject to change without notice.
- Body length does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not exceed 0.006 (0,15) each side.
- Body width does not include interlead flash. Interlead flash shall not exceed 0.017 (0,43) each side.
- E. Reference JEDEC MS-012 variation AA.





NOTES: A. All linear dimensions are in millimeters.

- B. This drawing is subject to change without notice.
- C. Publication IPC-7351 is recommended for alternate designs.
- D. Laser cutting apertures with trapezoidal walls and also rounding corners will offer better paste release. Customers should contact their board assembly site for stencil design recommendations. Refer to IPC-7525 for other stencil recommendations.
 E. Customers should contact their board fabrication site for solder mask tolerances between and around signal pads.



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