

SLES214C-DECEMBER 2007-REVISED SEPTEMBER 2010

# 4-Channel Low-Power PAL/NTSC/SECAM Video Decoder With Independent Scalers and Fast Lock

Check for Samples: TVP5154A

# 1 Introduction

- 1.1 Features
- Four Separate Video Decoder Channels With Features for Each Channel:
  - Accept NTSC (J, M, 4.43), PAL (B, D, G, H, I, M, N, Nc), and SECAM (B, D, G, K, K1, L) Video
  - Support ITU-R BT.601 Standard Sampling
  - High-Speed 9-Bit Analog-to-Digital Converter (ADC)
  - Two Composite Inputs or One S-Video Input (for Each Channel)
  - Fully Differential CMOS Analog Preprocessing Channels With Clamping and Automatic Gain Control (AGC) for Best Signal to Noise (SNR) Performance
  - Brightness, Contrast, Saturation, Hue, and Sharpness Control Through Inter-Integrated Circuit (I<sup>2</sup>C)
  - Complementary 4-Line (3-H Delay) Adaptive Comb Filters for Both Cross-Luminance and Cross-Chrominance Noise Reduction
  - Patented Architecture for Locking to Weak, Noisy, or Unstable Signals
- Four Independent Polymorphic Scalers
- Single or Concurrent Scaled and Unscaled Outputs Via Dual Clocking Data, Interleaved 54-MHz Data or Single 27-MHz Clock
- Scaled/Unscaled Image Toggle Mode Gives Variable Field Rate for Both Scaled and Unscaled Video
- Low Power Consumption: 700 mW Typical
- 128-Pin Thin Quad Flat Pack (TQFP) Package
- Single 14.31818-MHz Crystal for All Standards and All Channels

- Internal Phase-Locked Loop (PLL) for Line-Locked Clock (Separate for Each Channel) and Sampling
- Sub-Carrier Genlock Output for Synchronizing Color Sub-Carrier of External Encoder
- Standard Programmable Video Output Format
  - ITU-R BT.656, 8-Bit 4:2:2 With Embedded Syncs
  - 8-Bit 4:2:2 With Discrete Syncs
- Advanced Programmable Video Output Formats
  - 2x Over-Sampled Raw Vertical Blanking Interval (VBI) Data During Active Video
  - Sliced VBI Data During Horizontal Blanking or Active Video
- VBI Modes Supported:
  - Teletext (NABTS, WST)
  - Closed-Caption Decode With FIFO, and Extended Data Services (EDS)
  - Wide Screen Signaling (WSS), Video Program System (VPS), Copy Generation Management System (CGMS), Vertical Interval Time Code (VITC)
  - Gemstar 1×/2× Electronic Program Guide Compatible Mode
  - Custom Configuration Mode Allows User to Program the Slice Engine for Unique VBI Data Signals
- Improved Fast Lock Mode Can Be Used When Input Video Standard Is Known and Signals on Switching Channels Are Clean
- Four Possible I<sup>2</sup>C Addresses Allowing 16 Decoder Channels on a Single I<sup>2</sup>C Bus
- Available in Commercial (0°C to 70°C) and Industrial (–40°C to 85°C) Temperature Ranges

# 1.2 Description

The TVP5154A device is a 4-channel, low-power, NTSC/PAL/SECAM video decoder. Available in a space-saving 128-pin thin quad flat pack (TQFP) package, each channel of the TVP5154A decoder converts NTSC, PAL, or SECAM video signals to 8-bit ITU-R BT.656 format. Discrete syncs are also



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available. All four channels of the TVP5154A are independently controllable. The decoders share one crystal for all channels and for all supported standards. The TVP5154A can be programmed using a single inter-integrated circuit (I<sup>2</sup>C) serial interface. The decoder uses a 1.8-V supply for its analog and digital supplies, and a 3.3-V supply for its I/O. The optimized architecture of the TVP5154A decoder allows for low power consumption. The decoder consumes less than 720 mW of power in typical operation.

Each channel of the TVP5154A is an independent video decoder with a programmable polymorphic scaler. Each channel converts baseband analog video into digital YCbCr 4:2:2 component video, which can then be scaled down to any resolution to 1/256 vertical and 15-bit horizontal in 2-pixel decrements. Composite and S-video inputs are supported. Each channel includes one 9-bit analog-to-digital converter (ADC) with 2× sampling. Sampling is ITU-R BT.601 (27.0) MHz, generated from a single 14.31818-MHz crystal or oscillator input) and is line locked. The output formats can be 8-bit 4:2:2 with discrete syncs or 8-bit ITU-R BT.656 with embedded synchronization.

The TVP5154A utilizes Texas Instruments patented technology for locking to weak, noisy, or unstable signals. A real-time control (RTC) output is generated for each channel for synchronizing downstream video encoders.

Complementary 4-line adaptive comb filtering is available per channel for both the luma and chroma data paths to reduce both cross-luma and cross-chroma artifacts. A chroma trap filter also is available.

An improved fast lock mode can be used when the input video standard is known and the signals on the switching channels are clean. Note, switching from snow and/or noisy channels to good channels takes longer. In fast lock mode, video lock is achieved in three fields or less.

Video characteristics, including hue, contrast, brightness, saturation, and sharpness, may be independently programmed for each channel using the industry standard I<sup>2</sup>C serial interface. The TVP5154A generates synchronization, blanking, lock, and clock signals in addition to digital video outputs for each channel. The TVP5154A includes methods for advanced vertical blanking interval (VBI) data retrieval. The VBI data processor slices, parses, and performs error checking on teletext, closed caption, and other data in several formats.

I<sup>2</sup>C commands can be sent to one or more decoder cores simultaneously, reducing the amount of I<sup>2</sup>C activity necessary to configure each core. A register controls which decoder core receives I<sup>2</sup>C commands, and can be configured such that all four decoders receive commands at the same time.

The main blocks for each of the channels of the TVP5154A decoder include:

- Robust sync detector
- ADC with analog processor
- Y/C separation using 4-line adaptive comb filter
- Independent, concurrent scaler outputs
- Chrominance processor
- Luminance processor
- Video clock/timing processor and power-down control
- I<sup>2</sup>C interface
- VBI data processor

# 1.3 Applications

- Security/Surveillance Digital Video Recorders/Servers and PCI Products
- Automotive Infotainment Video Hub
- Large-Format Video Wall Displays
- Games Systems



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### 1.4 Related Products

- TVP5150AM1
- TVP5151
- TVP5146M2
- TVP5147M1
- TVP5158

# 1.5 Trademarks

PowerPAD is a trademark of Texas Instruments.

Macrovision is a trademark of Macrovision Corporation.

Gemstar is a trademark of Gemstar-TV Guide International.

Other trademarks are the property of their respective owners.

# **1.6 Document Conventions**

Throughout this data manual, several conventions are used to convey information. These conventions are:

- To identify a binary number or field, a lower case b follows the numbers. For example: 000b is a 3-bit binary field.
- To identify a hexadecimal number or field, a lower case h follows the numbers. For example: 8AFh is a 12-bit hexadecimal field.
- All other numbers that appear in this document that do not have either a b or h following the number are assumed to be decimal format.
- If the signal or terminal name has a bar above the name (for example, RESETB), then this indicates the logical NOT function. When asserted, this signal is a logic low, 0, or 0b.
- RSVD indicates that the referenced item is reserved.

# **1.7 Ordering Information**

T	PACKAGED DEVICES <sup>(1)</sup>	PACKAGE OPTION	
T <sub>A</sub>	128-PIN TQFP PowerPAD™	PACKAGE OF TION	
000 1- 7000	TVP5154APNP	Tray	
0°C to 70°C	TVP5154APNPR	Tape and reel	
40%C to 05%C	TVP5154AIPNP	Tray	
–40°C to 85°C	TVP5154AIPNPR	Tape and reel	

(1) For the most current package and ordering information, see the Package Option Addendum at the end of this document, or see the TI web site at <u>www.ti.com</u>.

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# 2 Device Details

# 2.1 Functional Block Diagram

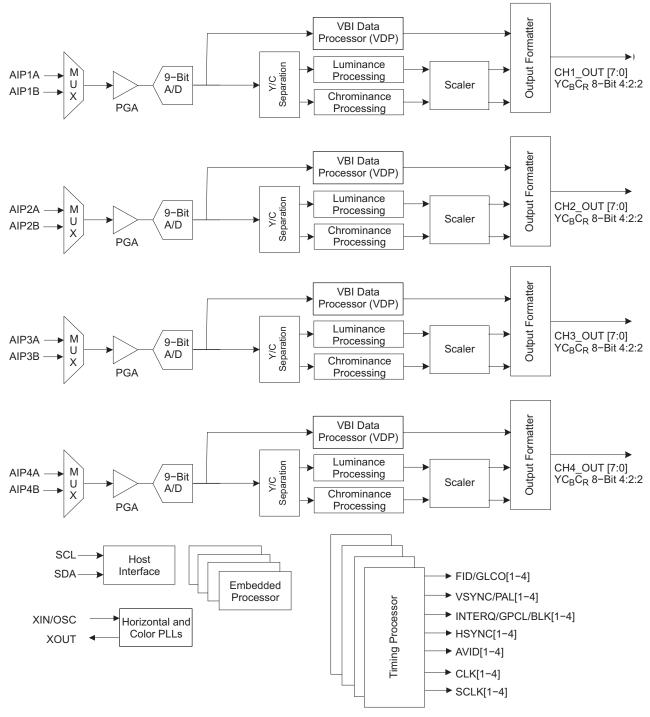
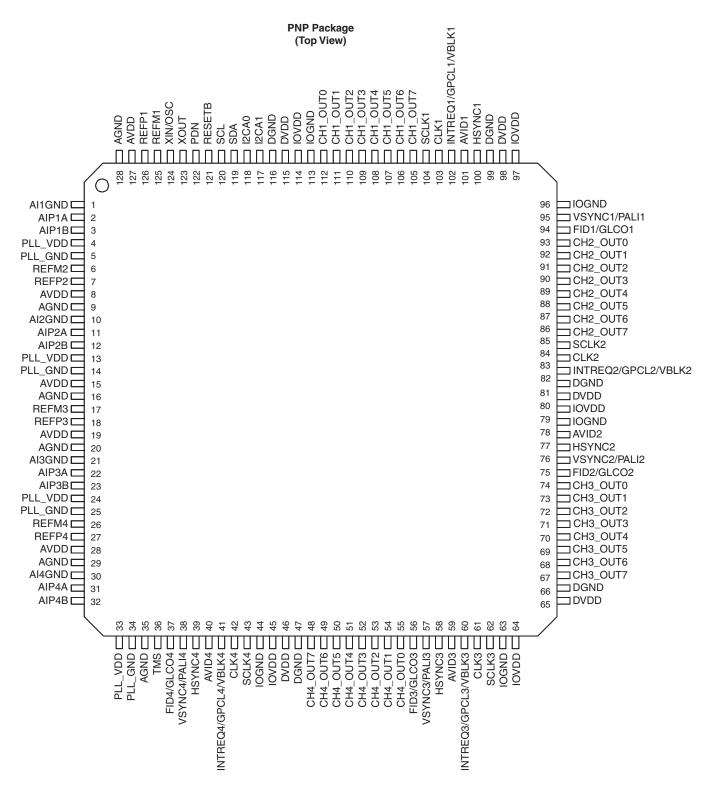


Figure 2-1. Functional Block Diagram



# 2.2 Terminal Diagram



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# 2.3 Terminal Functions

Z.3 Terminal Functions TERMINAL						
	NAME NO.		DESCRIPTION			
Analog Section	NO.	ļ				
AIP1A AIP1B	2 3	I	Analog inputs for Channel 1. Connect to the video analog input via a $0.1-\mu$ F capacitor. The maximum input range is 0–0.75 V <sub>PP</sub> , and may require an attenuator to reduce the input amplitude to the desired level. If not used, connect to AGND via a $0.1-\mu$ F capacitor. See the schematic in Section 10.			
AIP2A AIP2B	11 12	I	Analog inputs for Channel 2. Connect to the video analog input via a $0.1$ - $\mu$ F capacitor. Th maximum input range is 0-0.75 V <sub>PP</sub> , and may require an attenuator to reduce the input amplitude to the desired level. If not used, connect to AGND via a $0.1$ - $\mu$ F capacitor. See t schematic in Section 10.			
AIP3A AIP3B	22 23	I	Analog inputs for Channel 3. Connect to the video analog input via a 0.1- $\mu$ F capacitor. The maximum input range is 0-0.75 V <sub>PP</sub> , and may require an attenuator to reduce the input amplitude to the desired level. If not used, connect to AGND via a 0.1- $\mu$ F capacitor. See the schematic in Section 10.			
AIP4A AIP4B	31 32	I	Analog inputs for Channel 4. Connect to the video analog input via a 0.1- $\mu$ F capacitor. The maximum input range is 0-0.75 V <sub>PP</sub> , and may require an attenuator to reduce the input amplitude to the desired level. If not used, connect to AGND via a 0.1- $\mu$ F capacitor. See the schematic in Section 10.			
AVDD	8, 15, 19, 28, 127	Р	Analog power supply. Connect to 1.8-V analog supply.			
AGND	9, 16, 20, 29, 35, 128	G	Analog power supply return. Connect to analog ground.			
AlxGND	1, 10, 21, 30	G	Analog input signal return. Connect to analog ground.			
PLL_GND	5, 14, 25, 34	G	PLL power supply return. Connect to analog ground.			
PLL_VDD	4, 13, 24, 33	Р	PLL power supply. Connect to 1.8-V analog supply.			
REFMx	6, 17, 26, 125	I	Reference supply decoupling . Connect to analog ground through a $1-\mu F$ capacitor. Connet to REFPx through a $1-\mu F$ capacitor.			
REFPx	7, 18, 27, 126	I	Reference supply decoupling . Connect to analog ground through a $1-\mu$ F capacitor. Connect to REFMx through a $1-\mu$ F capacitor.			
Digital Section		1				
DGND	47, 66, 82, 99, 116	G	Digital power supply return. Connect to digital ground			
DVDD	46, 65, 81, 98, 115	Р	Digital power supply. Connect to 1.8-V digital supply.			
IOGND	44, 63, 79, 96, 113	G	I/O power supply return. Connect to digital ground.			
IOVDD	45, 64, 80, 97, 114	Р	I/O power supply. Connect to 3.3-V digital supply			
FID1/GLCO1 FID2/GLCO2 FID3/GLCO3 FID4/GLCO4	94 75 56 37	0	<ol> <li>FID: Odd/even field indicator or vertical lock indicator. For the odd/even indicator, a 1 indicates the odd field.</li> <li>GLCO: This serial output carries color PLL information. A slave device can decode the information to allow chroma frequency control from the TVP5154A decoder. Data is transmitted at the CLK rate in Genlock mode.</li> </ol>			
AVID1 AVID2 AVID3 AVID4	101 78 59 40	0	Active video indicator. This signal is high during the horizontal active time of the video output.			
INTREQ1/GPCL1/VBLK1 INTREQ2/GPCL2/VBLK2 INTREQ3/GPCL3/VBLK3 INTREQ4/GPCL4/VBLK4	102 83 60 41	I/O	<ol> <li>Interrupt request : Open drain when active low.</li> <li>GPCL: General-purpose output. In this mode, the state of GPCL is directly programmed via I<sup>2</sup>C.</li> <li>VBLK: Vertical blank output. In this mode, the GPCL terminal is used to indicate the VBI of the output video. The beginning and end times of this signal are programmable via I<sup>2</sup>C.</li> </ol>			



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TERMINAL				
NAME	NO.	I/O	DESCRIPTION	
HSYNC1 HSYNC2 HSYNC3 HSYNC4	100 77 58 39	0	Horizontal synchronization	
VSYNC1/PALI1 VSYNC2/PALI2 VSYNC3/PALI3 VSYNC4/PALI4	95 76 57 38	0	<ol> <li>VSYNC: Vertical synchronization</li> <li>PALI: PAL line indicator or horizontal lock indicator. For the PAL line indicator, a 1 indicates a noninverted line, and a 0 indicates an inverted line.</li> </ol>	
PDN	122	I	Power down (active low). A 0 on this pin puts the decoder in standby mode. PDN preserves the value of the registers.	
RESETB	121	I	Active-low reset. RESETB can be used only when PDN = 1. When RESETB is pulled low, it resets all the registers and restarts the internal microprocessor.	
SCL	120	I/O	l <sup>2</sup> C serial clock (open drain)	
SDA	119	I/O	l <sup>2</sup> C serial data (open drain)	
I2CA0	118	I	During power-on reset, this pin is sampled along with pin 117 (I2CA1) to determine the $I^2C$ address the device is configured to. A 10-k $\Omega$ resistor should pull this either high (to IOVDD) or low to select different $I^2C$ device addresses.	
I2CA1	117	I	During power-on reset, this pin is sampled along with pin 118 (I2CA0) to determine the I <sup>2</sup> C address the device is configured to. A 10-k $\Omega$ resistor should pull this either high (to IOVDD or low to select different I <sup>2</sup> C device addresses.	
CLK1 CLK2 CLK3 CLK4	103 84 61 42	0	Unscaled system data clock at either 27 MHz or 54 MHz	
SCLK1 SCLK2 SCLK3 SCLK4	104 85 62 43	0	Scaled system data clock at 27 MHz. This signal can be used to qualify scaled/unscaled data when the unscaled system data clock is set to 54 MHz.	
XIN/OSC XOUT	124 123	I O	External clock reference. The user may connect XIN to an oscillator or to one terminal of a crystal oscillator. The user may connect XOUT to the other terminal of the crystal oscillator or not connect XOUT at all. One single 14.31818-MHz crystal or oscillator is needed for ITU-R BT.601 sampling, for all supported standards.	
CH1_OUT[7:0]	105–112	0	Decoded ITU-R BT.656 output/YCbCr 4:2:2 output with discrete sync for channel 1	
CH2_OUT[7:0]	86–93	0	Decoded ITU-R BT.656 output/YCbCr 4:2:2 output with discrete sync for channel 2	
CH3_OUT[7:0]	67–74	0	Decoded ITU-R BT.656 output/YCbCr 4:2:2 output with discrete sync for channel 3	
CH4_OUT[7:0]	48–55	0	Decoded ITU-R BT.656 output/YCbCr 4:2:2 output with discrete sync for channel 4	
TMS	36	I	Test-mode select. This pin should be connected to digital ground for correct device operation.	



# **3** Functional Description

# 3.1 Analog Front End

Each channel of the TVP5154A decoder has an analog input channel that accepts two video inputs, which should be ac coupled through 0.1- $\mu$ F capacitors. The decoder supports a maximum input voltage range of 0.75 V; therefore, an attenuation of one-half is needed for standard input signals with a peak-to-peak variation of 1.5 V. The maximum parallel termination before the input to the device is 75  $\Omega$ . See the schematic in Section 10 for recommended configuration. The two analog input ports can be connected as follows:

- Two selectable composite video inputs or
- One S-video input

An internal clamping circuit restores the ac-coupled video signal to a fixed dc level.

The programmable gain amplifier (PGA) and the automatic gain control (AGC) circuit work together to ensure that the input signal is amplified or attenuated correctly, ensuring the proper input range for the ADC.

When switching CVBS inputs from one input to the other, the AGC settings are internally stored and the previous settings for the new input are restored. This eliminates flashes and dark frames associated with switching between inputs that have different signal amplitudes.

The ADC has nine bits of resolution and runs at a maximum speed of 27 MHz. The clock input for the ADC comes from the PLL.

# 3.2 Composite Processing Block Diagram

The composite processing block processes NTSC/PAL/SECAM signals into the YCbCr color space. Figure 2-1 shows the basic architecture of this processing block.

Figure 2-1 shows the luminance/chrominance (Y/C) separation process in the TVP5154A decoders. The composite video is multiplied by sub-carrier signals in the quadrature modulator to generate the color difference signals Cb and Cr. Cb and Cr are then low pass (LP) filtered to achieve the desired bandwidth and to reduce crosstalk.

An adaptive 4-line comb filter separates CbCr from Y. Chroma is remodulated through another quadrature modulator and subtracted from the line-delayed composite video to generate luma. Contrast, brightness, hue, saturation, and sharpness (using the peaking filter) are programmable via I<sup>2</sup>C.

The Y/C separation is bypassed for S-video input. For S-video, the remodulation path is disabled.

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# 3.3 Adaptive Comb Filtering

The 4-line comb filter can be selectively bypassed in the luma or chroma path. If the comb filter is bypassed in the luma path, then chroma trap filters are used which are shown in Figure 3-1 and Figure 3-2. TI's patented adaptive 4-line comb filter algorithm reduces artifacts, such as hanging dots at color boundaries, and detects and properly handles false colors in high-frequency luminance images, such as a multiburst pattern or circle pattern.

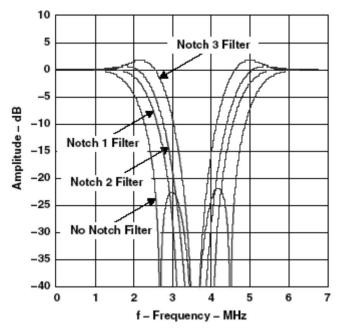


Figure 3-1. Chroma Trap Filter Frequency Response, NTSC ITU-R BT.601 Sampling

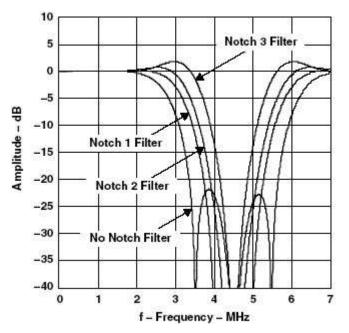


Figure 3-2. Chroma Trap Filter Frequency Response, PAL ITU-R BT.601 Sampling



### 3.4 Color Low-Pass Filter

In some applications, it is desirable to limit the Cb/Cr bandwidth to avoid crosstalk. This is especially true in the case of video signals that have asymmetrical Cb/Cr sidebands. The provided color LP filters limit the bandwidth of the Cb/Cr signals. Color LP filters are needed when the comb filtering turns off, due to extreme color transitions in the input image. See Chrominance Control #2 Register (Section 7.2.27), for the response of these filters. The filters have three options that allow three different frequency responses based on the color frequency characteristics of the input video as shown in Figure 3-3.

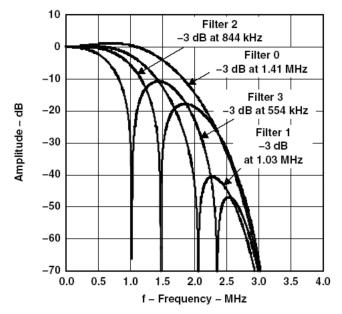


Figure 3-3. Color Low-Pass Filter with Filter Characteristics, NTSC/PAL ITU-R BT.601 Sampling

# 3.5 Luminance Processing

The luma component is derived from the composite signal by subtracting the remodulated chroma information. A line delay exists in this path to compensate for the line delay in the adaptive comb filter in the color processing chain. The luma information is then fed into the peaking circuit, which enhances the high-frequency components of the signal, thus, improving sharpness.

# 3.6 Chrominance Processing

For NTSC/PAL formats, the color processing begins with a quadrature demodulator. The Cb/Cr signals then pass through the gain control stage for chroma saturation adjustment. An adaptive comb filter is applied to the demodulated signals to separate chrominance and eliminate cross-chrominance artifacts. An automatic color-killer circuit is also included in this block. The color killer suppresses the chrominance processing when the burst amplitude falls below a programmable threshold (see I<sup>2</sup>C subaddress 06h, Section 7.2.7). The SECAM standard is similar to PAL except for the modulation of color, which is FM instead of QAM.

# 3.7 Timing Processor

The timing processor is a combination of hardware and software running in the internal microprocessor that serves to control horizontal lock to the input sync pulse edge, AGC and offset adjustment in the analog front end, and vertical sync detection.

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# 3.8 VBI Data Processor

The TVP5154A VBI data processor (VDP) slices various data services, such as teletext (WST, NABTS), closed caption (CC), wide screen signaling (WSS), etc. These services are acquired by programming the VDP to enable standards in the VBI. The results are stored in a FIFO and/or registers. The teletext results are stored in a FIFO only. Table 3-1 lists a summary of the types of VBI data supported according to the video standard. It supports ITU-R BT.601 sampling for each.

LINE MODE REGISTER (D0h-FCh) BITS [3:0]	NAME	DESCRIPTION			
0000b	WST SECAM	Teletext, SECAM			
0001b	WST PAL B	Teletext, PAL, System B			
0010b	WST PAL C	Teletext, PAL, System C			
0011b	WST, NTSC B	Teletext, NTSC, System B			
0100b	NABTS, NTSC C	Teletext, NTSC, System C			
0101b	NABTS, NTSC D	Teletext, NTSC, System D (Japan)			
0110b	CC, PAL	Closed caption PAL			
0111b	CC, NTSC	Closed caption NTSC			
1000b	WSS/CGMS-A, PAL	Wide-screen signaling/Copy Generation Management System-Analog, PAL			
1001b	WSS/CGMS-A, NTSC	Wide-screen signaling/Copy Generation Management System-Analog, NTSC			
1010b	VITC, PAL	Vertical interval timecode, PAL			
1011b	VITC, NTSC	Vertical interval timecode, NTSC			
1100b	VPS, PAL	Video program system, PAL			
1101b	Gemstar 2x Custom 1	Electronic program guide			
1110b	Reserved	Reserved			
1111b	Active Video	Active video/full field			

#### Table 3-1. Data Types Supported by the VDP

At power up, the host interface is required to program the VDP-configuration RAM (VDP-CRAM) contents with the lookup table (see Section 7.2.69). This is done through port address C3h. Each read from or write to this address auto increments an internal counter to the next RAM location. To access the VDP-CRAM, the line mode registers (D0h–FCh) must be programmed with FFh to avoid a conflict with the internal microprocessor and the VDP in both writing and reading. Full field mode must also be disabled.

Available VBI lines are from line 6 to line 27 of both field 1 and field 2. Each line can be any VBI mode.

Output data is available either through the VBI-FIFO (B0h) or through dedicated registers at 90h–AFh, both of which are available through the I<sup>2</sup>C port.



# 3.9 VBI FIFO and Ancillary Data in Video Stream

Sliced VBI data can be output as ancillary data in the video stream in the ITU-R BT.656 mode. VBI data is output during the horizontal blanking period following the line from which the data was retrieved. Table 3-2 shows the header format and sequence of the ancillary data inserted into the video stream. This format is also used to store any VBI data into the FIFO. The size of FIFO is 512 bytes. Therefore, the FIFO can store up to 11 lines of teletext data with the NTSC NABTS standard.

BYTE NO.	D7 (MSB)	D6	D5	D4	D3	D2	D1	D0 (LSB)	DESCRIPTION		
0	0	0	0	0	0	0	0	0	Ancillary data preamble		
1	1	1	1	1	1	1	1	1			
2	1	1	1	1	1	1	1	1			
3	NEP	EP	0	1	0	DID2	DID1	DID0	Data ID (DID	)	
4	NEP	EP	F5	F4	F3	F2	F1	F0	Secondary da	ata ID (SDID)	
5	NEP	EP	N5	N4	N3	N2	N1	N0	Number of 32	2 bit data (NN)	
6	Video line # [7:0] Internal data ID0 (IDID0)							ID0 (IDID0)			
7	0	0	0	Data error	Match #1	Match #2	Video lir	ne # [9:8]	Internal data ID1 (IDID1)		
8				1. [	Data				Data byte	1st word	
9				2. [	Data				Data byte		
10				3. E	Data				Data byte		
11				4. E	Data				Data byte		
÷					:				Ξ		
				—1.	Data				Data byte	Nth word	
		m. Data Data byte									
	NEP	EP			CS	[5:0]			Check sum		
4(N+2)-1	0	0	0	0	0	0	0	0	Fill byte		
EP	: Eve	en parity for	D0D5								

EP:	Even parity for D0–D5
NEP:	Negated even parity
DID:	91h: Sliced data of VBI lines of first field
	53h: Sliced data of line 24 to end of first field
	55h: Sliced data of VBI lines of second field
	97h: Sliced data of line 24 to end of second field
SDID:	This field holds the data format taken from the line mode register of the corresponding line.
NN:	Number of Dwords beginning with byte 8 through 4(N+2). This value is the number of Dwords where each Dword is 4 bytes.
IDID0:	Transaction video line number [7:0]
IDID1:	Bit 0/1 = Transaction video line number [9:8]
	Bit 2 = Match 2 flag
	Bit 3 = Match 1 flag
	Bit 4 = 1 if an error was detected in the EDC block. 0 if not.
CS:	Sum of D0–D7 of DID through last data byte
Fill byte:	Fill bytes make a multiple of four bytes from byte 0 to last fill byte. For teletext modes, byte 8 is the sync pattern byte. Byte 9 is 1. Data (the first data byte).



# 3.10 Raw Video Data Output

The TVP5154A decoder can output raw A/D video data at 2x sampling rate for external VBI slicing. This is transmitted as an ancillary data block during the active horizontal portion of the line and during vertical blanking.

# 3.11 Output Formatter

The output formatter is responsible for generating the output digital video stream. The YCbCr digital output can be programmed as 8-bit 4:2:2 or 8-bit ITU-R BT.656 parallel interface standard. Depending on which output mode is selected, the output for each channel can be unscaled data, scaled data, or both scaled and unscaled data interleaved in various ways.

STANDARDS (ITU-R BT.601)	PIXELS PER LINE	ACTIVE PIXELS PER LINE	LINES PER FRAME	PIXEL FREQUENCY (MHz)	COLOR SUB-CARRIER FREQUENCY (MHz)	HORIZONTAL LINE RATE (kHz)
NTSC-J, M	858	720	525	13.5	3.579545	15.73426
NTSC-4.43	858	720	525	13.5	4.43361875	15.73426
PAL-M	858	720	525	13.5	3.57561149	15.73426
PAL-B, D, G, H, I	864	720	625	13.5	4.43361875	15.625
PAL-N	864	720	625	13.5	4.43361875	15.625
PAL-Nc	864	720	625	13.5	3.58205625	15.625
SECAM	864	720	625	13.5	4.40625/4.25	15.625

Table 3-3. Summary of Line Frequencies, Data Rates and Pixel Counts for Different Standards

# 3.12 Synchronization Signals

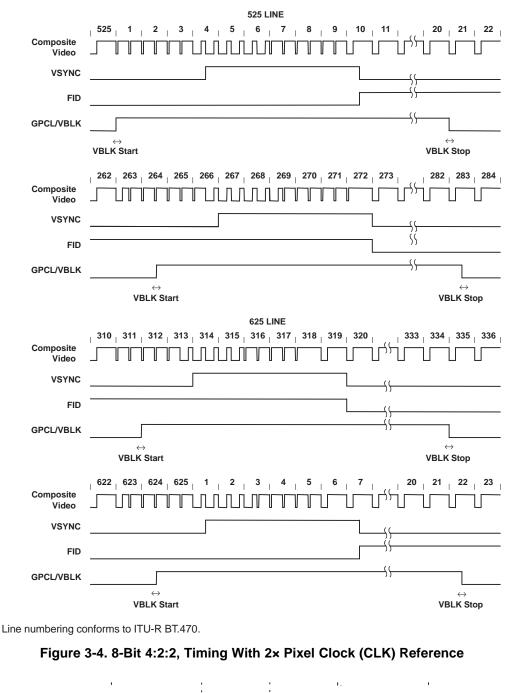
External (discrete) syncs are provided via the following signals:

- VSYNC (vertical sync)
- FID/VLK (field indicator or vertical lock indicator)
- GPCL/VBLK (general-purpose I/O or vertical blanking indicator)
- PALI/HLK (PAL switch indicator or horizontal lock indicator)
- HSYNC (horizontal sync)
- AVID (active video indicator)

VSYNC, FID, PALI, and VBLK are software set and programmable to the CLK pixel count. This allows any possible alignment to the internal pixel count and line count. The default settings for a 525-/625-line video output are shown in Figure 3-4.

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NOTE: AVID rising edge occurs four CLK cycles early when in ITU-R BT.656 output mode.

Figure 3-5. Horizontal Synchronization Signals

# 3.13 Active Video (AVID) Cropping

AVID cropping provides a means to decrease the amount of video data output. This is accomplished by horizontally blanking a number of AVID pulses and by vertically blanking a number of lines per frame. The horizontal AVID cropping is controlled using registers 11h and 12h for start pixels MSB and LSB, respectively.



Registers 13h and 14h provide access to stop pixels MSB and LSB, respectively. The vertical AVID cropping is controlled using the vertical blanking (VBLK) start and stop registers at addresses 18h and 19h. Figure 3-6 shows an AVID application.

AVID cropping can be independently controlled for scaled (registers 25h, 26h, 29h, and 2Ah) and unscaled (registers 11h thru 14h) data streams. AVID start and stop must be changed in multiples of two pixels to ensure correct UV alignment.

Additionally, AVID start and stop can be configured to include the SAV- and EAV-embedded sync signals or to exclude them, and to either include or exclude ITU656 ancillary data.

#### NOTE

The above settings alter AVID output timing, but the video output data is not forced to black level outside of the AVID interval.

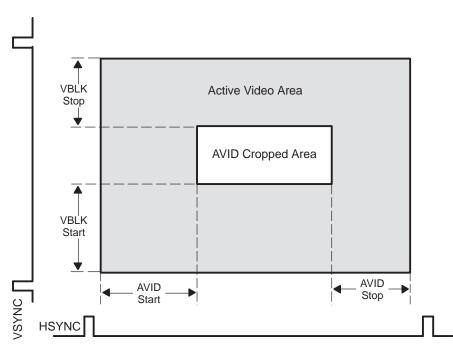


Figure 3-6. AVID Application



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# 3.14 Embedded Syncs

Standards with embedded syncs insert SAV and EAV codes into the data stream at the beginning and end of horizontal blanking. These codes contain the V and F bits that also define vertical timing. F and V change on EAV. Table 3-4 gives the format of the SAV and EAV codes.

H equals 1 always indicates EAV. H equals 0 always indicates SAV. The alignment of V and F to the line and field counter varies depending on the standard. See ITU-R BT.656 for more information on embedded syncs.

The P bits are protection bits:

P3 = V x or H P2 = F x or H P1 = F x or V P0 = F x orV x or H

		8-BIT DATA							
	D7 (MSB)	D6	D5	D4	D3	D2	D1	D0	
Preamble	1	1	1	1	1	1	1	1	
Preamble	0	0	0	0	0	0	0	0	
Preamble	0	0	0	0	0	0	0	0	
Status word	1	F	V	н	P3	P2	P1	P0	

#### Table 3-4. EAV and SAV Sequence

The status word may be modified to pass information about whether the current data corresponds to scaled or unscaled data. See register 1Fh for more information.

# 3.15 Clock and Data Control

Figure 3-7 shows a logical schematic of the data and clock control signals.

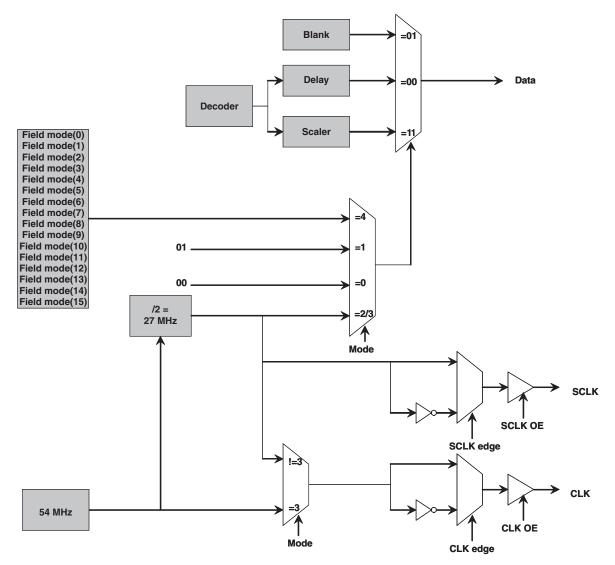


Figure 3-7. Clock and Data Control



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# 4 I<sup>2</sup>C Host Interface

The I<sup>2</sup>C standard consists of two signals, serial input/output data line (SDA) and input/output clock line (SCL), which carry information between the devices connected to the bus. The input pins I2CA0 and I2CA1 are used to select the slave address to which the device responds. Although the I<sup>2</sup>C system can be multimastered, the TVP5154A decoder functions as a slave device only.

Both SDA and SCL must be connected to IOVDD via pullup resistors. When the bus is free, both lines are high. The slave address select terminals (I2CA0 and I2CA1) enable the use of four TVP5154A decoders on the same  $I^2C$  bus. At the trailing edge of reset, the status of the I2CA0 and I2CA1 lines are sampled to determine the device address used. Table 4-1 summarizes the terminal functions of the  $I^2C$ -mode host interface. Table 4-2 shows the device address selection options.

SIGNAL	TYPE	DESCRIPTION
I2CA0	I	Slave address selection
I2CA1	Ι	Slave address selection
SCL	I/O (open drain)	Input/output clock line
SDA	I/O (open drain)	Input/output data line

# Table 4-1. I<sup>2</sup>C Terminal Description

### Table 4-2. I<sup>2</sup>C Host Interface Device Addresses

A6	A5	A4	A3	A2	A1 (I2CA1)	A0 (I2CA0)	R/W	HEX
1	0	1	1	1	0	0	1/0	B9/B8
1	0	1	1	1	0	1	1/0	BB/BA
1	0	1	1	1	1	0	1/0	BD/BC
1	0	1	1	1	1	1	1/0	BF/BE

Data transfer rate on the bus is up to 400 kbit/s. The number of interfaces connected to the bus is dependent on the bus capacitance limit of 400 pF. The data on the SDA line must be stable during the high period of the SCL, except for start and stop conditions. The high or low state of the data line can only change with the clock signal on the SCL line being low. A high-to-low transition on the SDA line while the SCL is high indicates an  $I^2C$  start condition. A low-to-high transition on the SDA line while the SCL is high indicates an  $I^2C$  stop condition.

Every byte placed on the SDA must be eight bits long. The number of bytes that can be transferred is unrestricted. Each byte must be followed by an acknowledge bit. The acknowledge-related clock pulse is generated by the I<sup>2</sup>C master.

To simplify programming of each of the four decoder channels, a single  $I^2C$  write transaction can be transmitted to any one or more of the four cores in parallel. This reduces the time required to download firmware or to configure the device when all channels are to be configured in the same manner. It also enables the addresses for all registers to be common across all decoders.

 $I^2C$  sub-address 0xFE contains four bits, with each bit corresponding to one of the decoder cores. If this bit is set,  $I^2C$  write transactions are sent to the corresponding decoder core. If the bit is 0, the corresponding decoder does not receive the  $I^2C$  write transactions.

I<sup>2</sup>C sub-address 0xFF contains four bits, with each bit corresponding to one of the decoder cores. If this bit is set, I<sup>2</sup>C read transactions are sent to the corresponding decoder core. Note, only one of the bits in this register should be set at a given time, ensuring that only one decoder core is accessed at a time for read operations. If more than one bit is set, the lowest set bit number corresponds to the core that responds to the read transaction.

Note that, when register 0xFE is written to with any value, register 0xFF is set to 0x00. Likewise, when register 0xFF is written to with any value, register 0xFE is set to 0x00.

# 4.1 I<sup>2</sup>C Write Operation

Data transfers occur utilizing the following illustrated formats.

An I<sup>2</sup>C master initiates a write operation to the TVP5154A decoder by generating a start condition (S) followed by the TVP5154A I<sup>2</sup>C address (as shown below), in MSB first bit order, followed by a 0 to indicate a write cycle. After receiving an acknowledge from the TVP5154A decoder, the master presents the sub-address of the register, or the first of a block of registers it wants to write, followed by one or more bytes of data, MSB first. The TVP5154A decoder acknowledges each byte after completion of each transfer. The I<sup>2</sup>C master terminates the write operation by generating a stop condition (P).

Step 1	0							
I <sup>2</sup> C start (master)	S							
Step 2	7	6	5	4	3	2	1	0
I <sup>2</sup> C general address (master)	1	0	1	1	1	0	Х	0
Step 3	9	[						
I <sup>2</sup> C acknowledge (slave)	А							
Step 4	7	6	5	4	3	2	1	0
I <sup>2</sup> C write register address (master)	addr							
Step 5	9	[						
I <sup>2</sup> C acknowledge (slave)	А							
Step 6	7	6	5	4	3	2	1	0
I <sup>2</sup> C write data (master)	Data							
Step 7 <sup>(1)</sup>	9							
I <sup>2</sup> C acknowledge (slave)	А							
Step 8	0							
I <sup>2</sup> C stop (master)	Р							

(1) Repeat steps 6 and 7 until all data have been written.

# 4.2 I<sup>2</sup>C Read Operation

The read operation consists of two phases. The first phase is the address phase. In this phase, an I<sup>2</sup>C master initiates a write operation to the TVP5154A decoder by generating a start condition (S) followed by the TVP5154A I<sup>2</sup>C address, in MSB first bit order, followed by a 0 to indicate a write cycle. After receiving acknowledges from the TVP5154A decoder, the master presents the sub-address of the register or the first of a block of registers it wants to read. After the cycle is acknowledged, the master terminates the cycle immediately by generating a stop condition (P).

The second phase is the data phase. In this phase, an  $I^2C$  master initiates a read operation to the TVP5154A decoder by generating a start condition followed by the TVP5154A  $I^2C$  address (as shown below for a read operation), in MSB first bit order, followed by a 1 to indicate a read cycle. After an acknowledge from the TVP5154A decoder, the  $I^2C$  master receives one or more bytes of data from the TVP5154A decoder. The  $I^2C$  master acknowledges the transfer at the end of each byte. After the last data byte desired has been transferred from the TVP5154A decoder to the master, the master generates a not acknowledge followed by a stop.

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### Read Phase 1

Step 1	0							
I <sup>2</sup> C start (master)	S							
Step 2	7	6	5	4	3	2	1	0
I <sup>2</sup> C general address (master)	1	0	1	1	1	0	Х	0
Step 3	9							
I <sup>2</sup> C acknowledge (slave)	А							
Step 4	7	6	5	4	3	2	1	0
I <sup>2</sup> C read register address (master)	addr	addr	addr	addr	addr	addr	addr	addr
Step 5	9							
I <sup>2</sup> C acknowledge (slave)	А							
Step 6	0							
I <sup>2</sup> C stop (master)	Р							
Read Phase 2								
Step 7	<b>0</b> S							
Step 7 I <sup>2</sup> C start (master)		6	5	4	3	2	1	0
Step 7 I <sup>2</sup> C start (master) Step 8	S	<b>6</b> 0	<b>5</b> 1	<b>4</b> 1	<b>3</b> 1	<b>2</b> 0	1 X	<b>0</b> 1
Step 7         I <sup>2</sup> C start (master)         Step 8         I <sup>2</sup> C general address (master)	S 7	-						-
Step 7         I <sup>2</sup> C start (master)         Step 8         I <sup>2</sup> C general address (master)         Step 9	S           7           1	-						-
Step 7       I <sup>2</sup> C start (master)       Step 8       I <sup>2</sup> C general address (master)       Step 9       I <sup>2</sup> C acknowledge (slave)       Step 10	S 7 1 9	-						-
Step 7         I <sup>2</sup> C start (master)         Step 8         I <sup>2</sup> C general address (master)         Step 9         I <sup>2</sup> C acknowledge (slave)	S 7 1 9 A	0	1	1	1	0	X	1
Step 7         I <sup>2</sup> C start (master)         Step 8         I <sup>2</sup> C general address (master)         Step 9         I <sup>2</sup> C acknowledge (slave)         Step 10         I <sup>2</sup> C read data (slave)	S           7           1           9           A           7	0 6	5	1 4	1 3	0 2	X 1	0
Step 7         I <sup>2</sup> C start (master)         Step 8         I <sup>2</sup> C general address (master)         Step 9         I <sup>2</sup> C acknowledge (slave)         Step 10         I <sup>2</sup> C read data (slave)         Step 11 <sup>(1)</sup>	S           7           1           9           A           7           Data	0 6	5	1 4	1 3	0 2	X 1	0
Step 7         I <sup>2</sup> C start (master)         Step 8         I <sup>2</sup> C general address (master)         Step 9         I <sup>2</sup> C acknowledge (slave)         Step 10	S 7 1 9 A 7 Data 9	0 6	5	1 4	1 3	0 2	X 1	0

(1) Repeat steps 10 and 11 for all bytes read. Master does not acknowledge the last read data received.

# 4.2.1 PC Timing Requirements

The TVP5154A decoder requires delays in the I<sup>2</sup>C accesses to accommodate its internal processor's timing. In accordance with I<sup>2</sup>C specifications, the TVP5154A decoder holds the I<sup>2</sup>C clock line (SCL) low to indicate the wait period to the I<sup>2</sup>C master. If the I<sup>2</sup>C master is not designed to check for the I<sup>2</sup>C clock line held-low condition, the maximum delays must always be inserted where required. These delays are of variable length; maximum delays are indicated in the following diagram:

# Table 4-3. I<sup>2</sup>C Timing

Start	Slave address (B8h)	Ack	Subaddress	Ack	Data (XXh)	Ack	Wait 128 µs <sup>(1)</sup>	Stop	

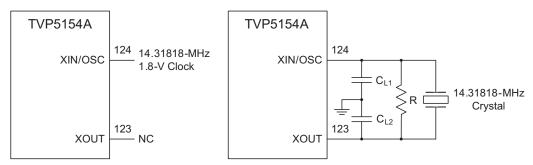
(1) If the SCL pin is not monitored by the master to enable pausing, a delay of 128 µs should be inserted between transactions for registers 00h through 8Fh.

# 5 Clock Circuits

An internal line-locked PLL generates the system and pixel clocks. A 14.31818-MHz clock is required to drive the PLL. This may be input to the TVP5154A decoder on terminal 124 (XIN), or a crystal of 14.31818-MHz fundamental resonant frequency may be connected across terminals 123 and 124 (XIN and XOUT). Figure 5-1 shows the reference clock configurations. For the example crystal circuit shown (a parallel-resonant crystal with 14.31818-MHz fundamental frequency), the external capacitors must have the following relationship:

 $C_{L1} = C_{L2} = 2C_L - C_{STRAY}$ 

where  $C_{STRAY}$  is the terminal capacitance with respect to ground and  $C_L$  is the crystal load capacitance specified by the crystal manufacturer. Figure 5-1 shows the reference clock configurations.



NOTE: The resistor (R) in parallel with the crystal is recommended to support a wide range of crystal types. A 100-kΩ resistor may be used for most crystal types.

Figure 5-1. Clock and Crystal Connectivity



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### 6 Genlock Control and RTC

A Genlock control (GLCO) function is provided to support a standard video encoder to synchronize its internal color oscillator for properly reproduced color with unstable timebase sources like VCRs.

The frequency control word of the internal color subcarrier digital control oscillator (DTO) and the subcarrier phase reset bit are transmitted via the GLCO terminal. The frequency control word is a 23-bit binary number. The frequency of the DTO can be calculated from the following equation:

$$\mathsf{F}_{\mathsf{dto}} = \frac{\mathsf{F}_{\mathsf{ctrl}}}{2^{23}} \times \mathsf{F}_{\mathsf{clk}} \tag{1}$$

where  $F_{dto}$  is the frequency of the DTO,  $F_{ctrl}$  is the 23–bit DTO frequency control, and  $F_{clk}$  is the frequency of the CLK.

#### 6.1 TVP5154A Genlock Control Interface

A write of 1 to bit 4 of the chrominance control register at I<sup>2</sup>C subaddress 1Ah causes the subcarrier DTO phase reset bit to be sent on the next scan line on GLCO. The active-low reset bit occurs seven CLKs after the transmission of the last bit of DCO frequency control. Upon the transmission of the reset bit, the phase of the TVP5154A internal subcarrier DCO is reset to zero.

A Genlock slave device can be connected to the GLCO terminal and uses the information on GLCO to synchronize its internal color phase DCO to achieve clean line and color lock.

#### 6.2 RTC Mode

Figure 6-1 shows the timing diagram of the RTC mode. Clock rate for the RTC mode is four times slower than the GLCO clock rate. For PLL frequency control, the upper 22 bits are used. Each frequency control bit is two clock cycles long. The active-low reset bit occurs six CLKs after the transmission of the last bit of PLL frequency control.



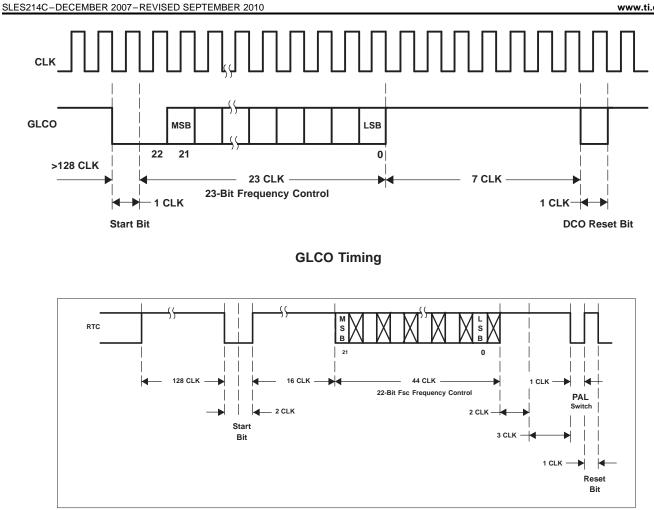


Figure 6-1. RTC Timing

#### 6.3 **Reset and Power Down**

The RESETB and PDN terminals work together to put the TVP5154A decoder into one of the two modes. Table 6-1 shows the configuration.

After power-up, the device is in an unknown state with its outputs undefined, until it receives a RESETB signal as depicted in Figure 6-2. After RESETB is released, the data (CHn\_OUT[7:0]), sync (HSYNCn, VSYNCn/PALIn), and clock (CLKn, SCLKn) outputs are Hi-Z until the chip is initialized and the outputs are activated.

#### NOTE

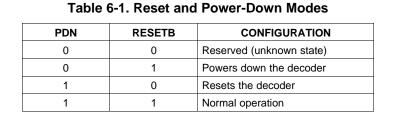
I2C SCL and SDA signals must not change state until the TVP5154A reset sequence has been completed.

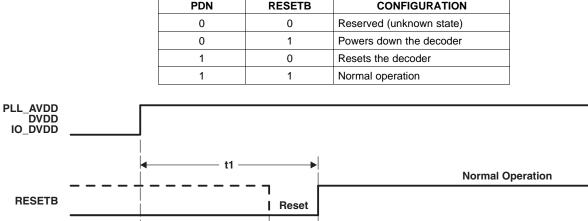
PDN

SDA

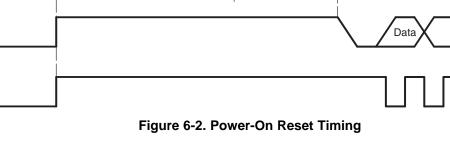
SCL

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# Table 6-2. Power-On Reset Timing

t3

NO.	PARAMETER	MIN	MAX	UNIT
t1	Delay time between power supplies active and reset	20		ms
t2	RESETB pulse duration	500		ns
t3	Delay time between end of reset to I <sup>2</sup> C active	200		μs

#### 6.4 **Reset Sequence**

Table 6-3 shows the reset sequence of the TVP5154A pins status during reset time and immediately after reset time.

# Table 6-3. Reset Sequence

PIN DESCRIPTION	DURING RESETB	IMMEDIATELY AFTER RESETB
INTREQ1/GPCL1/VBLK1, INTREQ2/GPCL2/VBLK2, INTREQ3/GPCL3/VBLK3, INTREQ4/GPCL4/VBLK4, HSYNC1, HSYNC2, HSYNC3, HSYNC4, VSYNC1/PAL11, VSYNC2/PAL12, VSYNC3/PAL13, VSYNC4/PAL14, CH1_OUT[7:0], CH2_OUT[7:0], CH3_OUT[7:0], CH4_OUT[7:0],	3-state	3-state
AIP1A, AIP1B, AIP2A, AIP2B, AIP3A, AIP3B, AIP4A, AIP4B, RESETB, PDN, SDA, SCL, I2CA0, I2CA1, XIN/OSC, TMS	Input	Input
FID1/GLCO1, FID2/GLCO2, FID3/GLCO3, FID4/GLCO4, AVID1, AVID2, AVID3, AVID4, CLK1, CLK2, CLK3, CLK4, SCLK1, SCLK2, SCLK3, SCLK4, XOUT	Output	Output



# 7 Internal Control Registers

#### 7.1 Overview

The TVP5154A decoder is initialized and controlled by sets of internal registers that set all device operating parameters. Communication between the external controller and the TVP5154A decoder is through the l<sup>2</sup>C. Two sets of registers exist, direct and indirect. Table 7-1 shows the summary of the direct registers. Reserved registers must not be written. Reserved bits in the defined registers must be written with zeros, unless otherwise noted. The detailed programming information of each register is described in the following sections.

I<sup>2</sup>C register FEh controls which of the four decoders receives I<sup>2</sup>C commands. I<sup>2</sup>C register FFh controls which decoder core responds to I<sup>2</sup>C reads. Note, for a read operation, it is necessary to perform a write first, to set the desired sub-address for reading.

After power up and the hardware reset, each decoder must be started by writing 00h to register 7Fh for all four decoders.

REGISTER FUNCTION	ADDRESS	DEFAULT	R/W <sup>(1)</sup>
Video input source selection #1	00h	00h	R/W
Analog channel controls	01h	15h	R/W
Operation mode controls	02h	00h	R/W
Miscellaneous controls	03h	01h	R/W
Autoswitch mask	04h	DCh	R/W
Clock control	05h	08h	R/W
Color killer threshold control	06h	10h	R/W
Luminance processing control #1	07h	60h	R/W
Luminance processing control #2	08h	00h	R/W
Brightness control	09h	80h	R/W
Color saturation control	0Ah	80h	R/W
Hue control	0Bh	00h	R/W
Contrast control	0Ch	80h	R/W
Outputs and data rates select	0Dh	47h	R/W
Luminance processing control #3	0Eh	00h	R/W
Configuration shared pins	0Fh	08h	R/W
Reserved	10h		
Active video cropping start MSB for unscaled data	11h	00h	R/W
Active video cropping start LSB for unscaled data	12h	00h	R/W
Active video cropping stop MSB for unscaled data	13h	00h	R/W
Active video cropping stop LSB for unscaled data	14h	00h	R/W
Genlock/RTC	15h	01h	R/W
Horizontal sync start	16h	80h	R/W
Ancillary SAV/EAV control	17h	52h	R/W
Vertical blanking start	18h	00h	R/W
Vertical blanking stop	19h	00h	R/W
Chrominance processing control #1	1Ah	0Ch	R/W
Chrominance processing control #2	1Bh	14h	R/W
Interrupt reset register B	1Ch	00h	R/W
Interrupt enable register B	1Dh	00h	R/W

#### Table 7-1. Direct Register Summary

(1) R = Read only, W = Write only, R/W = Read and write

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REGISTER FUNCTION	ADDRESS	DEFAULT	R/W <sup>(1)</sup>
Interrupt configuration register B	1Eh	00h	R/W
Output control	1Fh	00h	R/W
Reserved	20h		
Indirect Register Data	21h–22h	00h	R/W
Indirect Register Address	23h	00h	R/W
Indirect Register Read/Write Strobe	24h	00h	R/W
AVID start/control for scaled data	25h–26h	00h	R/W
Reserved	27h		
Video standard	28h	00h	R/W
AVID stop for scaled data	29h–2Ah	00h	R/W
Reserved	2Bh		
Cb gain factor	2Ch		R
Cr gain factor	2Dh		R
Reserved	2Eh–2Fh		
656 Revision Select	30	00h	R/W
Reserved	31h–7Dh		
Patch Write Address	7Eh	00h	R/W <sup>(2)</sup>
Patch Code Execute	7Fh	00h	R/W <sup>(2)</sup>
MSB of device ID	80h	51h	R
LSB of device ID	81h	54h	R
ROM major version	82h	02h	R
ROM minor version	83h	00h	R
Vertical line count MSB	84h		R
Vertical line count LSB	85h		R
Interrupt status register B	86h		R
Interrupt active register B	87h		R
Status register #1	88h		R
Status register #2	89h		R
Status register #3	8Ah		R
Status register #4	8Bh		R
Status register #5	8Ch		R
Reserved	8Dh		
Patch Read Address	8Eh	00h	R/W <sup>(2)</sup>
Reserved	8Fh		
Closed caption data registers	90h–93h		R
WSS/CGMS-A data registers	94h–99h		R
VPS/Gemstar 2x data registers	9Ah–A6h		R
VITC data registers	A7h–AFh		R
VBI FIFO read data	B0h		R
Teletext filter 1	B1h–B5h	00h	R/W
Teletext filter 2	B6h–BAh	00h	R/W
Teletext filter enable	BBh	00h	R/W
Reserved	BCh-BFh		
Interrupt status register A	C0h	00h	R/W
Interrupt enable register A	C1h	00h	R/W
Interrupt configuration	C2h	04h	R/W

Table 7-1. Direct Register Summary (continued)

(2) These registers are used for firmware patch code and should not be written to or read from during normal operation.

REGISTER FUNCTION	ADDRESS	DEFAULT	R/W <sup>(1)</sup>
VDP configuration RAM data	C3h	B8h	R/W
Configuration RAM address low byte	C4h	1Fh	R/W
Configuration RAM address high byte	C5h	00h	R/W
VDP status register	C6h		R
FIFO word count	C7h		R
FIFO interrupt threshold	C8h	80h	R/W
FIFO reset	C9h	00h	W
Line number interrupt	CAh	00h	R/W
Pixel alignment register low byte	CBh	4Eh	R/W
Pixel alignment register high byte	CCh	00h	R/W
FIFO output control	CDh	01h	R/W
Reserved	CEh		
Full field enable	CFh	00h	R/W
Line mode registers	D0h D1h–FBh	00h FFh	R/W
Full field mode register	FCh	7Fh	R/W
Reserved	FDh		
Decoder core write enables	FEh	0Fh	R/W
Decoder core read enables	FFh	00h	R/W

### Table 7-1. Direct Register Summary (continued)

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# 7.2 Direct Register Definitions

Direct registers are written to by performing a 3-byte I<sup>2</sup>C transaction: START : DEVICE\_ID : SUB\_ADDRESS : DATA : STOP

Each direct register is eight bits wide.

# 7.2.1 Video Input Source Selection #1 Register

Address		00h					
Default		00h					
7	6	5	4	3	2	1	0
	Reserved		Black output	Reserved	Channel n source selection	S-video selection	

Channel n source selection:

0 = AIPnA selected (default)

1 = AIPnB selected

Table 7-2. Analog Channel	and Video Mode Selection
---------------------------	--------------------------

		ADDRESS 00		
	INPUT(S) SELECTED	BIT 1	BIT 0	
Composito	AIPnA (default)	0	0	
Composite	AIPnB	1	0	
S-Video	AIPnA (luma), AIPnB (chroma)	х	1	

Where n = 1, 2, 3, 4

Black output:

- 0 = Normal operation (default)
- 1 = Force black screen output (outputs synchronized)

a. Forced to 10h in normal mode

b. Forced to 01h in extended mode

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# 7.2.2 Analog Channel Controls Register

Address	01h						
Default	15h						
7	6	5	4	3	2	1	0
	Reserved		1	0	1	Automatic	nain control

Automatic gain control (AGC):

00 = AGC disabled (fixed gain value)

01 = AGC enabled (default)

00h

10 = Reserved

11 = AGC frozen to the previously set value

# 7.2.3 Operation Mode Controls Register

Address	02h
---------	-----

7	6	5	4	3	2	1	0
Fast lock mode	Color burst reference enable	TV/VCR mode		Composite peak disable	Color subcarrier PLL frozen	Luma peak disable	Power down mode

Fast lock mode:

0 = Normal operation (default)

1 = Fast lock mode. Locks within three fields if stable input signal and forced video standard.

Color burst reference enable:

0 = Color burst reference for AGC disabled (default)

1 = Color burst reference for AGC enabled (not recommended)

TV/VCR mode:

00 = Automatic mode determined by the internal detection circuit (default)

01 = Reserved

10 = VCR (nonstandard video) mode (recommended when using a camera locked to the AC line frequency)

11 = TV (standard video) mode

With automatic detection enabled, unstable or nonstandard syncs on the input video forces the detector into the VCR mode. This turns off the comb filters and turns on the chroma trap filter.

Composite peak disable:

- 0 = Composite peak protection enabled (default)
- 1 = Composite peak protection disabled

Color subcarrier PLL frozen:

0 = Color subcarrier PLL increments by the internally generated phase increment (default).

GLCO pin outputs the frequency increment.

1 = Color subcarrier PLL stops operating.

GLCO pin outputs the frozen frequency increment.

Luma peak disable

- 0 = Luma peak processing enabled (default)
- 1 = Luma peak processing disabled (recommended)
- Power-down mode:
  - 0 = Normal operation (default)
  - 1 = Power-down mode. A/Ds are turned off and internal clocks are reduced to minimum.



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### 7.2.4 Miscellaneous Control Register

Address	03h	
Default	01h	

Delault	011	1					
7	6	5	4	3	2	1	0
VBKO	GPCL pin	GPCL output enable	Lock status (HVLK)	YCbCr output enable(TVPOE)	HSYNC, VSYNC/PALI, AVID, FID/GLCO output enable	Vertical blanking on/off	CLK output enable

VBKO (pins 41, 60, 83, 102) function select:

0 = GPCL (default)

1 = VBLK

Note, if these pins are not configured as outputs, they must not be left floating. A  $10-k\Omega$  pulldown resistor is recommended if not driven externally.

GPCL (data is output based on state of bit 5):

0 = GPCL outputs 0 (default)

1 = GPCL outputs 1

GPCL output enable:

- 0 = GPCL is inactive (default). GPCL should not be programmed to 0 when register 0Fh bit 1 is 1 (programmed to be GPCL/VBLK).
- 1 = GPCL is output.

Note that, if these pins are not configured as outputs, they must not be left floating. A 10-k $\Omega$  pulldown resistor is recommended if not driven externally.

Lock status (HVLK) (configured along with register 0Fh, see Figure 7-1 for the relationship between the configuration shared pins):

- 0 = Terminal VSYNC/PALI outputs the PAL indicator (PALI) signal and terminal FID/GLCO outputs the field ID (FID) signal (default) (if terminals are configured to output PALI and FID in register 0Fh).
- 1 = Terminal VSYNC/PALI outputs the horizontal lock indicator (HLK) and terminal FID outputs the vertical lock indicator (VLK) (if terminals are configured to output PALI and FID in register 0Fh).

These are additional functionalities that are provided for ease of use.

YCbCr output enable:

- 0 = YOUT[7:0] high impedance (default)
- 1 = YOUT[7:0] active

Note, if these pins are not configured as outputs, they must not be left floating. A  $10-k\Omega$  pulldown resistor is recommended if not driven externally.

HSYNC, VSYNC/PALI, active video indicator (AVID), and FID/GLCO output enables:

- 0 = HSYNC, VSYNC/PALI, AVID, and FID/GLCO are high impedance (default).
- 1 = HSYNC, VSYNC/PALI, AVID, and FID/GLCO are active.

Note, if these pins are not configured as outputs, they must not be left floating. A 10-k $\Omega$  pulldown resistor is recommended if not driven externally.

Vertical blanking on/off:

- 0 = Vertical blanking (VBLK) off (default)
- 1 = Vertical blanking (VBLK) on
- CLK output enable:
  - 0 = CLK output is high impedance.
  - 1 = CLK output is enabled (default).

Note: CLK edge and SCLK are configured through register 05h.

REGISTER 03h, BIT 3 (TVPOE) <sup>(1)</sup>	REGISTER C2h, BIT 2 (VDPOE) <sup>(1)</sup>	YCbCr OUTPUT
0	Х	High impedance
X	0	High impedance
1	1	Active

#### Table 7-3. Digital Output Control

(1) VDPOE default is 1 and TVPOE default is 0.



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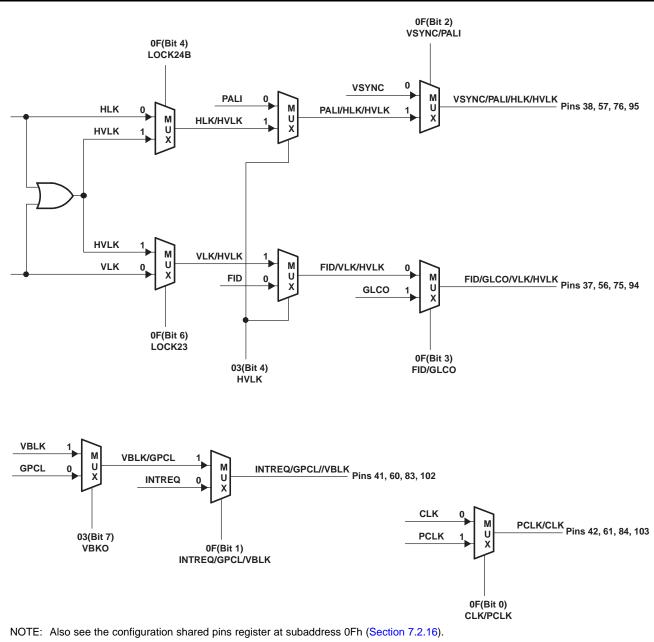


Figure 7-1. Configuration Shared Pins



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# 7.2.5 Autoswitch Mask Register

Address	04h							
Default	DCh							
7	6	5	4	3	2	1	0	
Res	served	SEC_OFF	N443_OFF	PALN_OFF	PALM_OFF	Res	served	
N443_OFF:								
0 = N	0 = NTSC443 is unmasked from the autoswitch process. Autoswitch does switch to NTSC443.							
1 = N	ITSC443 is masked	d from the autoswi	tch process. Auto	switch does not sv	witch to NTSC443	(default).		
PALN_OFF:								
0 = P	AL-N is unmasked	from the autoswit	ch process. Autos	witch does switch	to PAL-N.			
1 = P	AL-N is masked fro	om the autoswitch	process. Autoswi	tch does not switc	h to PAL-N (defau	ılt).		
PALM_OFF:								
0 = P	AL-M is unmasked	from the autoswit	ch process. Autos	witch does switch	n to PAL-M.			
1 = P	AL-M is masked fro	om the autoswitch	process. Autoswi	tch does not swite	ch to PAL-M (defa	ult).		
SEC_OFF:								
0 = S	ECAM is unmaske	d from the autosw	itch process. Auto	switch does switc	h to SECAM (defa	ault).		
1 = S	ECAM is masked f	rom the autoswitc	h process. Autosv	vitch does not swit	tch to SECAM.			
726 Cloc	k Control Re	aister						

# 7.2.6 Clock Control Register

Address	05h						
Default	08h						
7	6	5	4	3	2	1	0
	Reserved				Reserved	SCLK edge	CLK edge

CLK edge

0 = CLK data changes on falling edge of CLK.

1 = CLK data changes on rising edge of CLK.

SCLK edge

0 = SCLK data changes on falling edge of SCLK.

1 = SCLK data changes on rising edge of SCLK.

SCLK OE

0 = SCLK output disabled. Output is high impedance.

1 = SCLK output enabled.

NOTE: CLK OE is configured through register 0x03 to maintain compatibility with the TVP5150 family of devices.

# 7.2.7 Color Killer Threshold Control Register

Address	06h						
Default	10h						
7	6	5	4	3	2	1	0
Reserved	Automatic	matic color killer threshold					
Automatic color	killer:						
00 =	Automatic mode	(default)					
01 =	Reserved						
10 =	Color killer enabl	ed, the CbCr term	ninals are forced to	a zero color state			
11 =	Color killer disab	led					
Color killer three	shold:						
11111 =	–30 dB (minimun	n)					

10000 = -24 dB (default)

00000 = -18 dB (maximum)

# 7.2.8 Luminance Processing Control #1 Register

Address Default	07h 60h						
7	6	5	4	3	2	1	0
2× luma output enable	Pedestal not present	Disable raw header	Luma bypass enabled during vertical blanking	Luminar		delay with ance sign	n respect to al

2× luma output enable:

0 = Output depends on bit 4, luminance bypass enabled during vertical blanking (default).

1 = Outputs 2x luma samples during the entire frame. This bit takes precedence over bit 4.

Pedestal not present:

0 = 7.5 IRE pedestal is present on the analog video input signal.

1 = Pedestal is not present on the analog video input signal (default).

Disable raw header:

0 = Insert 656 ancillary headers for raw data

1 = Disable 656 ancillary headers and instead force dummy ones (0x40) (default)

Luminance bypass enabled during vertical blanking:

- 0 = Disabled. If bit 7, 2x luma output enable, is 0, normal luminance processing occurs and YCbCr samples are output during the entire frame (default).
- 1 = Enabled. If bit 7, 2x luma output enable, is 0, normal luminance processing occurs and YCbCr samples are output during VACTIVE and 2x luma samples are output during VBLK. Luminance bypass occurs for the duration of the vertical blanking as defined by registers 18h and 19h.

Luma signal delay with respect to chroma signal in pixel clock increments (range -8 to 7 pixel clocks):

- 1111 = -8 pixel clocks delay
- 1011 = -4 pixel clocks delay
- 1000 = -1 pixel clocks delay
- 0000 = 0 pixel clocks delay (default)
- 0011 = 3 pixel clocks delay
- 0111 = 7 pixel clocks delay

# 7.2.9 Luminance Processing Control #2 Register

Address	08h
Default	00h

7	6	5	4	3	2	1	0
Reserved	Luminance filter select	Reserved		Peaking gain		Res	erved

Luminance filter select:

0 = Luminance comb filter enabled (default)

1 = Luminance chroma trap filter enabled

Peaking gain (sharpness):

00 = 0 (default)

- 01 = 0.5
- 10 = 1

Information on peaking frequency: ITU-R BT.601 sampling rate: all standards — peaking center frequency is 2.6 MHz

# 7.2.10 Brightness Control Register

Default 7	80h	E	4	2	2	1	0
1	0	5	4	3	2	1	U

Brightness control: This register works for CVBS and S-Video luminance.

1111 1111 = 255 (bright)

1000 0000 = 128 (default)

 $0000\ 0000 = 0\ (dark)$ 

The output black level relative to the nominal black level (16 out of 256) as a function of the Brightness[7:0] setting and the Contrast[7:0] setting is as follows.

Black Level = nominal\_black\_level + (Brightness[7:0] - 128) + (438 / 4) x (1 - Contrast[7:0] / 128)

# 7.2.11 Color Saturation Control Register

Default	80h						
7	6	5	4	3	2	1	0
			Saturation	n control			

1111 1111 = 255 (maximum)

1000 0000 = 128 (default)

 $0000\ 0000 = 0$  (no color)

The total chrominance gain relative to the nominal chrominance gain as a function of the Saturation [7:0] setting is as follows. Chrominance Gain = nominal\_chrominance\_gain × (Saturation[7:0] / 128)

# 7.2.12 Hue Control Register (does not apply to SECAM)

Address Default	0Bh 00h									
7	6	5	4	3	2	1	0			
	Hue control									

Hue control:

0111 1111 = +180 degrees 0000 0000 = 0 degrees (default) 1000 0000 = -180 degrees

### 7.2.13 Contrast Control Register

Address Default	0Ch 80h								
7	6	5	4	3	2	1	0		
Contrast [7:0]									

Contrast [7:0]: This register works for CVBS and S-Video luminance.

1111 1111 to 1101 Reserved 0000 =

1100 1111 = 207 (maximum contrast)

1000 0000 = 128 (default)

0000 0000 = 0 (minimum contrast)

The total luminance gain relative to the nominal luminance gain as a function of the Contrast [7:0] setting is as follows.

Luminance Gain = nominal\_luminance\_gain × (Contrast[7:0] / 128)

Note: Luminance peak processing (see bit 1 of subaddress: 02h) may limit the upper end of the contrast control range.

Note: Whenever the contrast control setting is modified, the brightness control setting must be modified immediately afterward to maintain the proper output black level.

# 7.2.14 Outputs and Data Rates Select Register

Address Default	0Dh 47h						
7	6	5	4	3	2	1	0
Reserved	YCbCr output code range	CbCr code format	YCbCr data	YCb	Cr output f	iormat	

YCbCr output code range:

0 = ITU-R BT.601 coding range (Y ranges from 16 to 235. U and V range from 16 to 240)

1 = Extended coding range (Y, U, and V range from 1 to 254) (default)

CbCr code format:

0 = Offset binary code (2s complement + 128) (default)

1 = Straight binary code (2s complement)

YCbCr data path bypass:

- 00 = Normal operation (default)
- 01 = Decimation filter output connects directly to the YCbCr output pins. This data is similar to the digitized composite data, but the HBLANK area is replaced with ITU-R BT.656 digital blanking.
- 10 = Digitized composite (or digitized S-video luma). A/D output connects directly to the YCbCr output pins.

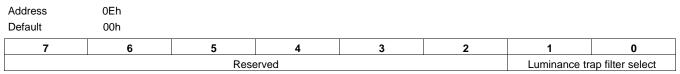
11 = Reserved

YCbCr output format:

- 000 = 8-bit 4:2:2 YCbCr with discrete sync output
- 001 = Reserved
- 010 = Reserved
- 011 = Reserved
- 100 = Reserved
- 101 = Reserved
- 110 = Reserved
- 110 = Reserved
- 111 = 8-bit ITU-R BT.656 interface with embedded sync output (default)



## 7.2.15 Luminance Processing Control #3 Register



Luminance filter stop band bandwidth (MHz):

00 = No notch (default)

- 01 = Notch 1
- 10 = Notch 2
- 11 = Notch

Luminance filter select [1:0] selects one of the four chroma trap (notch) filters to produce luminance signal by removing the chrominance signal from the composite video signal. The stopband of the chroma trap filter is centered at the chroma subcarrier frequency, with stopband bandwidth controlled by the two control bits. See Table 7-4 for the stopband bandwidths. The WCF bit is controlled in the chrominance control #2 register.

WCF	FILTER SELECT	NTSC/PAL/SECAM ITU-R BT.601
	00	1.2214
0	01	0.8782
0	10	0.7297
	11	0.4986
	00	1.4170
	01	1.0303
1	10	0.8438
	11	0.5537

Table 7-4. Luma Filter Selection

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## 7.2.16 Configuration Shared Pins Register

Address	0Fh						
Default	08h						
7	6	5	4	3	2	1	0
Reserved	FID PIN	Reserved	PALI PIN	FID/GLCO	VSYNC/PALI	INTREQ/GPCL/VBLK	CLK/PCLK
FID PIN funct	tion select:						
	0 = FID (de	efault, if bit 3 is s	selected to out	put FID)			
	1 = Lock ir	ndicator (indicate	es whether the	device is lock	ed vertically)		
PALI PIN fun	ction select:						
	0 = PALI (e	default, if bit 2 is	selected to o	utput PALI)			
	1 = Lock ir	ndicator (indicate	es whether the	device is lock	ed horizontally)		
FID/GLCO fu		ct (see register 0	3h, Section 7.	2.4, for enhand	ced functionality):		
	0 = FID						
	1 = GLCO	· · ·					
VSYNC/PALI			r 03h, Section	7.2.4, for enha	anced functionality):		
	0 = VSYN0	C (default)					
	1 = PALI						
INTREQ/GPC							
	0 = INTRE	,					
		or VBLK depend	-	f register 03h			
CLK/PCLK (p	oins 42, 61,	84, 103) function	n select:				
		t 27 MHz (defau	,				
	1 = PCLK (1x pixel clock frequency at 13.5 MHz)						
See	See Figure 7-1 for the relationship between the configuration shared pins.						

## 7.2.17 Active Video Cropping Start Pixel MSB for Unscaled Data Register

Address Default	11h 00h						
7	6	5	4	3	2	1	0
			AVID start pi	xel MSB [9:2]			

Active video cropping start pixel MSB [9:2], set this register first before setting register 12h. The TVP5154A decoder updates the AVID start values only when register 12h is written to. This start pixel value is relative to the default values of the AVID start pixel.



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## 7.2.18 Active Video Cropping Start Pixel LSB for Unscaled Data Register

Address	12h							
Default	00h							
7	6	5	4	3	2	1	0	
		Reserved			AVID active	AVID start p	ixel LSB [1:0]	
AVID active:								
	0 = AVID ou	t active in VBLK (de	efault)					
	1 = AVID ou	t inactive in VBLK						
AVID start [9:0	] (combined regist	ers 11h and 12h):						
01 1111	1111 = 511							
00 000	0001 = 1							
00 000	$00\ 0000\ 0000 = 0\ (default)$							
11 1111	11 1111 1111 = -1							
10 0000	$10\ 0000\ 0000 = -512$							

Active video cropping start pixel LSB [1:0]: The TVP5154A decoder updates the AVID start values only when this register is written to.

## 7.2.19 Active Video Cropping Stop Pixel MSB LSB for Unscaled Data Register

Address Default	13h 00h						
7	6	5	4	3	2	1	0
			AVID stop pi	xel MSB [9:2]			

Active video cropping stop pixel MSB [9:2], set this register first before setting the register 14h. The TVP5154A decoder updates the AVID stop values only when register 14h is written to. This stop pixel value is relative to the default values of the AVID stop pixel.

## 7.2.20 Active Video Cropping Stop Pixel LSB for Unscaled Data Register

Address	14h						
Default	00h						
7	6	5	4	3	2	1	0
			AVID stop pi	xel LSB [1:0]			

Active video cropping stop pixel LSB [1:0]: The number of pixels of active video must be an even number. The TVP5154A decoder updates the AVID stop values only when this register is written to.

AVID stop [9:0] (combined registers 13h and 14h):

01 1111 1111 = 511 00 0000 0001 = 1 00 0000 0000 = 0 (default) (see Figure 3-5) and Figure 3-6) 11 1111 1111 = -1 10 0000 0000 = -512



### 7.2.21 Genlock and RTC Register

Address	15h						
Default	01h						
7	6	5	4	3	2	1	0
Stable syncs	Reserved	F/V bit	control	Auto inc		GLCO/RTC	

Stable syncs

0 = Output F and V bits follow the input signal producing fixed vertical blanking periods by adapting the active video.

1 = Output F and V bits produce fixed active video periods by adapting the vertical blanking.

F/V bit control

BIT 5	BIT 4	NUMBER OF LINES	F BIT	V BIT
		Standard	ITU-R BT.656	ITU-R BT.656
0	0	Nonstandard even	Force to 1	Switch at field boundary
		Nonstandard odd	Toggles	Switch at field boundary
0	4	Standard	ITU-R BT.656	ITU-R BT.656
0	I	Nonstandard	Toggles	Switch at field boundary
4	0	Standard	ITU-R BT.656	ITU-R BT.656
1	0	Nonstandard	Pulse mode	Switch at field boundary
1	1	Illegal		

#### Table 7-5. F/V Bit Control

Auto inc: When this bit is set to 1, subsequent reading/writing from/to back door registers automatically increment the address index.

GLCO/RTC: Table 7-6 for different modes.

BIT 2	BIT 1	BIT 0	GENLOCK/RTC MODE	
0	x	0	GLCO	
0	x	1	RTC output mode 0 (default)	
1	x	0	GLCO	
1	x	1	RTC output mode 1	

#### Table 7-6. GLCO/RTC Control

All other values are reserved.

Figure 6-1 shows the timing of GLCO and the timing of RTC.



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# 7.2.22 Horizontal Sync (HSYNC) Start Register

Address	16h						
Default	80h						
7	6	5	4	3	2	1	0
			HSY	NC start			
HSYNC start:							
11	11 1111 = -127 >	4 pixel clocks					
11	11 1110 = -126 >	4 pixel clocks					
10	$00\ 0001 = -1 \times 4$	pixel clocks					
	$00\ 0000 = 0$ pixe						
	$11\ 1111 = 1 \times 4$						
	$11\ 1110 = 2 \times 4$						
00	$00\ 0000 = 128 \times$	4 pixel clocks					
		BT.656 EAV Code				BT.656 SAV Code	
Y	OUT[7:0] U Y V	Y F 0 0 X 8 1 F 0 0 Y 0 0				8 1 F 0 0 X U Y 0 0 F 0 0 Y	]
	HSYNC						_
	AVID	1	1				-
		Nhbhs		128 SCL	Start of	Digital ve Line	
		N <sub>hbhs</sub>	<b>→</b> ,	N <sub>hb</sub>			

Figure 7-2. Horizontal Sync

Table 7-7.	<b>Clock Delay</b>	ys (CLKs)
------------	--------------------	-----------

STANDARD	N <sub>hbhs</sub>	N <sub>hb</sub>
NTSC	16	272
PAL	20	284
SECAM	40	280

Detailed timing information is also available in Section 3.12, Synchronization Signals.

# 7.2.23 Ancillary SAV/EAV Control

Address	17h	
Default	52h	

7	6	5	4	3	2	1	0
Reserved	Scaler PD	Include scale ancillary	Include scale SAV	Include scale EAV	Include unscale ancillary	Include unscale SAV	Include unscale EAV

Include unscaled EAV:

0 = AVID period does not include the EAV sync codes (default).

1 = AVID period includes the EAV sync codes.

Include unscaled SAV:

0 = AVID period does not include the SAV sync codes.

1 = AVID period includes the SAV sync codes (default).

Include unscaled ancillary data:

0 = AVID period includes the ancillary data region (default).

1 = AVID period does not include the ancillary data region.

Include scaled EAV:

0 = AVID period does not include the EAV sync codes (default).

1 = AVID period includes the EAV sync codes.

Include scaled SAV:

0 = AVID period does not include the SAV sync codes.

1 = AVID period includes the SAV sync codes (default).

Include scaled ancillary data:

0 = AVID period includes the ancillary data region (default).

1 = AVID period does not include the ancillary data region.

Scaler PD (scaler power down):

0 = Scaler active

1 = Scaler powered down (default)



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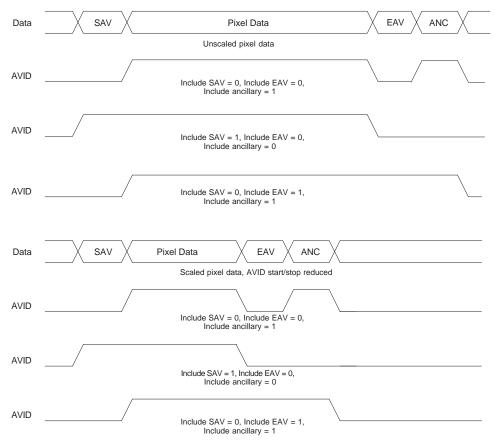


Figure 7-3. AVID Behavior When Ancillary Data Present

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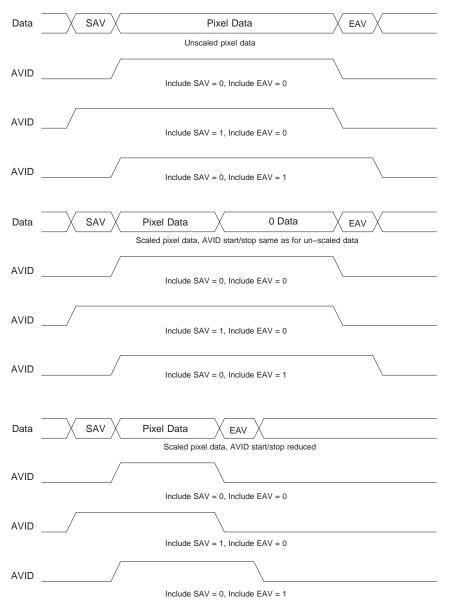


Figure 7-4. AVID Behavior When No Ancillary Data Present



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#### 7.2.24 Vertical Blanking Start Register

Address Default	18h 00h									
7	6	5	4	3	2	1	0			
Vertical blanking start										

Vertical blanking (VBLK) start:

0111 1111 = 127 lines after start of vertical blanking interval

0000 0001 = 1 line after start of vertical blanking interval

0000 0000 = Same time as start of vertical blanking interval (default) (see Figure 3-4, Figure 3-5, and Figure 3-6)

1111 1111 = 1 line before start of vertical blanking interval

1000 0000 = 128 lines before start of vertical blanking interval

Vertical blanking is adjustable with respect to the standard vertical blanking intervals. The setting in this register determines the timing of the GPCL/VBLK signal when it is configured to output vertical blank (see register 03h). The setting in this register also determines the duration of the luma bypass function (see register 07h).

### 7.2.25 Vertical Blanking Stop Register

Address Default	19h 00h						
7	6	5	4	3	2	1	0
			Vertical bla	anking stop			

Vertical blanking (VBLK) stop:

0111 1111 = 127 lines after stop of vertical blanking interval

 $0000\ 0001 = 1$  line after stop of vertical blanking interval

0000 0000 = Same time as stop of vertical blanking interval (default) (see Figure 3-4, Figure 3-5, and Figure 3-6)

1111 1111 = 1 line before stop of vertical blanking interval

1000 0000 = 128 lines before stop of vertical blanking interval

Vertical blanking is adjustable with respect to the standard vertical blanking intervals. The setting in this register determines the timing of the GPCL/VBLK signal when it is configured to output vertical blank (see register 03h). The setting in this register also determines the duration of the luma bypass function (see register 07h).

## 7.2.26 Chrominance Control #1 Register

Defau	lt		00	Ch				
7		6	5	4	3	2	1	0
Re	ser	ved c	olor	PLL reset	Chrominance adaptive comb filter enable (ACE)	Chrominance comb filter enable (CE)	Automatic c	olor gain control

Color PLL reset:

0 = Color PLL not reset (default)

1 = Color PLL reset

1Ah

Writing a 1 to this bit resets the color PLL and transmits a 1 in the reset bit of the GLCO output stream.

Chrominance adaptive comb filter enable (ACE):

- 0 = Disable
- 1 = Enable (default)

Chrominance comb filter enable (CE):

- 0 = Disable
- 1 = Enable (default)

Automatic color gain control (ACGC):

- 00 = ACGC enabled (default)
- 01 = Reserved
- 10 = ACGC disabled
- 11 = ACGC frozen to the previously set value

## 7.2.27 Chrominance Control #2 Register

Default	14h						
7	6	5	4	3	2	1	0
	Res	served		Reserved	WCF	Chrominanc	e filter select
Videband chr	oma filter (WCF):						
0 =	Disable						
1 =	Enable (default)						
hrominance	filter select:						
	No notch (default)						
00 =	No notch (default) Notch 1						
00 = 01 =	· · · ·						

WCF	FILTER SELECT	NTSC/PAL/SECAM ITU-R BT.601						
	00	1.2214						
0	01	0.8782						
0	10	0.7297						
	11	0.4986						
	00	1.4170						
4	01	1.0303						
1	10	0.8438						
	11	0.5537						

### Table 7-8. Chroma Output Bandwidth Select



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### 7.2.28 Interrupt Reset Register B

Address	1Ch						
Default	00h						
7	6	5	4	3	2	1	0
Software initialization reset	Reserved	Reserved	Field rate changed reset	Line alternation changed reset	Color lock changed reset	H/V lock changed reset	TV/VCR changed reset

Interrupt reset register B is used by the external processor to reset the interrupt status bits in interrupt status register B. Bits loaded with a 1 allow the corresponding interrupt status bit to reset to 0. Bits loaded with a 0 have no effect on the interrupt status bits.

Software initialization reset:

- 0 = No effect (default)
- 1 = Reset software initialization bit

Field rate changed reset:

0 = No effect (default)

1 = Reset field rate changed bit

Line alternation changed reset:

- 0 = No effect (default)
- 1 = Reset line alternation changed bit

Color lock changed reset:

- 0 = No effect (default)
- 1 = Reset color lock changed bit

H/V lock changed reset:

- 0 = No effect (default)
- 1 = Reset H/V lock changed bit

TV/VCR changed reset [TV/VCR mode is determined by counting the total number of lines/frame. The mode switches to VCR for nonstandard number of lines]:

- 0 = No effect (default)
- 1 = Reset TV/VCR changed bit

# 7.2.29 Interrupt Enable Register B

1Dh

006

Address	
Default	

Default 00h							
7	6	5	4	3	2	1	0
Software initialization occurred enable	Reserved	Reserved	Field rate changed	Line alternation changed	Color lock changed	H/V lock changed	TV/VCR changed

Software initialization occurred enable:

0 = Disabled (default)

1 = Enabled

Field rate changed:

0 = Disabled (default)

1 = Enabled

Line alternation changed:

0 =Disabled (default)

1 = Enabled

Color lock changed:

0 = Disabled (default)

1 = Enabled

H/V lock changed:

0 = Disabled (default)

1 = Enabled

#### TV/VCR changed:

0 = Disabled (default)

1 = Enabled

Interrupt enable register B is used by the external processor to mask unnecessary interrupt sources for interrupt B. Bits loaded with a 1 allow the corresponding interrupt condition to generate an interrupt on the external pin. Conversely, bits loaded with zeros mask the corresponding interrupt condition from generating an interrupt on the external pin. This register only affects the external pin; it does not affect the bits in the interrupt status register. A given condition can set the appropriate bit in the status register and not cause an interrupt on the external pin. To determine if this device is driving the interrupt pin, either AND interrupt status register B with interrupt enable register B, or check the state of interrupt B in the interrupt B active register.



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### 7.2.30 Interrupt Configuration Register B

Address Default	1Eh 00h						
7	6	5	4	3	2	1	0
			Reserved				Interrupt polarity B

Interrupt polarity B:

0 = Interrupt B is active low (default).

1 = Interrupt B is active high.

Interrupt polarity B must be same as interrupt polarity A bit at bit 0 of the interrupt configuration register A at address C2h.

Interrupt configuration register B is used to configure the polarity of interrupt B on the external interrupt pin. When the interrupt B is configured for active low, the pin is driven low when active and high impedance when inactive (open drain). Conversely, when the interrupt B is configured for active high, it is driven high for active and driven low for inactive.

### 7.2.31 Indirect Register Data

Address	21h-22h										
Default	00h										
Address	7	6	5	4	3	2	1	0			
22h				Data	[15:8]						
21h		Data[7:0]									

 $I^2C$  registers 21h and 22h can be used to write data to or read data from indirect registers. See  $I^2C$  registers 23h and 24h.

#### 7.2.32 Indirect Register Address

Address Default	23h 00h									
7	6	5	4	3	2	1	0			
	ADDR[7:0]									

ADDR[7:0] = LSB of indirect address

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## 7.2.33 Indirect Register Read/Write Strobe

Address Default	24h 00h									
7	6	5	4	3	2	1	0			
	R/W[7:0]									

This register selects the most significant bits of the indirect register address and performs either an indirect read or write operation. Data will be written from are read to Indirect Register Data registers 21h-22h.

R/W[7:0]:

01h = read from 00h-1FFh address bank

02h = write to 00h-1FFh address bank

03h = read from 200h-3FFh address bank

04h = write to 200h-3FFh address bank

05h = read from 300h-3FFh address bank

06h = write to 300h-3FFh address bank

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### 7.2.34 Output Control

Address	1Fh						
Default	00h						
7	6	5	4	3	2	1	0
	Bit swap	Ancillary Enable	Parity modifier	SAV/EAV modifier		Output mode	

Output mode:

000 = Mode 0 : Unscaled data clocked by clock 1

001 = Mode 1 : Scaled data clocked by clock 1

010 = Mode 2 : Multiplexed data with separate clocks

011 = Mode 3 : Multiplexed data with clock 1 at 54 MHz

100 = Mode 4 : Unscaled/scaled field toggled data clocked by clock 1

SAV/EAV modifier:

0 = SAV/EAV codes not modified

1 = SAV/EAV MSB modified. MSB = 1 indicates unscaled data, MSB = 0 indicates scaled data

Parity modifier:

0 = Parity calculation includes SAV/EAV MSB.

1 = Parity calculation does not include SAV/EAV MSB.

Ancillary enable:

0 = Ancillary data not enabled

1 = Ancillary data packet added to indicate scaled or unscaled data

Note : Scaled/unscaled ancillary data cannot be enabled at the same time as VBI ancillary data

#### Bit swap:

0 = chx\_out(0) corresponds to data LSB, chx\_out(7) corresponds to data MSB

1 = chx\_out(0) corresponds to data MSB, chx\_out(7) corresponds to data LSB

BYTE NO.	D7 (MSB)	D6	D5	D4	D3	D2	D1	D0 (LSB)		DESCRIPTION
0	0	0	0	0	0	0	0	0	Ancillary data pre	eamble
1	1	1	1	1	1	1	1	1	-	
2	1	1	1	1	1	1	1	1	-	
3	NEP	EP	0	1	DID3	DID2	DID1	DID0	Data ID (DID)	
4	1	0	0	0	0	0	0	0	Secondary data	D (SDID)
5	0	1	0	0	0	0	0	1	Number of 32 bit	data (NN)
6				Video I	ine # [7:0]				Internal data ID0	(IDID0)
Z	0	0	0	0	0	0	Video li	ne # [9:8]	Internal data ID1	(IDID1)
8					00h				Data byte	Data
9					00h				Data byte	
10	1	0			(	)0h			Check sum	
11	1	0	0	0	0	0	0	0	Fill byte	

#### Table 7-9. Ancillary Data Format and Sequence

EP: Even parity for D0–D5

NEP: Negated even parity

DID: For unscaled data D0–D3 taken from EAV DID value for unscaled data stream register low nibble for field 0 and from high nibble for field 1

For scaled data D0–D3 taken from EAV DID value for scaled data stream register low nibble for field 0 and from high nibble for field 1

SDID: Zero data

NN: Indicates 1 D word of data

IDID0: Transaction video line number [7:0]

IDID1: Bit 0/1 = Transaction video line number [9:8]

CS: Sum of D0–D7 of DID through last data byte

Fill byte: Fill bytes make a multiple of four bytes from byte 0 to last fill byte. For teletext modes, byte 8 is the sync pattern byte. Byte 9 is 1. Data (the first data byte).

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## 7.2.35 Active Video Cropping Start Pixel MSB for Scaled Data Register

Address Default	25h 00h										
7	6	5	4	3	2	1	0				
	AVID start pixel MSB [9:2]										

Active video cropping start pixel MSB [9:2], set this register first before setting register 26h. The TVP5154A decoder updates the AVID start values only when register 26h is written to. This start pixel value is relative to the default values of the AVID start pixel.

## 7.2.36 Active Video Cropping Start Pixel LSB for Scaled Data Register

Address Default	26h 00h						
7	6	5	4	3	2	1	0
		Reserved	Active	AVID start pi	xel LSB [1:0]		

AVID active:

0 = AVID out active in VBLK (default)

1 = AVID out inactive in VBLK

Active video cropping start pixel LSB [1:0]: The TVP5154A decoder updates the AVID start values only when this register is written to. AVID start [9:0]:

01 1111 1111 = 511 00 0000 0001 = 1 00 0000 0000 = 0 (default) 11 1111 1111 = -1 10 0000 0000 = -512



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## 7.2.37 Video Standard Register

Address	28h						
Default	00h						
7	6	5	4	3	2	1	0
	Rese	erved			Video s	tandard	
Video standaro	1:						
0000 =	Autoswitch mode	(default)					
0001 =	Reserved						
0010 =	= (M, J) NTSC ITU-	-R BT.601					
0011 =	Reserved						
0100 =	= (B, G, H, I, N) PA	L ITU-R BT.601					
0101 =	Reserved						
0110 =	= (M) PAL ITU-R B	T.601					
0111 =	Reserved						
1000 =	= (Combination-N)	PAL ITU-R BT.601					
1001 =	Reserved						
1010 =	= NTSC 4.43 ITU-F	R BT.601					
1011 =	Reserved						
1100 =	SECAM ITU-R B	T.601					

With the autoswitch code running, the user can force the device to operate in a particular video standard mode and sample rate by writing the appropriate value into this register.

## 7.2.38 Active Video Cropping Stop Pixel MSB for Scaled Data Register

Address Default	29h 00h										
7	6	5	4	3	2	1	0				
	AVID stop pixel MSB [9:2]										

Active video cropping stop pixel MSB [9:2], set this register first before setting the register 2Ah. The TVP5154A decoder updates the AVID stop values only when register 2Ah is written to. This stop pixel value is relative to the default values of the AVID stop pixel.

### 7.2.39 Active Video Cropping Stop Pixel LSB for Scaled Data Register

Address	2Ah						
Default	00h						
7	6	5	4	3	2	1	0
		Res	erved			AVID stop pi	xel LSB [1:0]
AVID stop [9:0]:							
01 111	11 1111 = 511						
00 000	1000001 = 1						
00 000	00 0000 = 0 (defau	ult) (see Figure 3-	4, Figure 3-5, and	Figure 3-6)			
11 111	11 1111 = -1						
10 000	$00\ 0000 = -512$						

Active video cropping stop pixel LSB [1:0]: The number of pixels of active video must be an even number. The TVP5154A decoder updates the AVID stop values only when this register is written to.



### 7.2.40 Cb Gain Factor Register

			Cb gai	n factor			
7	6	5	4	3	2	1	0
Address	2Ch						

This is a read-only register that provides the gain applied to the Cb in the YCbCr data stream.

## 7.2.41 Cr Gain Factor Register

Address	2Dh									
7	6	5	4	3	2	1	0			
	Cr gain factor									

This is a read-only register that provides the gain applied to the Cr in the YCbCr data stream.

## 7.2.42 656 Revision Select Register

Address Default	30h 00h						
7	6	5	4	3	2	1	0
							656 Rev

656 revision select:

0 = Adheres to ITU-R BT.656-4 and BT.656-5 timing (default)

1 = Adheres to ITU-R BT.656-3 timing

## 7.2.43 MSB of Device ID Register

Address Default	80h 51h										
7	6	5	4	3	2	1	0				
	MSB of device ID										

This register identifies the MSB of the device ID. Value = 0x51.

## 7.2.44 Patch Write Address

Address Default	7Eh 00h										
7	6	5	4	3	2	1	0				
	R/W[7:0]										

This register is used for downloading firmware patch code. Please refer to the patch load application note for more detail. This register must not be written to or read from during normal operation.



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#### 7.2.45 Patch Code Execute

Address Default	7Fh 00h										
7	6	5	4	3	2	1	0				
	R/W[7:0]										

Writing to this register following a firmware patch load restarts the CPU and initiates execution of the patch code. This register must not be written to or read from during normal operation.

### 7.2.46 LSB of Device ID Register

Default	54h										
7	6	5	4	3	2	1	0				
	LSB of device ID										

This register identifies the LSB of the device ID. Value = 0x54.

### 7.2.47 ROM Major Version Register

Address Default	82h 02h										
7	6	5	4	3	2	1	0				
	ROM major version <sup>(1)</sup>										

(1) This register can contain a number from 0x01 to 0xFF.

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## 7.2.48 ROM Minor Version Register

Address Default	83h 00h										
7	6	5	4	3	2	1	0				
	ROM minor version <sup>(1)</sup>										

(1) This register can contain a number from 0x01 to 0xFF.

## 7.2.49 Vertical Line Count MSB Register

Address	84h						
7	6	5	4	3	2	1	0
		Vertical line	count MSB				

Vertical line count bits [9:8]

## 7.2.50 Vertical Line Count LSB Register

Address	85h							
7	6	5	4	3	2	1	0	
Vertical line count LSB								

Vertical line count bits [7:0]

Registers 84h and 85h can be read and combined to extract the detected number of lines per frame. This can be used with nonstandard video signals, such as a VCR in fast-forward or rewind modes, to synchronize the downstream video circuitry.



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## 7.2.51 Interrupt Status Register B

Address	86h

7	6	5	4	3	2	1	0
Software initialization	Reserved	Command ready	Field rate changed	Line alternation changed	Color lock changed	H/V lock changed	TV/VCR changed

Software initialization:

0 = Software initialization is not ready (default).

1 = Software initialization is ready.

Command ready:

0 = TVP5154A is not ready to accept a new command (default).

1 = TVP5154A is ready to accept a new command.

Field rate changed:

0 = Field rate has not changed (default).

1 = Field rate has changed.

Line alternation changed:

0 = Line alteration has not changed (default).

1 = Line alternation has changed.

Color lock changed:

0 = Color lock status has not changed (default).

1 = Color lock status has changed.

H/V lock changed:

0 = H/V lock status has not changed (default).

1 = H/V lock status has changed.

TV/VCR changed:

0 = TV/VCR status has not changed (default).

1 = TV/VCR status has changed.

Interrupt status register B is polled by the external processor to determine the interrupt source for interrupt B. After an interrupt condition is set, it can be reset by writing to the interrupt reset register B at subaddress 1Ch with a 1 in the appropriate bit.



### 7.2.52 Interrupt Active Register B

Address	87h							
7	6	5	4	3	2	1	0	
	Reserved							

Interrupt B:

0 = Interrupt B is not active on the external terminal (default).

1 = Interrupt B is active on the external terminal.

The interrupt active register B is polled by the external processor to determine if interrupt B is active.

### 7.2.53 Status Register #1

88h

Address

7	6	5	4	3	2	1	0
Peak white	Line-alternating	Field rate	Lost lock	Color subcarrier	Vertical sync	Horizontal sync	TV/VCR
detect status	status	status	detect	lock status	lock status	lock status	status

Peak white detect status:

0 = Peak white is not detected.

1 = Peak white is detected.

Line-alternating status:

0 = Nonline alternating

1 = Line alternating

Field rate status:

0 = 60 Hz

1 = 50 Hz

Lost lock detect:

0 = No lost lock since status register #1 was last read

1 = Lost lock since status register #1 was last read

Color subcarrier lock status:

0 = Color subcarrier is not locked.

1 = Color subcarrier is locked.

Vertical sync lock status:

0 = Vertical sync is not locked.

1 = Vertical sync is locked.

Horizontal sync lock status:

0 = Horizontal sync is not locked.

1 = Horizontal sync is locked.

TV/VCR status. TV mode is determined by detecting standard line-to-line variations and specific chroma SCH phases based on the standard input video format. VCR mode is determined by detecting variations in the chroma SCH phases compared to the chroma SCH phases of the standard input video format.

0 = TV

1 = VCR



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### 7.2.54 Status Register #2

Address	89h						
7	6	5	4	3	2	1	0
Reserved	Weak signal detection	PAL switch polarity	Field sequence status	AGC and offset frozen status	F	Reserve	ed
Weak signa	I detection:						
0 :	<ul> <li>No weak signal</li> </ul>						
1 :	<ul> <li>Weak signal mode</li> </ul>						
PAL switch	polarity of first line of odd	I field:					
0 :	= PAL switch is 0.						
1 :	= PAL switch is 1.						
Field seque	ence status:						
0 :	<ul> <li>Even field</li> </ul>						
1 :	<ul> <li>Odd field</li> </ul>						
AGC and of	ffset frozen status:						
0	ACC and affect and as	+ f=====					

0 = AGC and offset are not frozen.

1 = AGC and offset are frozen.

## 7.2.55 Status Register #3

Address 8Ah

7	6	5	4	3	2	1	0
	Analo	g gain			Digita	al gain	

Analog gain: 4-bit front-end AGC analog gain setting

Digital gain: 4 MSBs of 6-bit front-end AGC digital gain setting

The product of the analog and digital gain is given below.

Gain Product = (1 + 3 × analog\_gain/15) × (1 + gain\_step × digital\_gain/4096)

Where,

 $0 \le analog_gain \le 15$ 

 $0 \le \text{digital}_{\text{gain}} \le 63$ 

The gain\_step setting as a function of the analog\_gain setting is shown below.

analog_gain	gain_step
0	61
1	55
2	48
3	44
4	38
5	33
6	29
7	26
8	24
9	22
10	20
11	19
12	18
13	17
14	16
15	15

## 7.2.56 Status Register #4

Address	8Bh						
7	6	5	4	3	2	1	0
			Subcarrier to horizo	ontal (SCH) phase	e		
SCH (color PL	L subcarrier phase a	at 50% of the falli	ng edge of horizont	al sync of line on	e of odd field; ste	p size 360°/256):	
0000	$0000 = 0.00^{\circ}$						
0000	$0001 = 1.41^{\circ}$						
0000	$0010 = 2.81^{\circ}$						
1111	1110 = 357.2°						
1111	1111 = 358.6°						

## 7.2.57 Status Register #5

Address 8Ch							
7	6	5	4	3	2	1	0
Autoswitch mode		Reserved			Video standard		Sampling rate

Autoswitch mode:

0 = Stand-alone (forced video standard) mode

1 = Autoswitch mode

This register contains information about the detected video standard and the sampling rate at which the device is currently operating. When autoswitch code is running, this register must be tested to determine which video standard has been detected.

VID	EO STANDARD	[3:1]	SR <sup>(1)</sup>	VIDEO STANDARD
BIT 3	BIT 2	BIT 1	BIT 0	
0	0	0	0	Reserved
0	0	0	1	(M, J) NTSC ITU-R BT.601
0	0	1	0	Reserved
0	0	1	1	(B, G, H, I, N) PAL ITU-R BT.601
0	1	0	0	Reserved
0	1	0	1	(M) PAL ITU-R BT.601
0	1	1	0	Reserved
0	1	1	1	PAL-Nc ITU-R BT.601
1	0	0	0	Reserved
1	0	0	1	NTSC 4.43 ITU-R BT.601
1	0	1	0	Reserved
1	0	1	1	SECAM ITU-R BT.601

#### Table 7-10. Auto Switch Video Standard

(1) Sampling rate (SR): 0 = Reserved, 1 = ITU-R BT.601



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### 7.2.58 Patch Read Address

Address Default	8Eh 00h						
7	6	5	4	3	2	1	0
			R/W	/[7:0]			

This register can be used for patch code read-back. This register must not be written to or read from during normal operation.

## 7.2.59 Closed Caption Data Registers

Address	90h–93h										
Address	7	6	5	4	3	2	1	0			
90h		Closed caption field 1 byte 1									
91h				Closed captio	on field 1 byte 2						
92h		Closed caption field 2 byte 1									
93h				Closed captio	on field 2 byte 2						

These registers contain the closed caption data arranged in bytes per field.

# 7.2.60 WSS/CGMS-A Data Registers

Address 94h–99h

### NTSC

Address	7	6	5	4	3	2	1	0	BYTE
94h			b5	b4	b3	b2	b1	b0	WSS field 1 byte 1
95h	b13	b12	b11	b10	b9	b8	b7	b6	WSS field 1 byte 2
96h			b19	b18	b17	b16	b15	b14	WSS field 1 byte 3
97h			b5	b4	b3	b2	b1	b0	WSS field 2 byte 1
98h	b13	b12	b11	b10	b9	b8	b7	b6	WSS field 2 byte 2
99h			b19	b18	b17	b16	b15	b14	WSS field 2 byte 3

These registers contain the wide screen signaling (WSS/CGMS-A) data for NTSC.

Bits 0–1 represent word 0, aspect ratio.

Bits 2-5 represent word 1, header code for word 2.

Bits 6-13 represent word 2, copy control.

Bits 14-19 represent word 3, CRC.

### PAL/SECAM

Address	7	6	5	4	3	2	1	0	BYTE
94h	b7	b6	b5	b4	b3	b2	b1	b0	WSS field 1 byte 1
95h			b13	b12	b11	b10	b9	b8	WSS field 1 byte 2
96h									
97h	b7	b6	b5	b4	b3	b2	b1	b0	WSS field 2 byte 1
98h			b13	b12	b11	b10	b9	b8	WSS field 2 byte 2
99h									

Bits 0–3 represent group 1, aspect ratio.

Bits 4-7 represent group 2, enhanced services.

Bits 8–10 represent group 3, subtitles.

Bits 11–13 represent group 4, others.



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## 7.2.61 VPS/Gemstar 2x Data Registers

Address	9Ah–A6h												
Address	7	6	5	4	3	2	1	0					
9Ah				VPS/Gem	star 2x byte 1								
9Bh				VPS/Gem	star 2x byte 2								
9Ch				VPS/Gem	star 2x byte 3								
9Dh		VPS/Gemstar 2x byte 4											
9Eh				VPS/Gem	star 2x byte 5								
9Fh				VPS/Gem	star 2x byte 6								
A0h				VPS/Gem	star 2x byte 7								
A1h				VPS/Gem	star 2x byte 8								
A2h				VPS/Gem	star 2x byte 9								
A3h				VPS/Gems	star 2x byte 10								
A4h		VPS/Gemstar 2x byte 11											
A5h				VPS/Gems	star 2x byte 12								
A6h				VPS/Gems	star 2x byte 13								

When PAL VPS is used, these registers contain the entire VPS data line except the clock run-in code and the start code. When NTSC Gemstar 2x is used, these registers contain the Gemstar 2x data.

## 7.2.62 VITC Data Registers

Address	A7h–AFh												
Address	7	6	5	4	3	2	1	0					
A7h				VITC byte 1	, frame byte 1								
A8h				VITC byte 2	, frame byte 2								
A9h		VITC byte 3, seconds byte 1											
AAh		VITC byte 4, seconds byte 2											
ABh				VITC byte 5,	minutes byte 1								
ACh				VITC byte 6,	minutes byte 2								
ADh		VITC byte 7, hour byte 1											
AEh		VITC byte 8, hour byte 2											
AFh				VITC by	rte 9, CRC								

These registers contain the VITC data.

## 7.2.63 VBI FIFO Read Data Register



This address is provided to access VBI data in the FIFO through the host port. All forms of teletext data come directly from the FIFO, while all other forms of VBI data can be programmed to come from the registers or from the FIFO. Current status of the FIFO can be found at address C6h and the number of bytes in the FIFO is located at address C7h. If the host port is to be used to read data from the FIFO, the output formatter must be disabled at address CDh bit 0. The format used for the VBI FIFO is shown in Section 3.9.

# 7.2.64 Teletext Filter and Mask Registers

Address Default	B1h–BAh 00h												
Address	7	6	5	4	3	2	1	0					
B1h		Filter 1 mask 1 Filter 1 pattern 1											
B2h		Filter 1	mask 2		Filter 1 pattern 2								
B3h		Filter 1	mask 3			Filter 1	pattern 3						
B4h		Filter 1	mask 4			Filter 1	pattern 4						
B5h		Filter 1	mask 5			Filter 1	pattern 5						
B6h		Filter 2	mask 1		Filter 2 pattern 1								
B7h		Filter 2	mask 2			Filter 2	pattern 2						
B8h		Filter 2	mask 3		Filter 2 pattern 3								
B9h		Filter 2	mask 4		Filter 2 pattern 4								
BAh		Filter 2	mask 5		Filter 2 pattern 5								

For an	NABTS syster	m, the packet	prefix consists	s of five bytes.	Each byte co	ntains four dat	a bits (D[3:0])
interlac	ed wi	th fou	ur Hai	mming	protection	bits	(H[3:0]):
				0	•		
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
D[3]	H[3]	D[2]	H[2]	D[1]	H[1]	D[0]	H[0]

Only the data portion D[3:0] from each byte is applied to a teletext filter function with the corresponding pattern bits P[3:0] and mask bits M[3:0]. Hamming protection bits are ignored by the filter.

For a WST system (PAL or NTSC), the packet prefix consists of two bytes so that two patterns are used. Patterns 3, 4, and 5 are ignored.

The mask bits enable filtering using the corresponding bit in the pattern register. For example, a 1 in the LSB of mask 1 means that the filter module must compare the LSB of nibble 1 in the pattern register to the first data bit on the transaction. If these match, a true result is returned. A 0 in a bit of mask 1 means that the filter module must ignore that data bit of the transaction. If all zeros are programmed in the mask bits, the filter matches all patterns returning a true result (default 00h).

Pattern and mask for each byte and filter are referred as <1,2><P,M><1,2,3,4,5> where:

<1,2> identifies the filter 1 or 2

<P,M> identifies the pattern or mask

<1,2,3,4,5> identifies the byte number



#### 7.2.65 Teletext Filter Control Register

Address	BBh						
Default	00h						
7	6	5	4	3	2	1	0
	Reserved		Filte	r logic	Mode	TTX filter 2 enable	TTX filter 1 enable
Filter logic:	Allows differe	ent logic to b	e applied wh	en combining	the decision of fil	ter 1 and filter 2 as follows:	
00	= NOR (defa	ult)					
01	= NAND						
10	= OR						
11 :	= AND						
Mode:							
0	= Teletext W	ST PAL mod	de B (2 head	er bytes) (defa	ault)		
1	= Teletext N	ABTS NTSC	mode C (5 ł	neader bytes)			
TTX filter 2	enable:						
0	= Disabled (	default)					
1 :	= Enabled						
TTX filter 1	enable:						

- 0 = Disabled (default)
- 1 = Enabled

If the filter matches or if the filter mask is all zeros, a true result is returned.

#### 7.2.66 Interrupt Status Register A

Address	C0h
Dofoult	00h

D	elault 00	11						
	7	6	5	4	3	2	1	0
	Lock state interrupt	Lock interrupt		Reserved		FIFO threshold interrupt	Line interrupt	Data interrupt

Lock state interrupt:

0 = TVP5154A is not locked to the video signal (default)

1 = TVP5154A is locked to the video signal.

Lock interrupt:

0 = A transition has not occurred on the lock signal (default).

1 = A transition has occurred on the lock signal.

FIFO threshold interrupt:

0 = The amount of data in the FIFO has not yet crossed the threshold programmed at address C8h (default).

1 = The amount of data in the FIFO has crossed the threshold programmed at address C8h.

Line interrupt:

0 = The video line number has not yet been reached (default).

1 = The video line number programmed in address CAh has occurred.

Data interrupt:

0 = No data is available (default).

1 = VBI data is available either in the FIFO or in the VBI data registers.

The interrupt status register A can be polled by the host processor to determine the source of an interrupt. After an interrupt condition is set it can be reset by writing to this register with a 1 in the appropriate bit(s).

# 7.2.67 Interrupt Enable Register A

Address	C1h						
Default	00h						
7	6	5	4	3	2	1	0
Reserved	Lock interrupt enable	Cycle complete interrupt enable	Bus error interrupt enable	Reserved	FIFO threshold interrupt enable	Line interrupt enable	Data interrupt enable
Lock interrupt	enable:						
0 =	Disabled (defaul	lt)					
1 =	Enabled						
Cycle complete	e interrupt enabl	le:					
0 =	Disabled (defaul	lt)					
1 =	Enabled						
Bus error inter	rupt enable:						
0 =	Disabled (defaul	lt)					
1 =	Enabled						
FIFO threshold	d interrupt enabl	e:					
0 =	Disabled (defaul	lt)					
1 =	Enabled						
Line interrupt e	enable:						
0 =	Disabled (defaul	lt)					
1 =	Enabled						
Data interrupt	enable:						
0 =	Disabled (defaul	lt)					
1 =	Enabled						

Ine interrupt enable register A is used by the nost processor to mask unnecessary interrupt sources. Bits loaded with a 1 allow the corresponding interrupt condition to generate an interrupt on the external pin. Conversely, bits loaded with a 0 mask the corresponding interrupt condition from generating an interrupt on the external pin. This register only affects the interrupt on the external terminal, it does not affect the bits in interrupt status register A. A given condition can set the appropriate bit in the status register and not cause an interrupt on the external terminal. To determine if this device is driving the interrupt terminal either perform a logical AND of interrupt status register A with interrupt enable register A, or check the state of the interrupt A bit in the interrupt configuration register at address C2h.



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#### 7.2.68 Interrupt Configuration Register A

Address Default		C2h 04h					
7	6	5	4	3	2	1	0
		Reserved			YCbCr enable (VDPOE)	Interrupt A	Interrupt polarity A

YCbCr enable (VDPOE):

0 = YCbCr pins are high impedance.

1 = YCbCr pins are active if other conditions are met (default).

Interrupt A (read only):

0 = Interrupt A is not active on the external pin (default).

1 = Interrupt A is active on the external pin.

Interrupt polarity A:

0 = Interrupt A is active low (default).

1 = Interrupt A is active high.

Interrupt configuration register A is used to configure the polarity of the external interrupt terminal. When interrupt A is configured as active low, the terminal is driven low when active and high impedance when inactive (open collector). Conversely, when the terminal is configured as active high, it is driven high when active and driven low when inactive.

#### 7.2.69 VDP Configuration RAM Register

Address Default	C3h B8h	C4h 1Fh	C5h 00h									
Address	7	6	5	4	3	2	1	0				
C3h		Configuration data										
C4h		RAM address (7:0)										
C5h		Reserved RAM address 8										

The configuration RAM data is provided to initialize the VDP with initial constants. The configuration RAM is 512 bytes organized as 32 different configurations of 16 bytes each. The first 12 configurations are defined for the current VBI standards. An additional two configurations can be used as a custom programmed mode for unique standards, such as Gemstar.

Address C3h is used to read or write to the RAM. The RAM internal address counter is automatically incremented with each transaction. Addresses C5h and C4h make up a 9-bit address to load the internal address counter with a specific start address. This can be used to write a subset of the RAM for only those standards of interest. Registers D0h–FBh must all be programmed with FFh before writing or reading the configuration RAM. Full field mode (CFh) must be disabled as well.

The suggested RAM contents are shown in Table 7-11. All values are hexadecimal.

INDEX	ADDRESS	0	1	2	3	4	5	6	7	8	9	Α	В	С	D	Е	F
WST SECAM	000	AA	AA	FF	FF	E7	2E	20	A6	E4	B4	0E	0	7	0	10	0
WST SECAM	010	AA	AA	FF	FF	E7	2E	20	A6	E4	B4	0E	0	7	0	10	0
WST PAL B	020	AA	AA	FF	FF	27	2E	20	AB	A4	72	10	0	7	0	10	0
WST PAL B	030	AA	AA	FF	FF	27	2E	20	AB	A4	72	10	0	7	0	10	0
WST PAL C	040	AA	AA	FF	FF	E7	2E	20	22	A4	98	0D	0	0	0	10	0
WST PAL C	050	AA	AA	FF	FF	E7	2E	20	22	A4	98	0D	0	0	0	10	0
WST NTSC	060	AA	AA	FF	FF	27	2E	20	23	63	93	0D	0	0	0	10	0
WST NTSC	070	AA	AA	FF	FF	27	2E	20	23	63	93	0D	0	0	0	10	0
NABTS, NTSC	080	AA	AA	FF	FF	E7	2E	20	A2	63	93	0D	0	7	0	15	0

#### Table 7-11. VBI Configuration RAM for Signals With Pedestal

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Table 7-11. VBI Configuration RAM for Signals with Pedestal (continued)																	
INDEX	ADDRESS	0	1	2	3	4	5	6	7	8	9	Α	в	С	D	Е	F
NABTS, NTSC	090	AA	AA	FF	FF	E7	2E	20	A2	63	93	0D	0	7	0	15	0
NABTS, NTSC-J	0A0	AA	AA	FF	FF	A7	2E	20	A3	63	93	0D	0	7	0	10	0
NABTS, NTSC-J	0B0	AA	AA	FF	FF	A7	2E	20	A3	63	93	0D	0	7	0	10	0
CC, PAL/SECAM	0C0	AA	2A	FF	3F	04	51	6E	02	A4	7B	09	0	0	0	27	0
CC, PAL/SECAM	0D0	AA	2A	FF	3F	04	51	6E	02	A4	7B	09	0	0	0	27	0
CC, NTSC	0E0	AA	2A	FF	3F	04	51	6E	02	63	8C	09	0	0	0	27	0
CC, NTSC	0F0	AA	2A	FF	3F	04	51	6E	02	63	8C	09	0	0	0	27	0
WSS/CGMS-A, PAL/SECAM	100	5B	55	C5	FF	0	71	6E	42	A4	CD	0F	0	0	0	ЗA	0
WSS/CGMS-A, PAL/SECAM	110	5B	55	C5	FF	0	71	6E	42	A4	CD	0F	0	0	0	ЗA	0
WSS/CGMS-A, NTSC C	120	38	00	3F	00	0	71	6E	43	63	7C	08	0	0	0	39	0
WSS/CGMS-A, NTSC C	130	38	00	3F	00	0	71	6E	43	63	7C	08	0	0	0	39	0
VITC, PAL/SECAM	140	0	0	0	0	0	8F	6D	49	A4	85	08	0	0	0	4C	0
VITC, PAL/SECAM	150	0	0	0	0	0	8F	6D	49	A4	85	08	0	0	0	4C	0
VITC, NTSC	160	0	0	0	0	0	8F	6D	49	63	94	08	0	0	0	4C	0
VITC, NTSC	170	0	0	0	0	0	8F	6D	49	63	94	08	0	0	0	4C	0
VPS, PAL	180	AA	AA	FF	FF	BA	CE	2B	8D	A4	DA	0B	0	7	0	60	0
VPS, PAL	190	AA	AA	FF	FF	BA	CE	2B	8D	A4	DA	0B	0	7	0	60	0
Gemstar 2x Custom 1	1A0	99	99	FF	FF	05	51	6E	05	63	18	13	80	00	00	60	00
Gemstar 2x Custom 1	1B0	99	99	FF	FF	05	51	6E	05	63	18	13	80	00	00	60	00
Custom 2	1C0		•	•	•	•	•		Progra	nmable	e	•	•	•	•	•	•
Custom 2	1D0	Programmable															

## Table 7-11. VBI Configuration RAM for Signals With Pedestal (continued)



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### 7.2.70 VDP Status Register

Address	C6h						
7	6	5	4	3	2	1	0
FIFO full error	FIFO empty	TTX available	CC field 1 available	CC field 2 available	WSS/CGMS-A available	VPS/Gemstar 2x available	VITC available

The VDP status register indicates whether data is available in either the FIFO or data registers, and status information about the FIFO. Reading data from the corresponding register does not clear the status flags automatically. These flags are only reset by writing a 1 to the respective bit. However, bit 6 is updated automatically.

FIFO full error:

0 = No FIFO full error

1 = FIFO was full during a write to FIFO.

The FIFO full error flag is set when the current line of VBI data can not enter the FIFO. For example, if the FIFO has only ten bytes left and teletext is the current VBI line, the FIFO full error flag is set, but no data is written because the entire teletext line will not fit. However, if the next VBI line is closed caption requiring only two bytes of data plus the header, this goes into the FIFO (even if the full error flag is set).

FIFO empty:

- 0 = FIFO is not empty.
- 1 = FIFO is empty.

TTX available:

- 0 = Teletext data is not available.
- 1 = Teletext data is available.

CC field 1 available:

- 0 = Closed caption data from field 1 is not available.
- 1 = Closed caption data from field 1 is available.

CC field 2 available:

- 0 = Closed caption data from field 2 is not available.
- 1 = Closed caption data from field 2 is available.
- WSS/CGMS-A available:
  - 0 = WSS/CGMS-A data is not available.
  - 1 = WSS/CGMS-A data is available.
- VPS/Gemstar 2x available
  - 0 = VPS/Gemstar 2x data is not available.

1 = VPS/Gemstar 2x data is available.

VITC available:

- 0 = VITC data is not available.
- 1 = VITC data is available.

## 7.2.71 FIFO Word Count Register

Address	C7h								
7	6	5	4	3	2	1	0		
Number of words									

This register provides the number of words in the FIFO. One word equals two bytes.

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## 7.2.72 FIFO Interrupt Threshold Register

Address Default	C8h 80h								
7	6	5	4	3	2	1	0		
	Number of words								

This register is programmed to trigger an interrupt when the number of words in the FIFO exceeds this value (default 80h). This interrupt must be enabled at address C1h. One word equals two bytes.

## 7.2.73 FIFO Reset Register

Address Default	C9h 00h								
7	6	5	4	3	2	1	0		
	Any data								

Writing any data to this register resets the FIFO and clears any data present in both the FIFO and the VDP registers.

## 7.2.74 Line Number Interrupt Register

Address Default	CAh 00h							
7	6	5	4	3	2	1	0	
Field 1 enable	Field 2 enable	Line number						

This register is programmed to trigger an interrupt when the video line number matches this value in bits 5:0. This interrupt must be enabled at address C1h. The value of 0 or 1 does not generate an interrupt.

Field 1 enable:

0 = Disabled (default)

1 = Enabled

Field 2 enable:

0 = Disabled (default)

1 = Enabled

Line number: (default 00h)

## 7.2.75 Pixel Alignment Registers

Address	CBh	CCh							
Default	4Eh	00h							
Address	7	6	5	4	3	2	1	0	
CBh		Switch pixel [7:0]							
CCh	Reserved Switch pixel [9:8]								

These registers form a 10-bit horizontal pixel position from the falling edge of sync, where the VDP controller initiates the program from one line standard to the next line standard; for example, the previous line of teletext to the next line of closed caption. This value must be set so that the switch occurs after the previous transaction has cleared the delay in the VDP, but early enough to allow the new values to be programmed before the current settings are required.

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## 7.2.76 FIFO Output Control Register

Address	CDh						
Default	01h						
7	6	5	4	3	2	1	0
		Host access enable					

This register is programmed to allow  $I^2C$  access to the FIFO or allowing all VDP data to go out the video port. Host access enable:

0 = Output FIFO data to the video output Y[7:0]

1 = Allow I<sup>2</sup>C access to the FIFO data (default)

### 7.2.77 Full Field Enable Register

Address	CFh								
Default	00h								
7	6	5	4	3	2	1	0		
	Reserved								

This register enables the full field mode. In this mode, all lines outside the vertical blank area and all lines in the line mode registers programmed with FFh are sliced with the definition of register FCh. Values other than FFh in the line mode registers allow a different slice mode for that particular line.

Full field enable:

- 0 = Disable full field mode (default)
- 1 = Enable full field mode



# 7.2.78 Line Mode Registers

Address Default	D0h 00h	D1h–FBh FFh										
Address	7	6	5	4	3	2	1	0				
D0h		Line 6 Field 1										
D1h		Line 6 Field 2										
D2h		Line 7 Field 1										
D3h		Line 7 Field 2										
D4h		Line 8 Field 1										
D5h				Line	8 Field 2							
D6h				Line	9 Field 1							
D7h				Line	9 Field 2							
D8h				Line	10 Field 1							
D9h				Line	10 Field 2							
DAh				Line	11 Field 1							
DBh					11 Field 2							
DCh				Line	12 Field 1							
DDh				Line	12 Field 2							
DEh				Line	13 Field 1							
DFh				Line	13 Field 2							
E0h				Line	14 Field 1							
E1h				Line	14 Field 2							
E2h				Line	15 Field 1							
E3h				Line	15 Field 2							
E4h				Line	16 Field 1							
E5h				Line	16 Field 2							
E6h				Line	17 Field 1							
E7h				Line	17 Field 2							
E8h				Line	18 Field 1							
E9h				Line	18 Field 2							
EAh				Line	19 Field 1							
EBh				Line	19 Field 2							
ECh				Line	20 Field 1							
EDh				Line	20 Field 2							
EEh				Line	21 Field 1							
EFh				Line	21 Field 2							
F0h				Line	22 Field 1							
F1h				Line	22 Field 2							
F2h				Line	23 Field 1							
F3h				Line	23 Field 2							
F4h				Line	24 Field 1							
F5h				Line	24 Field 2							
F6h				Line	25 Field 1							
F7h				Line	25 Field 2							
F8h				Line	26 Field 1							
F9h				Line	26 Field 2							
FAh				Line	27 Field 1							
FBh				Line	27 Field 2							

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These registers program the specific VBI standard at a specific line in the video field.

- Bit 7:
- 0 = Disable filtering of null bytes in closed caption modes.
- 1 = Enable filtering of null bytes in closed caption modes (default).

In teletext modes, bit 7 enables the data filter function for that particular line. If it is set to 0, the data filter passes all data on that line.

Bit 6:

- 0 = Send VBI data to registers only.
- 1 = Send VBI data to FIFO and the registers. Teletext data only goes to FIFO. (default)

Bit 5:

- 0 = Allow VBI data with errors in the FIFO.
- 1 = Do not allow VBI data with errors in the FIFO (default).

Bit 4:

- 0 = Do not enable error detection and correction.
- 1 = Enable error detection and correction (when bits [3:0] = 1 2, 3, and 4 only) (default).

Bits [3:0]:

- 0000 = WST SECAM
- 0001 = WST PAL B
- 0010 = WST PAL C
- 0011 = WST NTSC
- 0100 = NABTS NTSC C
- 0101 = NABTS NTSC D
- 0110 = CC PAL
- 0111 = CC NTSC
- 1000 = WSS/CGMS-A PAL
- 1001 = WSS/CGMS-A NTSC
- 1010 = VITC PAL
- 1010 = VITC NTSC
- 1100 = VPS PAL
- 1100 = VPS PAL
- 1101 = Gemstar 2x Custom 1
- 1110 = Custom 2
- 1111 = Active video (VDP off) (default)

A value of FFh in the line mode registers is required for any line to be sliced as part of the full field mode.



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#### 7.2.79 Full Field Mode Register

Address Default	FCh 7Fh										
7	6	5	4	3	2	1	0				
	Full field mode										

This register programs the specific VBI standard for full field mode. It can be any VBI standard. Individual line settings take priority over the full field register. This allows each VBI line to be programmed independently but have the remaining lines in full field mode. The full field mode register has the same definitions as the line mode registers (default 7Fh).

#### 7.2.80 Decoder Write Enable Register

Address Default	FEh 0Fh						
7	6	5	4	3	2	1	0
	Rese	erved		Decoder 4	Decoder 3	Decoder 2	Decoder 1

This register controls which of the four decoder cores receives  $I^2C$  write transactions. A 1 in the corresponding bit position enables the decoder to receive write commands.

Any combination of decoders can be configured to receive write commands, allowing all four decoders to be programmed concurrently.

#### 7.2.81 Decoder Read Enable Register

Address Default	FFh 00h						
7	6	5	4	3	2	1	0
	Res	erved		Decoder 4	Decoder 3	Decoder 2	Decoder 1

This register controls which of the four decoder cores responds to  $I^2C$  read transactions. A 1 in the corresponding bit position enables the decoder to respond to read commands.

If more than one decoder is enabled for reading, only the lowest numbered decoder responds. Reads from multiple decoders at the same time is not possible.

Note that when register 0xFE is written to with any value, register 0xFF is set to 0x00. Likewise, when register 0xFF is written to with any value, register 0xFE is set to 0x00.



#### 7.3 Indirect Register Definitions

To write to the TVP5154A indirect registers, it is required that the registers be unlocked using a password. The password prevents undesirable writes into the device at start-up due to power surges, for example.

The following example demonstrates the method for unlocking the indirect registers.

After writing to the desired indirect registers described in the following text, it is recommended that the device be locked again.

- Unlock the device
  - 1. Write 0x51 to I2C\_0x21. //MSB data
  - 2. Write 0x54 to I2C\_0x22. //LSB data
  - 3. Write 0xFF to I2C\_0x23. //Data address
  - 4. Write 0x04 to I2C\_0x24. //Write command
- Lock the device
  - 1. Write 0x00 to I2C\_0x21. //MSB data
  - 2. Write 0x00 to I2C\_0x22. //LSB data
  - 3. Write 0xFF to I2C\_0x23. //Data address
  - 4. Write 0x04 to I2C\_0x24. //Write command

Indirect registers are written to by performing the following I<sup>2</sup>C transaction:

START : DEVICE\_ID\_w : 0x21 : DATA\_HIGH : STOP

START : DEVICE\_ID\_w : 0x22 : DATA\_LOW : STOP

START : DEVICE\_ID\_w : 0x23 : ADDRESS\_LOW : STOP

START : DEVICE\_ID\_w : 0x24 : WR\_STROBE : STOP

To read from an indirect register, the following I<sup>2</sup>C transaction should be performed:

START : DEVICE\_ID\_w : 0x23 : ADDRESS\_LOW : STOP

START : DEVICE\_ID\_w : 0x24 : RD\_STROBE : STOP

START : DEVICE\_ID\_r : 0x21 : data\_msb : STOP

START : DEVICE\_ID\_r : 0x22 : data\_lsb : STOP

Where:

DEVICE\_ID\_w is the selected TVP5154A device ID with the read/write bit (LSB) set to write.

DEVICE\_ID\_r is the selected TVP5154A device ID with the read/write bit (LSB) set to read.

ADDRESS\_LOW is the low byte of the register address.

WR\_STROBE is 0x06.

RD\_STROBE is 0x05.

Note, the upper byte of the address is not directly used but is replaced by the corresponding STROBE signal.

Each indirect register is 16 bits wide.

# 7.3.1 DID Control

Address Default	36Ah 000h								
7	6	5	4	3	2	1	0		
	Unscaled field 1 DI	D		Unscaled field 0 DID					
15	14	13	12	11	10	9	8		
	Scaled field 1 DID				Scaled field 0 DID				

This register controls the value of the EAV DID bytes for scaled and unscaled data. The value for each field can be independently set, allowing identification of both which field is being processed and whether the data comes from the scaled or unscaled channel.

## 7.3.2 Misc Control

Address Default	36Bh 0Ch						
7	6	5	4	3	2	1	0
	Clock rate				k OE	Cloc	k edge
15	14	13	12	11	10	9	8

Scaled blank data

Scaled blank data:

When no active scaled data is available, this value is output during the active video region.

Clock rate:

This register controls various clock modes. Since this register is modified by the device during normal operation, the clock rate bits should not be modified by the user.

Clock OE:

This register controls various clock modes. Since this register is modified by the device during normal operation, the clock rate bits should not be modified by the user.

Clock edge:

This register controls various clock modes. Since this register is modified by the device during normal operation, the clock rate bits should not be modified by the user.

## 7.3.3 Interleave Field Control 1

Address	36Dh						
Default	0h						
7	6	5	4	3	2	1	0
			End pixel	count[7:0]			
15	14	13	12	11	10	9	8
	Field	count		Reserved	Blank timing	End pixel	count[9:8]

End pixel count:

Pixel count at which the frame status is updated. Do not change this value.

Blank timing:

- 0: No timing signals are generated for blank fields.
- 1: H, V, and F timing generated for blank fields based on unscaled video timing sequences

Field count:

Number of output fields in field interleaved sequence



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#### 7.3.4 Interleave Field Control 2

Field mode(7)		Field mode(6)		Field mode(5)		Field mode(4)			
15	14	13	12	11	10	9	8		
Field	d mode(3)	Field r	node(2)	bde(2) Field mode(1)			Field mode(0)		
7	6	5	4	3	2	1	0		
Default	0h								
Address	36Eh								

## 7.3.5 Interleave Field Control 3

Address	36Fh
Default	0h

7	6	5	4	3	2	1	0
Field ı	mode(11)	Field m	Field mode(10) Field mo		ode(9) Field mode(8)		node(8)
15	14	13	12	11	10	9	8
Field ı	Field mode(15) Field mode(14)		Field mode(13)		Field mode(12)		

These registers allow the output data stream to toggle between unscaled and scaled data on a field basis. By setting Field mode[n] appropriately, it is possible to use the available output bandwidth to interleave unscaled and scaled frames to achieve reduced frame rates, while still maintaining compatibility with legacy data receivers. These registers can also be used to reduce the frame rate of either unscaled data or scaled data by disabling fields within the sequence.

A counter automatically moves from Field mode[0] to Field mode[n] where n can be 0 through 15, then returns back to Field mode[0]. Depending on the value of Field mode[n], either unscaled data, scaled data, or no data is sent for the current frame.

- 00 = Unscaled data
- 01 = Null frame (no SAV/EAV sequence will be generated)
- 10 = Scaled data
- 11 = Reserved

The values programmed for registers 3A8h and 3A9h are different for NTSC (also NTSC4.43 and PAL-M) and for PAL (also PAL-Nc and SECAM).

#### 7.3.6 Vertical Scaling Field 1 Control

Address Default	3A8h 0h								
7	6	5	4	3	2	1	0		
			V_Fiel	d1[7:0]					
15	14	13	12	11	10	9	8		
	Reserved								

Vertical scaling initial value in field 1 [8:0]: Initial value of vertical accumulator for field 1

For NTSC:

V\_Field1 = (1.5 × V\_Field2) - 128

If V\_Field 1 is negative, add V\_Field2 to V\_Field1 and add V\_Field2 to V\_Field2 until V\_Field1 is positive.

For PAL:

V\_Field1 = (Vdesired/Vactive) × 256

## 7.3.7 Vertical Scaling Field 2 Control

Address	3A9h								
Default	0h								
7	6	5	4	3	2	1	0		
			V_Fiel	d2[7:0]					
15	14	13	12	11	10	9	8		
	Reserved								

Vertical scaling initial value in field 2 [8:0]: Initial value of vertical accumulator for field 2

For NTSC:

V\_Field2 = (Vdesired/Vactive) × 256

For PAL:

 $V_{Field2} = (1.5 \times V_{Field1}) - 128$ 

If V\_Field 2 is negative, add V\_Field1 to V\_Field2 and add V\_Field1 to V\_Field1 until V\_Field2 is positive.

## 7.3.8 Scaler Output Active Pixels

Address Default	3ABh 2D0h						
7	6	5	4	3	2	1	0
			SCAL_P	IXEL[7:0]			
15	14	13	12	11	10	9	8
		Rese	erved			SCAL_P	IXEL[9:8]

SCAL\_PIXEL [9:0]: Scaler active pixel outputs per line

## 7.3.9 Vertical Scaling Control

Address Default	3ACh 2100h						
7	6	5	4	3	2	1	0
			VERT_C	OEF[7:0]			
15	14	13	12	11	10	9	8
R	eserved	1	Enable		Reserved		VERT_COEF[8]
	his continui and have						

Enabled: Enable vertical and horizontal scaler

0 = Disable scaler (default)

1 = Enable scaler

VERT\_COEF [8:0]: Vertical scaling coefficient

VERT\_COEF = (Vdesired/Vactive) × 256

## 7.3.10 Horizontal Scaling Control

Address Default	3ADh 400h						
7	6	5	4	3	2	1	0
			HORZ_C	OEF[7:0]			
15	14	13	12	11	10	9	8
Reserved			ŀ	HORZ_COEF[14:8	3]		

HORZ\_COEF[14:0]: Horizontal scaling coefficient, MSB five bits are integer values and LSB ten bits are fraction numbers.

HORZ\_COEF = Hactive/Hdesired



### 8 Scaler Configuration

#### 8.1 Overview

The TVP5154A contains four independent scalers, one for each video decoder channel. Each scaler is able to filter and scale both horizontally and vertically to different ratios.

Horizontally, a 7-tap poly-phase filter is used to ensure optimal scaling performance and can be configured to scale to any output size below the input resolution, in decrements of two pixels. Vertically a running average filter is used to filter vertically and can be configured to scale to any output size below the input resolution.

When scaling horizontally, the output pixels are packed together to allow continuous reading of the pixels. AVID should be configured so that it qualifies the active pixels, allowing the receiving back end to ignore nonactive pixels. When scaling vertically, inactive lines are not removed from the output since there is no internal frame memory. The receiving back end must use AVID to qualify active lines/pixels. AVID can be configured to be either active or inactive during invalid output lines.

Due to the fact that vertical scaling is performed on a field basis, it is possible that the vertical resolution will be reduced due to filtering across lines within the field, rather than adjacent lines in the frame. Aliasing will not occur, but the output image will appear soft vertically. If the desired scaling ration is 0.5, this can be achieved by simply ignoring every other field. This maintains sharpness, but may introduce aliasing artifacts.

#### 8.2 Horizontal Scaling

#### 8.2.1 Registers

The horizontal scaler uses a 32-phase polymorphic filter. Excellent performance can be achieved by using the set of coefficients programmed into the 5154 for all scaling ratios.

It is necessary to program the input and output scaling control registers (3AB and 3AD).

Figure 8-1 shows how data is packed horizontally when scaled.

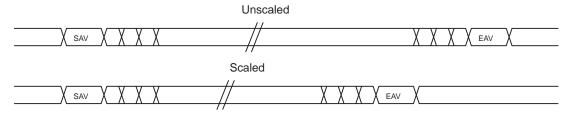


Figure 8-1. Unscaled and Scaled Pixel Data Alignment

#### 8.3 Vertical Scaling

#### 8.3.1 Registers

The vertical scaler implements a weighted running average filter, which requires the initial weights and the ratio registers to be configured.

Additionally, it is necessary to program the input and output scaling control registers (3A8, 3A9, and 3AC). Figure 8-2 shows the active and inactive data lines when scaled vertically.

	Unscaled	
Line n	(SAV) X X X	X X X EAV X
Line n+1	(SAV X X X	X X X EAV X
Line n+2	(SAV X X X	X X X X EAV X
Line n+3	( SAV X X X	XXXEAVX
Line n+4	( SAV X X X	XXXEAV
Line n+5	( SAV X X X	X X X X EAV X
Line n+6	( SAV X X X	X X X EAV X
Line n+7	(SAV) X X X	X X X EAV X
	Scaled	
Line n	(SAV) X X X	X X X EAV X
Line n+1	( SAV X X X	X X X EAV X
Line n+2		
Line n+3	(SAV) X X X	X X X EAV X
Line n+4	(SAV) X X X	X X X EAV X
Line n+5		
Line n+6	( sav )	X X X EAV X
Line n+7	(sav) XXX	X X X EAV X

Figure 8-2. Unscaled and Scaled Vertical Data Formatting

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#### 8.4 Field Interleaving

In systems where either there are insufficient video ports on the back end processor to accommodate both scaled and unscaled video streams, or where the back end processor does not have sufficient processing power to perform compression on the unscaled image at the same time as other video processing, such as composting of scaled images for display, it is possible to configure the TVP5154A to output different image types on consecutive fields. In this configuration, the field rates for each of the scaled and unscaled images is reduced to accommodate the interleaving of fields, while maintaining a 27-MHz pixel clock.

This is useful in video recording systems that are required to display a scaled image but still wish to compress and store full resolution images, albeit at reduced field rates.

Field interleaving can generate a sequence of up to 16 fields, where each field can be either unscaled, scaled, or blank.

#### 8.4.1 Registers

The field loop count register controls how many fields are in the sequence. The field mode registers control the output field type for each field.

Figure 8-3 shows how to configure field interleaving for a sequence of five fields where the first field is unscaled, the second field is scaled, the third field is blank, the fourth field is scaled, and the fifth field is blank.

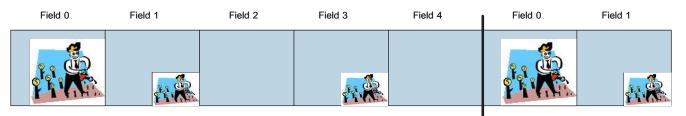


Figure 8-3. Field Interleaving

Various additional registers exist to configure how the TVP5154A indicates to the back-end processor the state of the current field. The Output Control register 1Fh allows the scaled/unscaled status to be indicated by the upper bit of the SAV/EAV codes. The Output Control register 1Fh also allows the scaled/unscaled status to be indicated by the DID codes of ancillary data.

# 9 Electrical Specifications

## 9.1 Absolute Maximum Ratings<sup>(1)</sup>

over operating free-air temperature range (unless otherwise noted)

			VALUE	UNIT	
		IOVDD to DGND	-0.5 to 3.6		
	Supply voltage range	DVDD to DGND	-0.5 to 2	v	
	Supply voltage range	PLL_AVDD to PLL_AGND	-0.5 to 2	v	
		AVDD to AGND	-0.5 to 2		
	Digital input voltage range, V <sub>I</sub> to DGND	-0.5 to 3.6	V		
	Input voltage range, XIN to PLL_GND		-0.5 to 2	V	
	Analog input voltage range, A <sub>I</sub> to AGND		-0.2 to 2	V	
	Digital output voltage range, $V_O$ to DGND		-0.5 to 3.6	V	
т		Commercial	0 to 70	°C	
T <sub>A</sub>	Operating free-air temperature range	Industrial	-40 to 85		
T <sub>stg</sub>	Storage temperature range		-65 to 150	°C	

(1) Stresses beyond those listed under absolute maximum ratings may cause permanent damage to the device. These are stress ratings only and functional operation of the device at these or any other conditions beyond those indicated under recommended operating conditions is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

## 9.2 Recommended Operating Conditions

			MIN	NOM	MAX	UNIT
IOVDD	Digital I/O supply voltage		3.0	3.3	3.6	V
DVDD	Digital supply voltage		1.65	1.8	1.95	V
PLL_AVDD	Analog PLL supply voltage		1.65	1.8	1.95	V
AVDD	Analog core supply voltage	nalog core supply voltage				V
V <sub>I(P-P)</sub>	Analog input voltage (ac-coupling neo	cessary)	0		0.75	V
V <sub>IH</sub>	Digital input voltage high		0.7 IOVDD			V
VIL	Digital input voltage low				0.3 IOVDD	V
V <sub>IH_XIN</sub>	XIN input voltage high		0.7 PLL_AVDD			V
V <sub>IL_XIN</sub>	XIN input voltage low				0.3 PLL_AVDD	V
I <sub>OH</sub>	High-level output current		2	4		mA
I <sub>OL</sub>	Low-level output current		-2	-4		mA
I <sub>OH_CLK</sub>	CLK high-level output current		4	8		mA
I <sub>OL_CLK</sub>	CLK low-level output current		-4	-8		mA
-		Commercial	0		70	°C
T <sub>A</sub>	Operating free-air temperature	Industrial	-40		85	-0

## 9.3 Reference Clock Specifications

		MIN	NOM	MAX	UNIT
f	Frequency		14.31818		MHz
Δf	Frequency tolerance <sup>(1)</sup>	-50		+50	ppm

(1) Specified by design

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#### 9.4 **Electrical Characteristics**

For typical values: Nominal conditions,  $T_A = 25^{\circ}C$ 

For minimum/maximum values: Over recommended operating conditions (unless otherwise noted)

	PARAMETER	TEST CONDITIONS <sup>(1)</sup>	MIN	TYP	MAX	UNIT
DC		I				
I <sub>DD(IO_D)</sub>	I/O digital supply current at 27 MHz	Color bar input <sup>(2)</sup>		46	52	mA
	I/O digital supply current at 54 MHz	Color bar input <sup>(2)</sup>		84	90	mA
I <sub>DD(D)</sub>	Digital supply current	Color bar input <sup>(2)</sup>		154	174	mA
I <sub>DD(PLL_A)</sub>	Analog PLL supply current	Color bar input <sup>(2)</sup>		20	29	mA
I <sub>DD(A)</sub>	Analog core supply current	Color bar input (2)		134	168	mA
P <sub>TOT</sub>	Total power dissipation, normal mode at 27 MHz	Color bar input <sup>(2)</sup>		706	910	mW
	Total power dissipation, normal mode at 54 MHz	Color bar input <sup>(2)</sup>		832	1050	mW
C <sub>i</sub>	Input capacitance <sup>(3)</sup>				10	pF
V <sub>OH</sub>	Output voltage high	I <sub>OH</sub> = 2 mA	0.8 IOVDD			V
V <sub>OL</sub>	Output voltage low	$I_{OL} = -2 \text{ mA}$			0.22 IOVDD	V
V <sub>OH_CLK</sub>	CLK output voltage high	I <sub>OH</sub> = 4 mA	0.8 IOVDD			V
V <sub>OL_CLK</sub>	CLK output voltage low	$I_{OL} = -4 \text{ mA}$			0.22 IOVDD	V
I <sub>IH</sub>	High-level input current	$V_{I} = V_{IH}$			±22	μA
IIL	Low-level input current	$V_{I} = V_{IL}$			±22	μA
Analog P	rocessing and ADCs (at FS = 30 MSPS)					
Z <sub>i</sub>	Input impedance, analog video inputs	By design	200	500		kΩ
C <sub>i</sub>	Input capacitance, analog video inputs	By design			10	pF
V <sub>I(pp)</sub>	Input voltage range <sup>(4)</sup>	$C_{coupling} = 0.1 \ \mu F$	0		0.75	V
DG	Gain control minimum			0		dB
DG	Gain control maximum			12		dB
DNL	DC differential nonlinearity	A/D only		±0.5	±1	LSB
INL	DC integral nonlinearity	A/D only		±1	±2.5	LSB
Fr	Frequency response	6 MHz		-0.9	-3	dB
SNR	Signal-to-noise ratio	1 MHz, 0.5 V <sub>P-P</sub>	48	50		dB
NS	Noise spectrum ®	50% flat field	48	50		dB
DP	Differential phase (5)	Modulated ramp		1.5		deg
DG	Differential gain (5)	Modulated ramp		0.5		%

Measured with a load of 15 pF. For typical measurements only (1)

(2) (3)

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(4) (5) The 0.75-V maximum applies to the sync-chroma amplitude, not sync-white. The recommended termination resistors are 37.4 Ω.

Specified by design



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#### 9.5 Timing Requirements

	PARAMETER	TEST CONDITIONS <sup>(1)</sup>	MIN	ТҮР	МАХ	UNIT
	Duty cycle SCL			50		%
t <sub>1</sub>	CLK high time (at 27 MHz)		13.5			ns
t <sub>2</sub>	CLK low time (at 27 MHz)		13.5			ns
t <sub>3</sub>	CLK fall time (at 27 MHz)	90% to 10%			5	ns
t <sub>4</sub>	CLK rise time (at 27 MHz)	10% to 90%			5	ns
t <sub>5</sub>	Output hold time		10			ns
t <sub>6</sub>	Output delay time				25	ns
t <sub>7</sub>	Output hold time		4			ns
t <sub>8</sub>	Output delay time				16.5	ns
t <sub>9</sub>	Data period			18.5		ns
t <sub>10</sub>	Output hold time		4			ns
t <sub>11</sub>	Output delay time				16.5	ns
t <sub>12</sub>	Data period			18.5		ns
t <sub>13</sub>	CLK high time (at 54 MHz)		3			ns
t <sub>14</sub>	CLK low time (at 54 MHz)		3			ns
t <sub>15</sub>	CLK fall time (at 54 MHz)	90% to 10%			6	ns
t <sub>16</sub>	CLK rise time (at 54 MHz)	10% to 90%			6	ns

(1) Measured with a load of 15 pF for 27-MHz signals, 25 pF for 54-MHz signals. Specified by design.

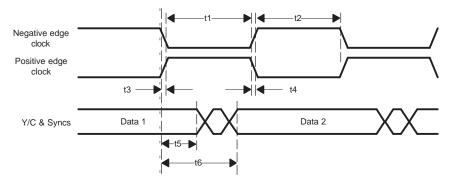


Figure 9-1. Output Modes 0 and 1: Clocks, Video Data, and Sync

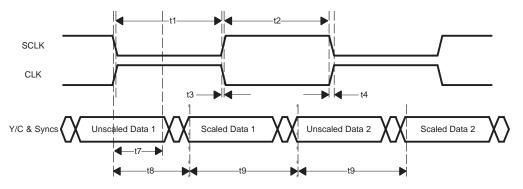


Figure 9-2. Output Mode 2: Clocks, Video Data, and Sync





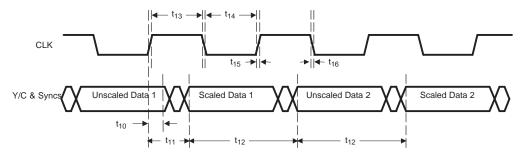
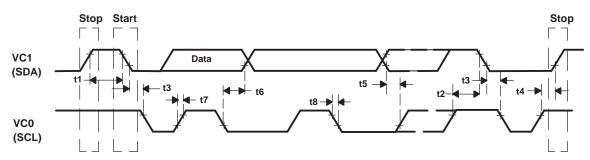


Figure 9-3. Output Mode 3: Clock, Video Data, and Sync (Positive Edge Clock)

## 9.6 I<sup>2</sup>C Host Port Timing

	PARAMETER	TEST CONDITIONS	MIN	MAX	UNIT
t <sub>1</sub>	Bus free time, between STOP and START		1.3		μs
t <sub>2</sub>	Setup time, (repeated) START condition		0.6		μs
t <sub>3</sub>	Hold time, (repeated) START condition		0.6		μs
t <sub>4</sub>	Setup time, STOP condition		0.6		ns
t <sub>5</sub>	Data setup time		100		ns
t <sub>6</sub>	Data hold time		0	0.9	μs
t <sub>7</sub>	Rise time, VC1(SDA) and VC0(SCL) signal	Specified by design		250	ns
t <sub>8</sub>	Fall time, VC1(SDA) and VC0(SCL) signal	Specified by design		250	ns
Cb	Capacitive load for each bus line	Specified by design		400	pF
f <sub>I2C</sub>	I <sup>2</sup> C clock frequency			400	kHz



## Figure 9-4. I<sup>2</sup>C Host Port Timing

## 9.7 Thermal Specifications

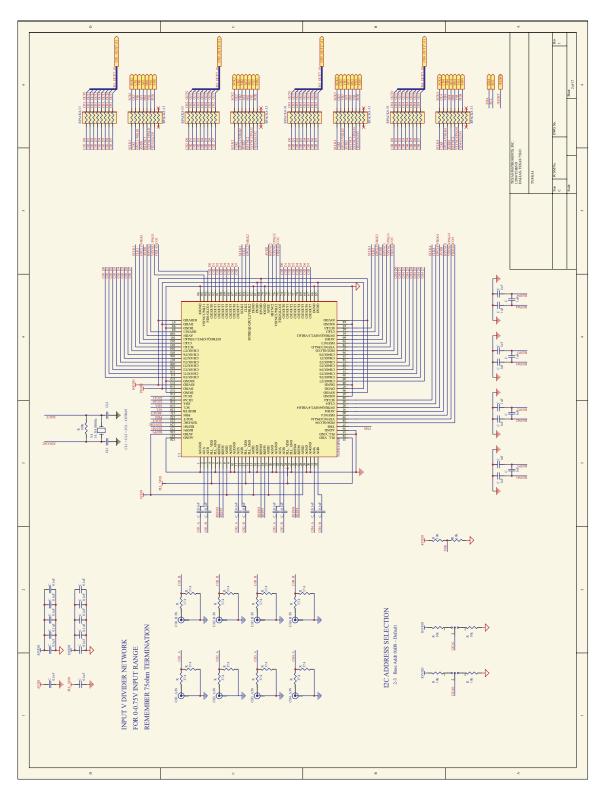
	PARAMETER	TEST CONDITIONS <sup>(1)</sup>	MIN	TYP	MAX	UNIT
$\theta_{JA}$	Junction-to-ambient thermal resistance, still air	Thermal pad soldered to 4-layer High-K PCB		17.17		°C/W
$\theta_{\text{JC}}$	Junction-to-case thermal resistance, still air	Thermal pad soldered to 4-layer High-K PCB		0.12		°C/W
T <sub>J(MAX)</sub>	Maximum junction temperature for reliable operation				105	°C

(1) The exposed thermal pad must be soldered to a JEDEC High-K PCB with adequate ground plane.



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# 10 Schematic





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# 11 Revision History

REVISION	COMMENTS
SLES214	Initial release
SLES214A	Industrial temperature devices added
SLES214B	Section 1.1, NTSC-J and PAL-Nc support added to feature list.
	Section 1.2, Application list modified.
	Section 1.4, Related Products modified.
	Section 1.5, Trademarks added.
	Section 1.6, Document conventions added.
	Section 2, Figure 2-1, Block diagram modified.
	Section 3.2, I/O type modified for ground pins.
	Section 4.3, Figure 4-1, Chroma trap filter characteristics for NTSC added.
	Section 4.3, Figure 4-2, Chroma trap filter characteristics for PAL added.
	Section 4.4, Figure 4-3, Color low-pass filter characteristics added.
	Section 4.8, Table 4-1, CGMS-A and Gemstar 2x support added.
	Section 4.11, Table 4-3, NTSC-J and PAL-Nc support added. Lines per frame and color subcarrier frequency columns also added.
	Section 6, Figure 6.1, Crystal parallel resistor recommendation added.
	Section 7.3, Reset and power down information added.
	Section 8.1, Table 8-1, CGMS-A support added to address 94h-99h. Gemstar 2x support added to address 9Ah-A6h.
	Section 8.2.2, Automatic offset control description removed.
	Section 8.2.3, Changed white peak to composite peak. Recommendations added.
	Section 8.2.10, Brightness control register description modified.
	Section 8.2.11, Color saturation control register description modified.
	Section 8.2.13, Contrast control register description modified.
	Section 8.2.34, NTSC-J support added.
	Section 8.2.39, Reference to ITU-R BT.656-5 standard added.
	Section 8.2.50, Status Register #3 description modified.
	Section 8.2.52, Table 8-10, NTSC-J and PAL-Nc support added.
	Section 8.2.54, CGMS-A support added.
	Section 8.2.63, Recommended VBI Configuration RAM settings modifications. Gemstar support included.
	Section 8.2.64, CGMS-A and Gemstar 2x support added.
	Section 8.2.72, CGMS-A and Gemstar 2x support added.
	Section 10.1, Units for temperature corrected.
	Section 10.2, Units for temperature corrected.
	Section 10.3, Table formatting modified.
	Made minor editorial changes (throughout).
SLES214C	Changed order of some sections in chapters 1, 2, and 3
	Section 3.6, Modified when color killer suppresses chrominance processing.
	Section 9.7, Added thermal specifications.
	Section 7.2.31, Added Indirect Register Data
	Section 7.2.32, Added Indirect Register Address
	Section 7.2.33, Added Indirect Register Read/Write Strobe
	Section 7.2.44, Added Patch Write Address
	Section 7.2.45, Added Patch Code Execute
	Section 7.2.58, Added Patch Read Address

## Table 11-1. Revision History



#### **PACKAGING INFORMATION**

Orderable Device	Status (1)	Package Type	Package Drawing	Pins	Package Qty	Eco Plan (2)	Lead/Ball Finish	MSL Peak Temp (3)	Op Temp (°C)	Device Marking (4/5)	Samples
TVP5154AIPNP	NRND	HTQFP	PNP	128	90	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-3-260C-168 HR	-40 to 85	TVP5154AI	
TVP5154AIPNPR	NRND	HTQFP	PNP	128	1000	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-3-260C-168 HR	-40 to 85	TVP5154AI	
TVP5154APNP	NRND	HTQFP	PNP	128	90	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-3-260C-168 HR	0 to 70	TVP5154A	
TVP5154APNPR	NRND	HTQFP	PNP	128	1000	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-3-260C-168 HR	0 to 70	TVP5154A	

<sup>(1)</sup> The marketing status values are defined as follows:

ACTIVE: Product device recommended for new designs.

LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

NRND: Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

PREVIEW: Device has been announced but is not in production. Samples may or may not be available.

**OBSOLETE:** TI has discontinued the production of the device.

<sup>(2)</sup> Eco Plan - The planned eco-friendly classification: Pb-Free (RoHS), Pb-Free (RoHS Exempt), or Green (RoHS & no Sb/Br) - please check http://www.ti.com/productcontent for the latest availability information and additional product content details.

**TBD:** The Pb-Free/Green conversion plan has not been defined.

**Pb-Free (RoHS):** TI's terms "Lead-Free" or "Pb-Free" mean semiconductor products that are compatible with the current RoHS requirements for all 6 substances, including the requirement that lead not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, TI Pb-Free products are suitable for use in specified lead-free processes.

**Pb-Free (RoHS Exempt):** This component has a RoHS exemption for either 1) lead-based flip-chip solder bumps used between the die and package, or 2) lead-based die adhesive used between the die and leadframe. The component is otherwise considered Pb-Free (RoHS compatible) as defined above.

Green (RoHS & no Sb/Br): TI defines "Green" to mean Pb-Free (RoHS compatible), and free of Bromine (Br) and Antimony (Sb) based flame retardants (Br or Sb do not exceed 0.1% by weight in homogeneous material)

<sup>(3)</sup> MSL, Peak Temp. -- The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

<sup>(4)</sup> There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.

(5) Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "~" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.

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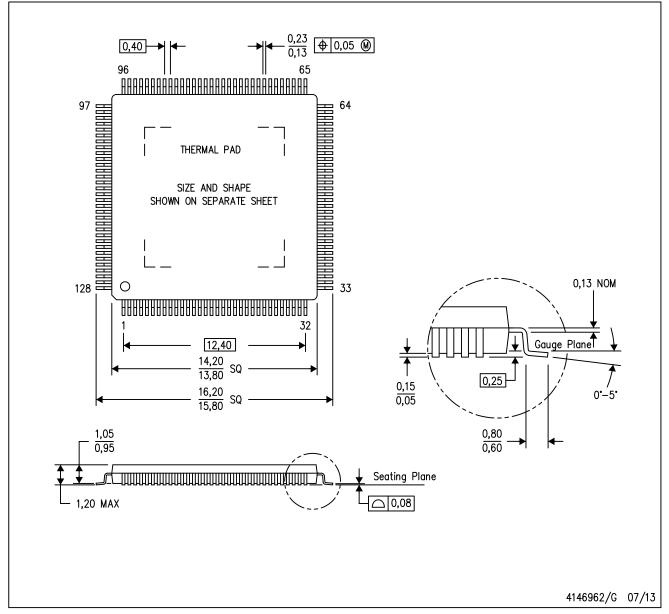
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PNP (S-PQFP-G128)

PowerPAD<sup>™</sup> PLASTIC QUAD FLATPACK



NOTES: A. All linear dimensions are in millimeters.

- B. This drawing is subject to change without notice.
- C. Body dimensions do not include mold flash or protrusion
- D. This package is designed to be soldered to a thermal pad on the board. Refer to Technical Brief, PowerPad Thermally Enhanced Package, Texas Instruments Literature No. SLMA002 for information regarding recommended board layout. This document is available at www.ti.com <a href="http://www.ti.com">http://www.ti.com</a>.
- recommended board layout. This document is available at www.ti.com <http://www.ti.com>. E. See the additional figure in the Product Data Sheet for details regarding the exposed thermal pad features and dimensions.

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# PNP (S-PQFP-G128)

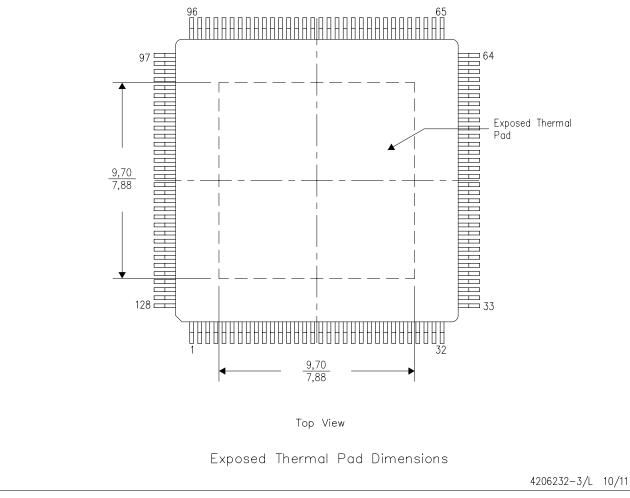
# PowerPAD<sup>™</sup> PLASTIC QUAD FLATPACK

THERMAL INFORMATION

This PowerPAD<sup>M</sup> package incorporates an exposed thermal pad that is designed to be attached to a printed circuit board (PCB). The thermal pad must be soldered directly to the PCB. After soldering, the PCB can be used as a heatsink. In addition, through the use of thermal vias, the thermal pad can be attached directly to the appropriate copper plane shown in the electrical schematic for the device, or alternatively, can be attached to a special heatsink structure designed into the PCB. This design optimizes the heat transfer from the integrated circuit (IC).

For additional information on the PowerPAD package and how to take advantage of its heat dissipating abilities, refer to Technical Brief, PowerPAD Thermally Enhanced Package, Texas Instruments Literature No. SLMA002 and Application Brief, PowerPAD Made Easy, Texas Instruments Literature No. SLMA004. Both documents are available at www.ti.com.

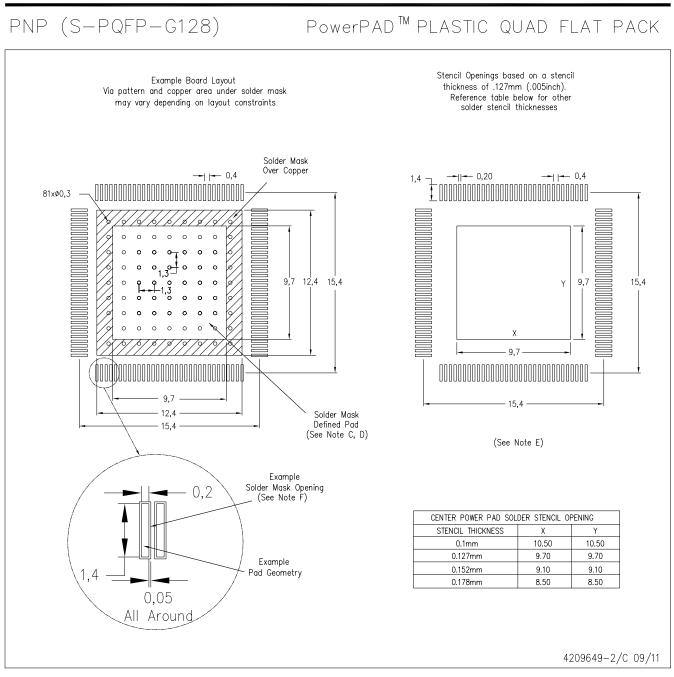
The exposed thermal pad dimensions for this package are shown in the following illustration.



NOTE: All linear dimensions are in millimeters

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NOTES: A. All linear dimensions are in millimeters.

- B. This drawing is subject to change without notice.
- C. Customers should place a note on the circuit board fabrication drawing not to alter the center solder mask defined pad.
- D. This package is designed to be soldered to a thermal pad on the board. Refer to Technical Brief, PowerPad Thermally Enhanced Package, Texas Instruments Literature No. SLMA002, SLMA004, and also the Product Data Sheets for specific thermal information, via requirements, and recommended board layout. These documents are available at www.ti.com <http://www.ti.com>. Publication IPC-7351 is recommended for alternate designs.
- E. Laser cutting apertures with trapezoidal walls and also rounding corners will offer better paste release. Customers should contact their board assembly site for stencil design recommendations. Example stencil design based on a 50% volumetric metal load solder paste. Refer to IPC-7525 for other stencil recommendations.

F. Customers should contact their board fabrication site for solder mask tolerances between and around signal pads. PowerPAD is a trademark of Texas Instruments.



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