



Sample &

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### UCC28050, UCC28051, UCC38050, UCC38051

SLUS515G - SEPTEMBER 2002 - REVISED DECEMBER 2015

# UCC2805x, UCC3805x Transition Mode PFC Controller

#### 1 Features

**Fexas** 

Instruments

- Transition Mode PFC Controller for Low Implementation Cost
- Industry Pin Compatibility With Improved Feature Set
- Improved Transient Response With Slew-Rate Comparator
- Zero Power Detect to Prevent Overvoltage Protection (OVP) During Light Load Conditions
- Accurate Internal VREF for Tight Output Regulation
- Two UVLO Options
- OVP, Open-Feedback Protection, and Enable Circuits
- ±750-mA Peak Gate Drive Current
- Low Start-Up and Operating Currents
- Lead (Pb)-Free Packages

#### 2 Applications

- Single-Stage PFC Flyback Converters for Lighting and Motor Drives
- Switch-Mode Power Supplies for Desktops. Monitors, TVs, and Set Top Boxes (STBs)
- AC Adapter Front-End Power Supplies
- **Electronic Ballasts**

### 3 Description

The UCC38050 and UCC38051 are PFC controllers for low-to-medium power applications requiring compliance with IEC 1000-3-2 harmonic reduction standard. The controllers are designed for a boost preregulator operating in transition mode (also referred to as boundary-conduction mode or critical conduction-mode operation). They feature а transconductance voltage amplifier for feedback error processing, a simple multiplier for generating a current command proportional to the input voltage, a current-sense (PWM) comparator, PWM logic, and a totem-pole driver for driving an external FET.

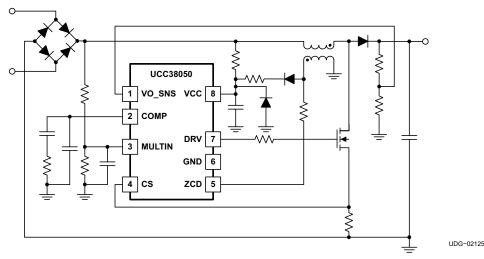
In the transition mode operation, the PWM circuit is self-oscillating, with the turnon being governed by an inductor zero-current detector (ZCD pin), and the turnoff being governed by the current-sense comparator. Additionally, the controller provides features such as peak current limit, default timer, overvoltage protection (OVP) and enable.

#### Device Information<sup>(1)</sup>

PART NUMBER	PACKAGE	BODY SIZE (NOM)
UCC28050,	SOIC (8)	3.91 mm × 4.90 mm
UCC28051, UCC38050, UCC38051	PDIP (8)	6.35 mm × 9.81 mm

(1) For all available packages, see the orderable addendum at the end of the data sheet.

#### Simplified Application Diagram



An IMPORTANT NOTICE at the end of this data sheet addresses availability, warranty, changes, use in safety-critical applications, intellectual property matters and other important disclaimers. PRODUCTION DATA.



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## **4** Revision History

### Changes from Revision F (March 2009) to Revision G

Added ESD Ratings table, Feature Description sectio • section, Power Supply Recommendations section, La Mechanical, Packaging, and Orderable Information se

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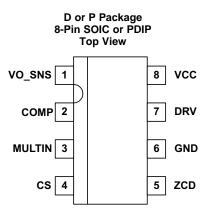
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## 5 Pin Configuration and Functions



### **Pin Functions**

Р	IN		DECODIDION
NAME	NO.	I/O	DESCRIPTION
СОМР	2	0	Output of the transconductance error amplifier. Loop compensation components are connected between this pin and ground. The output current capability of this pin is 10- $\mu$ A under normal conditions, but increases to approximately 1-mA when the differential input is greater than the specified values in the specifications table. This voltage is one of the inputs to the multiplier, with a dynamic input range of 2.5 V to 3.8 V. During zero power or overvoltage conditions, this pin goes below 2.5 V nominal. When it goes below 2.3 V, the zero power comparator is activated, which prevents the gate drive from switching.
CS	4	I	This pin senses the instantaneous switch current in the boost switch and uses it as the internal ramp for PWM comparator. The internal circuitry filters out switching noise spikes without requiring external components. In addition, an external R-C filter may be required to suppress the noise spikes. An internal clamp on the multiplier output terminates the switching cycle if this pin voltage exceeds 1.7 V. Additional external filtering may be required. CS threshold is approximately equal to: $L = \frac{\left(V_{AC(min)}\right)^2 \times \left(V_{OUT} - \sqrt{2} \times V_{AC(min)}\right)}{2 \times F_{s(min)} \times V_{OUT} \times P_{IN}} $ (1)
			V <sub>OFFSET</sub> is approximately 75 mV to improve the zero crossing distortion.
DRV	7	0	The gate drive output for an external boost switch. This output is capable of delivering up to 750- mA peak currents during turn-on and turn-off. An external gate drive resistor may be needed to limit the peak current depending on the $V_{CC}$ voltage being used. Below the UVLO threshold, the output is held low.
GND	6	-	The chip reference ground. All bypassing elements are connected to ground pin with shortest loops feasible.
MULTIN	3	I	This pin senses the instantaneous boost regulator input voltage through a voltage divider. The voltage acts as one of the inputs to the internal multiplier. Recommended operating range is 0 V to 2.5 V at high line.
VCC	8	_	The supply voltage for the chip. This pin should be bypassed with a high-frequency capacitor (greater than $0.1$ - $\mu$ F) and tied to GND. The UCC38050 has a wide UVLO hysteresis of approximately 6.3 V that allows use of a lower value supply capacitor on this pin for quicker and easier start-up. The UCC38051 has a narrow UVLO hysteresis with of about 2.8 V, and a start-up voltage of about 12.5 V for applications where the operation of the PFC device must be controlled by a downstream PWM controller.
VO_SNS	1	I	This pin senses the boost regulator output voltage through a voltage divider. Internally, this pin is the inverting input to the transconductance amplifier (with a nominal value of 2.5 V) and also is input to the OVP comparator. Additionally, pulling this pin below the ENABLE threshold turns off the output switching, ensuring that the gate drive is held off while the boost output is pre-charging, and also ensuring no runaway if the feedback path is open.
ZCD	5	1	Input for the zero current detect comparator. The boost inductor current is indirectly sensed through the bias winding on the boost inductor. The ZCD pin input goes low when the inductor current reaches zero and that transition is detected. Internal active voltage clamps are provided to prevent this pin from going below ground or too high. If zero current is not detected within 400 $\mu$ s, a reset timer sets the latch and gate drive.

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### 6 Specifications

### 6.1 Absolute Maximum Ratings

over operating free-air temperature range (unless otherwise noted)<sup>(1)</sup>

		MIN	MAX	UNIT
Supply voltage, V <sub>CC</sub>	(Internally clamped)		20	V
Input current into V <sub>CC</sub> clamp	I <sub>DD</sub>		30	mA
Input current	ZCD		±10	mA
Gate drive current (peak), I <sub>DRV</sub>	DRV		±750	mA
Input voltage, V <sub>CC</sub>	VO_SNS, MULTIN, CS		5	V
Maximum negative voltage	VO_SNS, MULTIN, DRV, CS		-0.5	V
	D package		650	mW
Power dissipation at $T_A = 50^{\circ}C$	P package		1	W
Operating junction temperature range, T <sub>J</sub>		-55	150	°C
Storage temperature, T <sub>stg</sub>		65	150	°C
Lead temperature 1,6 mm (1/16 inch) from case for 10 seconds			300	°C

(1) Stresses beyond those listed under Absolute Maximum Ratings may cause permanent damage to the device. These are stress ratings only, which do not imply functional operation of the device at these or any other conditions beyond those indicated under Recommended Operating Conditions. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

### 6.2 ESD Ratings

			VALUE	UNIT		
SOIC P	OIC PACKAGE					
		Human-body model (HBM), per ANSI/ESDA/JEDEC JS-001 <sup>(1)</sup>		V		
V <sub>(ESD)</sub>	Electrostatic discharge	Charged-device model (CDM), per JEDEC specification JESD22-C101 $^{\left( 2\right) }$	±500	V		

(1) JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process.

(2) JEDEC document JEP157 states that 250-V CDM allows safe manufacturing with a standard ESD control process.

### 6.3 Recommended Operating Conditions

over operating free-air temperature range (unless otherwise noted)

	MIN	NOM MAX	UNIT
VCC input voltage from a low-impedance source	VCC <sub>OFF</sub> + 1 V	18	V
Operating junction temperature, T <sub>J</sub>	-40	125	°C

### 6.4 Thermal Information

			UCC2805x, UCC3805x		
	THERMAL METRIC <sup>(1)</sup>	D (SOIC)	D (SOIC) P (PDIP)		
		8 PINS	8 PINS		
$R_{\theta JA}$	Junction-to-ambient thermal resistance	113.6	55.6	°C/W	
R <sub>0JC(top)</sub>	Junction-to-case (top) thermal resistance	60.3	45.5	°C/W	
$R_{ extsf{ heta}JB}$	Junction-to-board thermal resistance	54.3	32.7	°C/W	
$\Psi_{JT}$	Junction-to-top characterization parameter	14	23.1	°C/W	
Ψ <sub>JB</sub>	Junction-to-board characterization parameter	53.8	32.6	°C/W	

(1) For more information about traditional and new thermal metrics, see the Semiconductor and IC Package Thermal Metrics application report, SPRA953.

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### 6.5 Electrical Characteristics

 $T_A = 0^{\circ}C$  to 70°C for the UCC3805x, -40°C to +105°C for the UCC2805x,  $T_A = T_J$ ,  $V_{CC} = 12$  V.

PARAMETER		TEST CONDITIONS	MIN	ТҮР	MAX	UNIT
SUPPLY						
V <sub>CC</sub> operating voltage					18	V
Shunt voltage		I <sub>VCC</sub> = 25 mA	18	19	20	V
Supply current, off		$V_{CC} = V_{CC}$ turnon threshold -300 mV		75	125	μA
Supply current, disabled		VO_SNS = 0.5 V		2	4	mA
Supply current, on		75 kHz, C <sub>L</sub> = 0 nF		4	6	mA
Supply current, dynamic oper	ating	75 kHz, C <sub>L</sub> = 1 nF		5	7	mA
UVLO						
	UCCx8050		15.4	15.8	16.4	
$V_{CC}$ turnon threshold	UCCx8051		12	12.5	13	V
V <sub>CC</sub> turnoff threshold			9.4	9.7	10	V
IIV/I O hystore	UCCx8050		5.8	6.3	6.8	
UVLO hysteresis	UCCx8051		2.3	2.8	3.3	V
VOLTAGE AMPLIFIER (VO_SNS	)	· · · · · · · · · · · · · · · · · · ·			1	
	UCC3805x		2.46	2.5	2.54	
Input voltage (V <sub>REF</sub> )	UCC2805x		2.45	2.5	2.55	V
Input bias current					0.5	μA
V <sub>COMP</sub> high		VO_SNS = 2.1 V	4.5		5.5	V
V <sub>COMP</sub> low		VO_SNS = 2.55 V		1.8	2.45	V
gM			60	90	130	μS
0	UCCx8050	VO_SNS = 2.1 V, V <sub>COMP</sub> = 3.5 V	-0.2	-0.1		mA
Source current	UCCx8051	VO_SNS = 2.1 V, V <sub>COMP</sub> = 2.5 V	-200	-300	-400	μA
Sink current		VO_SNS = 2.7 V, $V_{COMP}$ = 3.5 V	0.2	1		mA
OVER VOLTAGE PROTECTION	ENABLE					
0	UCCx8050		VREF + 0.165	VREF + 0.19	VREF + 0.21	
Overvoltage reference	UCCx8051		VREF + 0.15	VREF + 0.18	VREF + 0.21	V
1 hardene ele	UCCx8050		175	200	225	
Hysteresis	UCCx8051		150	180	210	mV
<b>F</b> . 1 . 4	UCCx8050		0.62	0.67	0.72	
Enable threshold	UCCx8051		0.18	0.23	0.28	V
Enable hysteresis	·		0.05	0.1	0.2	V
MULTIPLIER						
Multiplier gain constant (k)		V <sub>MULTIN</sub> = 0.5 V, COMP = 3.5 V	0.43	0.65	0.87	1/V
Dynamic input range, V <sub>MULTIN</sub>	INPUT		0 to 2.5	0 to 3.5		V
Dynamic input range, COMP	INPUT		2.5 to 3.8	2.5 to 4		V
Input bias current, MULTIN				0.1	1	μA
ZERO POWER		L			1	
Zero power comparator thres	hold <sup>(1)</sup>	Measured on V <sub>COMP</sub>	2.1	2.3	2.5	V

(1) Ensured by design. Not production tested.

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### **Electrical Characteristics (continued)**

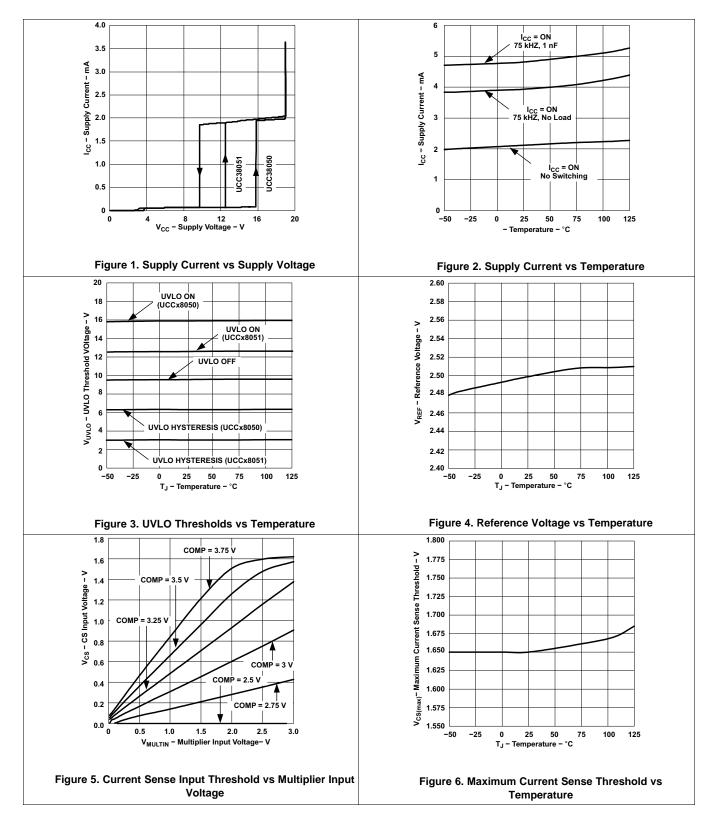
### $T_A = 0^{\circ}C$ to 70°C for the UCC3805x, -40°C to +105°C for the UCC2805x, $T_A = T_J$ , $V_{CC} = 12$ V.

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
ZERO CURRENT DETECT					
Input threshold (rising edge) <sup>(1)</sup>		1.5	1.7	2	V
Hysteresis <sup>(1)</sup>		250	350	450	mV
Input high clamp	I = 3 mA		5	6	V
Input low clamp	I = −3 mA	0.3	0.65	0.9	V
Restart time delay		200	400		μs
CURRENT SENSE COMPARATOR	· · · · · · · · · · · · · · · · · · ·			i.	
Input bias current	CS = 0 V		0.1	1	μA
Input offset voltage <sup>(1)</sup>		-10		10	mV
Delay to output	CS to DRV		300	450	ns
Maximum current sense threshold voltage		1.55	1.7	1.8	V
PFC GATE DRIVER				·	
GT1 pull-up resistance	I <sub>OUT</sub> = -125 mA		5	12	Ω
GT1 pull-down resistance	I <sub>OUT</sub> = 125 mA		2	10	Ω
GT1 output rise time	$C_{LOAD} = 1 \text{ nF}, R_{LOAD} = 10 \Omega$		25	75	ns
GT1 output fall time	$C_{LOAD} = 1 \text{ nF}, R_{LOAD} = 10 \Omega$		10	50	ns

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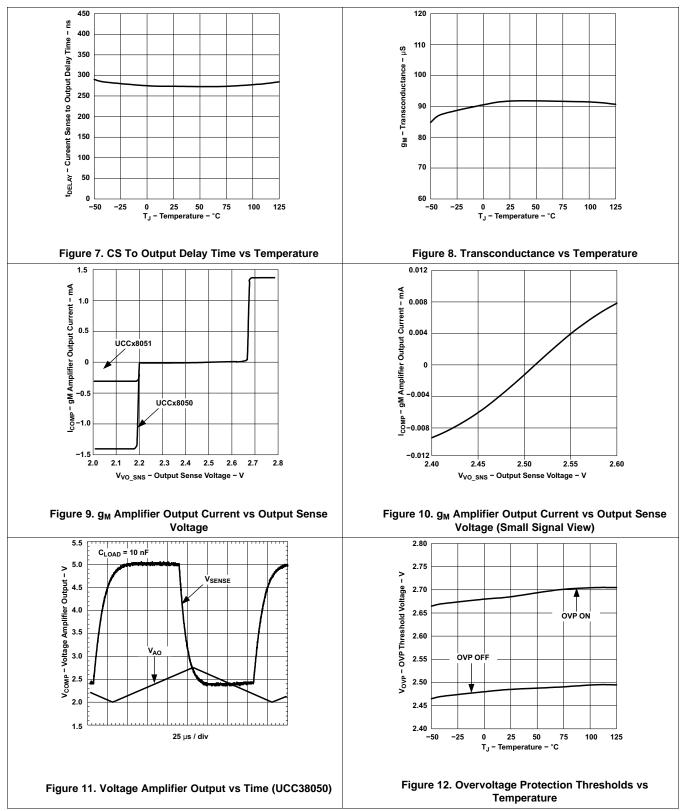


### 6.6 Typical Characteristics



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### **Typical Characteristics (continued)**

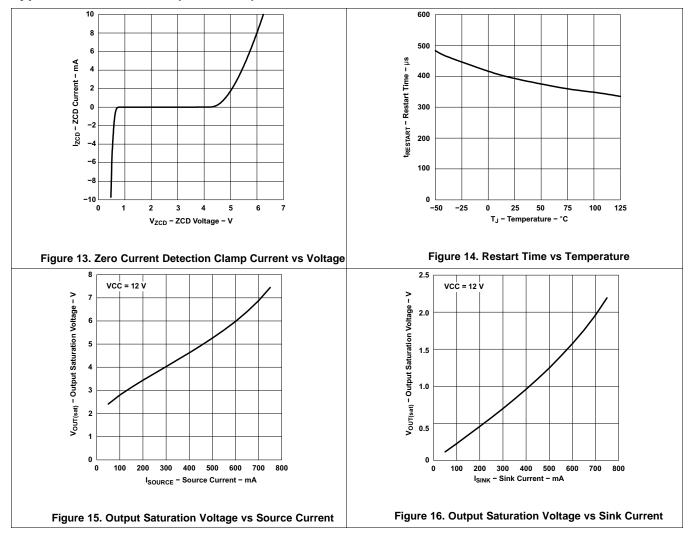


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Product Folder Links: UCC28050 UCC28051 UCC38050 UCC38051



#### **Typical Characteristics (continued)**





### 7 Detailed Description

### 7.1 Overview

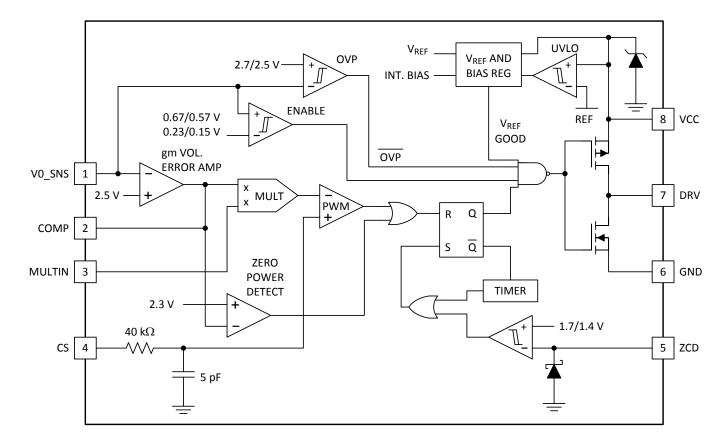
The UCC38050 and UCC38051 are PFC controllers for low-to-medium power applications requiring compliance with IEC 1000-3-2 harmonic reduction. The controller is designed for a boost preregulator operating in transition mode (also referred to as boundary-conduction mode or critical conduction-mode operation). It features a transconductance voltage amplifier for feedback error processing, a simple multiplier for generating a current command proportional to the input voltage, a current-sense (PWM) comparator, PWM logic, and a totem-pole driver for driving an external FET.

The UCC38050 and UCC38051, while being pin-compatible with other industry controllers providing similar functionality, offer many feature enhancements and tighter specifications, leading to an overall reduction in system implementation cost. The system performance is enhanced by incorporation of a zero-power detect function, which allows the controller output to shut down at light load conditions without running into overvoltage. The device also features innovative slew rate enhancement circuits, which improve the large signal transient performance of the voltage error amplifier. The low start-up and operating currents of the device result in low power consumption and ease of start-up. Highly accurate internal bandgap reference leads to tight regulation of output voltage in normal and OVP conditions, resulting in higher system reliability. The enable comparator ensures that the controller is off if the feedback sense path is broken or if the input voltage is very low.

There are two key parameteric differences between UCC38050 and UCC38051. The UVLO turn-on threshold of UCC38050 is 15.8 V, while for UCC38051 it is 12.5 V. Secondly, the gM amplifier source current for UCC38050 is typically 1.3 mA, while for UCC38051 it is 300  $\mu$ A. The higher UVLO turn-on threshold of the UCC38050 allows quicker and easier start-up with a smaller V<sub>CC</sub> capacitance, while the lower UVLO turn-on threshold of UCC38051 allows the operation of the PFC chip to be easily controlled by the downsteam PWM controller in two-stage power converters. The UCC38050 gM amplifier also provides a full 1.3-mA typical source current for faster start-up and improved transient response when output is low, either at start-up or during transient conditions. The UCC38051 scales this source current back down to 300- $\mu$ A typical source current to gradually increase the error voltage, preventing a step increase in line currents at start-up, but still providing good transient response. The UCC38051 is suitable for multiple applications, including AC adapters, where a two-stage power conversion is needed. The UCC38050 is suitable for applications such as electronic ballasts, where there is no down-stream PWM conversion and the advantages of a smaller V<sub>CC</sub> capacitor and improved transient response can be realized.



### 7.2 Functional Block Diagram



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### 7.3 Feature Description

#### 7.3.1 UVLO and Reference Block

This block generates a precision reference voltage used to obtain tightly controlled UVLO threshold. In addition to generating a 2.5-V reference for the non-inverting terminal of the gM amplifier, it generates the reference voltages for blocks such as OVP, enable, zero power, and multiplier. An internal rail of 7.5 V is also generated, to drive all the internal blocks.

#### 7.3.2 Error Amplifier

The voltage error amplifier in UCC3805x is a transcoductance amplifier, with a typical transconductance value of 90  $\mu$ S. A transconductance amplifier is advantageous in that the inverting input of the amplifier is solely determined by the external resistive-divider from the output voltage, and not the transient behavior of the amplifier itself. This allows the VO\_SNS pin to be used for sensing overvoltage conditions.

The sink and source capability of the error amplifier is approximately 10  $\mu$ A during normal operation of the amplifier. However, when the VO\_SNS pin voltage is beyond the normal operating conditions (VO\_SNS > 1.05 × V<sub>REF</sub>, VO\_SNS < 0.88 × V<sub>REF</sub>), additional circuitry to enhance the slew-rate of the amplifier is activated. Enhanced slew-rate of the compensation capacitor results in a faster start-up and transient response. This prevents the output voltage from drifting too high or too low, which can happen if the compensation capacitor were to be slewed by the normal slewing current of 10  $\mu$ A. When VO\_SNS falls below the normal range, the enhanced sink current capability is in excess of 1 mA. When VO\_SNS falls below the normal range, the UCC38050 can source more than 1 mA, and the UCC38051 sources approximately 300  $\mu$ A. The limited source current in the UCC38051 helps to gradually increase the error voltage on the COMP pin preventing a step increase in line current. The actual rate of increase of V<sub>COMP</sub> depends on the compensation network connected to the COMP pin.

#### 7.3.3 Zero Current Detection and Re-Start Timer Blocks

When the boost inductor current becomes zero, the voltage at the power MOSFET drain end falls. This is indirectly sensed with a secondary winding connected to the ZCD pin. The internal active clamp circuitry prevents the voltage from going to a negative or a high positive value. The clamp has the sink and source capability of 10 mA. The resistor value in series with the secondary winding should be chosen to limit the ZCD current to less than 10 mA. The rising edge threshold of the ZCD comparator can be as high as 2 V. The auxiliary winding should be chosen such that the positive voltage (when the power MOSFET is off) at the ZCD pin is in excess of 2 V.

The restart timer attempts to set the gate drive high in case the gate drive remains off for more than 400  $\mu$ s nominally. The minimum guaranteed time period of the timer is 200  $\mu$ s. This translates to a minimum switching frequency of 5 kHz. In other words, the boost inductor value should be chosen for switching frequencies greater than 5 kHz.



#### Feature Description (continued)

#### 7.3.4 Enable Block

The gate drive signal is held low if the voltage at the VO\_SNS pin is less than the ENABLE threshold. This feature can disable the converter by pulling VO\_SNS low. If the output feedback path is broken, VO\_SNS is pulled to ground, and the output is disabled to protect the power stage.

### 7.3.5 Zero Power Block

When the output of the  $g_M$  amplifier goes below 2.3 V, the zero power comparator latches the gate drive signal low. The slew rate enhancement circuitry of the gM amplifier activated during overvoltage conditions slews the COMP pin to approximately 2.4 V. This ensures that the zero power comparator is not activated during transient behavior, when the slew rate enhancement circuitry is enhanced.

#### 7.3.6 Multiplier Block

The multiplier block has two inputs. One is the error amplifier output voltage ( $V_{COMP}$ ), and the other is  $V_{MULTIN}$ , which is obtained by a resistive divider from the rectified line. The multiplier output is approximately 0.67 ×  $V_{MULTIN} \times (V_{COMP} - 2.5 \text{ V})$ . There is a positive offset of about 75 mV to the  $V_{MULTIN}$  signal because this improves the zero-crossing distortion and thus the THD performance of the controller in the application. The dynamic range of the inputs can be found in *Electrical Characteristics*.

### 7.3.7 Overvoltage Protection (OVP) Block

The OVP feature in the part is not activated under most operating conditions because of the presence of the slew rate enhancement circuitry present in the error amplifier. As soon as the output voltage reaches to approximately 5% to 7% above the nominal value, the slew rate enhancement circuit is activated, and the error amplifier output voltage is pulled below the dynamic range of the multiplier block. This prevents further rise in output voltage.

If the COMP pin is not pulled low fast enough and the voltage rises further, the OVP circuit acts as a second line of protection. When the voltage at the VO\_SNS pin is more than 7.5% of the nominal value (> ( $V_{REF}$  + 0.19)), the OVP feature is activated. It stops the gate drive from switching as long as the voltage at the VO\_SNS pin is above the nominal value ( $V_{REF}$ ). This prevents the output DC voltage from going above 7.5% of the nominal value designed for, and protects the switch and other components of the system such as the boost capacitor.



#### 7.4 Device Functional Modes

#### 7.4.1 Transition Mode Control

The boost converter, the most common topology used for power factor correction, can operate in two modes: continuous conduction code (CCM) and discontinuous conduction mode (DCM). Transition mode control, also referred to as critical conduction mode (CRM) or boundary conduction mode, maintains the converter at the boundary between CCM and DCM by adjusting the switching frequency.

The CRM converter typically uses a variation of hysteretic control, with the lower boundary equal to zero current. It is a variable frequency control technique that has inherently stable input current control while eliminating reverse recovery rectifier losses. As shown in Figure 17, the switch current is compared to the reference signal (output of the multiplier) directly. This control method has the advantage of simple implementation and good power factor correction.

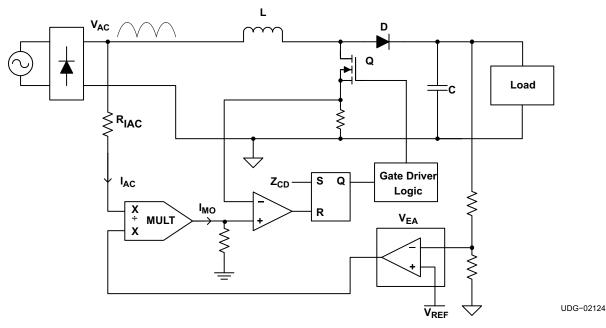


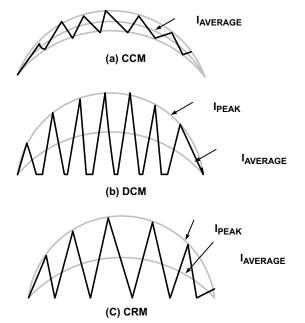
Figure 17. Basic Block Diagram of CRM Boost PFC

The power stage equations and the transfer functions of the CRM are the same as the CCM. However, implementations of the control functions are different. Transition mode forces the inductor current to operate just at the border of CCM and DCM. The current profile is also different, and affects the component power loss and filtering requirements. The peak current in the CRM boost is twice the amplitude of CCM, leading to higher conduction losses. The peak-to-peak ripple is twice the average current, which affects MOSFET switching losses and magnetics ac losses.



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### **Device Functional Modes (continued)**



Note: Operating Frequency >> 120 Hz

UDG-02123

Figure 18. PFC Inductor Current Profiles

For low to medium power applications up to approximately 300 W, the CRM boost has an advantage in losses. The filtering requirement is not severe, and therefore is not a disadvantage. For medium to higher power applications, where the input filter requirements dominate the size of the magnetics, the CCM boost is a good choice due to lower peak currents (which reduces conduction losses) and lower ripple current (which reduces filter requirements). The main tradeoff in using CRM boost is lower losses due to no reverse recovery in the boost diode vs. higher ripple and peak currents.



### 8 Application and Implementation

#### NOTE

Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes. Customers should validate and test their design implementation to confirm system functionality.

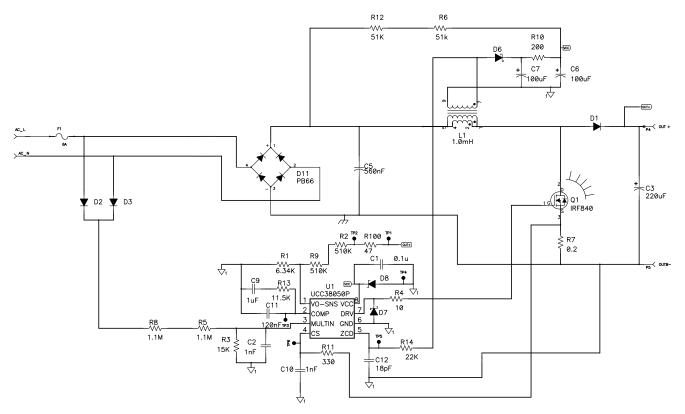
### 8.1 Application Information

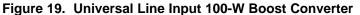
The UCC38050 and UCC38051 are switch-mode controllers used in boost converters for power factor correction operating in transition mode. In the transition mode operation, the PWM circuit is self-oscillating, with the turnon being governed by an inductor zero-current detector (ZCD pin), and the turnoff being governed by the current-sense comparator. Additionally, the controller provides features such as peak current limit, default timer, OVP, and enable.

There are two key parametric differences between UCC38050 and UCC38051. The UVLO turnon threshold of UCC38050 is 15.8 V, while for UCC38051 it is 12.5 V. Secondly, the gM amplifier source current for UCC38050 is typically 1.3 mA, while for UCC38051 it is 300  $\mu$ A. The UCC38051 is suitable for multiple applications, including AC adapters, where a two-stage power conversion is needed. The UCC38050 is suitable for applications such as electronic ballasts, where there is no down-stream PWM conversion and the advantages of a smaller VCC capacitor and improved transient response can be realized. Figure 19 is an example of a critical conduction mode power factor correction boost converter utilizing the UCC38050.

### 8.2 Typical Application

The UCC38050 is used for the off-line power factor corrected pre-regulator with operation over a universal input range of 85 V to 265 V with a 400- $V_{DC}$  regulated output. The schematic is shown in Figure 19, and the board layout for the reference design is shown in Figure 24.







### **Typical Application (continued)**

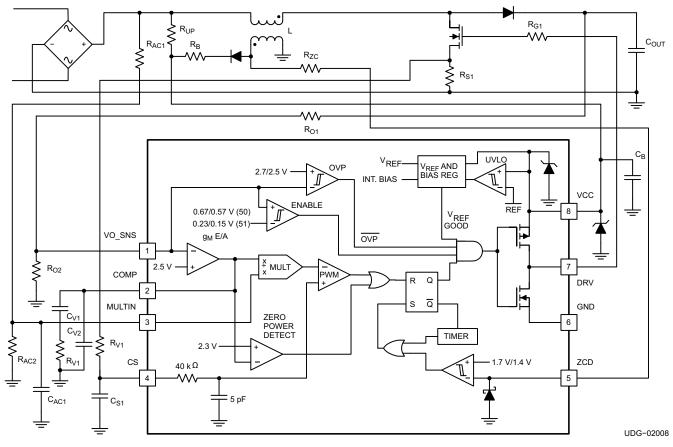


Figure 20. Typical Application Diagram

### 8.2.1 Design Requirements

Table 1 shows the design requirements for a CCM, PFC boost converter utilizing the UCC38050.

	PARAMETER	TEST CONDITION	MIN	TYP	MAX	UNIT
V <sub>IN</sub>	Input voltage		85		265	V <sub>RMS</sub>
	Input frequency			60		Hz
V <sub>OUT</sub>	Output voltage DC	$V_{IN} = 85 V_{RMS}$	370	400	425	V
V <sub>OUT</sub>	Output voltage DC	V <sub>IN</sub> = 265 V <sub>RMS</sub>	370	390	410	V
P <sub>OUT</sub>	Output power		0		100	W
	Output voltage ripple	$V_{IN} = 85 V_{RMS}$			3%	
	Efficiency	P <sub>OUT</sub> = 100 W	90%			
	Total harmonic distortion (THD)	$V_{IN}$ = 85 $V_{RMS}$ , $P_{OUT}$ = 100 W		5%		
	Total harmonic distortion (THD)	V <sub>IN</sub> = 265 V <sub>RMS</sub> , P <sub>OUT</sub> = 100 W		15%		
	Hold-up time		16.7			ms

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#### 8.2.2 Detailed Design Procedure

For a selected V<sub>OUT</sub> and minimum switching frequency, the following equations outline the design guidelines for power stage component selection, using a universal input, 100-W PFC converter with an output voltage of 390 V. Refer to Figure 20 for reference designators.

#### 8.2.2.1 Inductor Selection

In the transition mode control, the inductor value must be calculated to start the next switching cycle at zero current. The time it takes to reach zero depends on line voltage and inductance and as shown in Equation 2. L determines the frequency range of the converter.

$$L = \frac{\left(V_{AC(min)}\right)^{2} \times \left(V_{OUT} - \sqrt{2} \times V_{AC(min)}\right)}{2 \times F_{s(min)} \times V_{OUT} \times P_{IN}}$$

where

V<sub>AC</sub> = RMS line voltage

2

V<sub>AC(min)</sub> = minimum AC line voltage

<ul> <li>P<sub>IN</sub> = maximum input power averaged over the ac line period</li> </ul>	(2)
$I_{L(peak)} = 2 \times \sqrt{2} \times (P_{IN}/V_{AC(min)})$	(3)
$I_{L(rms)} = I_{L(peak)} / \sqrt{6}$	(4)

$$I_{L(rms)} = I_{L(peak)} / \sqrt{6}$$

#### 8.2.2.2 MOSFET Selection

The main switch selection is driven by the amount of power dissipation allowable. Choose a device that minimizes gate charge and capacitance, and minimizes the sum of switching and conduction losses at a given frequency.

$$I_{Q(rms\_crm)} = \sqrt{\frac{1}{6} - (4 \times \sqrt{2}) \times (\frac{V_{AC(min)}}{9\pi \times V_{OUT}})} \times IL_{PEAK(crm)}$$
(5)  
$$V_{Q(max)} = V_{OUT}$$
(6)

#### 8.2.2.3 Diode Selection

The effects of the reverse recovery current in the diode can be eliminated with relatively little negative impact to the system. The diode selection is based on reverse voltage, forward current, and switching speed.

$$I_{D(avg)} = I_{OUT(avg)}$$

$$I_{D(rms)} = I_{L(peak)} \sqrt{\frac{\sqrt{2} \times V_{AC}}{\pi \times V_{OUT}}}$$

$$V_{D(peak)} = V_{OUT}$$
(8)
(9)

 $V_{D(peak)} = V_{OUT}$ 

#### 8.2.2.4 Capacitor Selection

The hold-up time is the main requirement in determining the output capacitance. ESR and the maximum RMS ripple current rating can also be important, especially at higher power levels.

 $C_{OUT(min)} = (2 \times P_{OUT} \times t_{HOLDUP}) / ((V_{OUT})^2 - (V_{OUT(min)})^2)$ 

where

$$I_{C(rms)} = \sqrt{\left(I_{L(peak)}\right)^{2} \times \frac{\sqrt{2} \times V_{AC(max)}}{\pi \times V_{OUT}} - \left(\frac{P_{OUT}}{V_{OUT}}\right)^{2} + (ac rms load currents)^{2}}$$
(11)



#### 8.2.2.5 Multiplier Set-Up

Select  $R_{AC1}$  and  $R_{AC2}$  so that their ratio uses the full dynamic range of the multiplier input at the peak line voltage, and yet with values small enough to negate the effects of the multiplier bias current. To use the maximum range of the multiplier, select the divider ratio so that  $V_{MULTIN}$ , evaluated at the peak of the maximum ac line voltage, is the maximum of the minimum dynamic input range of MULTIN, which is 2.5 V. Choose  $R_{AC1}$  so that it has at least 100 µA at the peak of the minimum AC operating line voltage.

$$\frac{R_{AC1}}{R_{AC2}} = \left(\frac{\sqrt{2}}{2.5} V_{AC(max)}\right) - 1$$
(12)

In extreme cases, switching transients can contaminate the MULTIN signal, so it can be beneficial to add capacitor  $C_{AC1}$ . Select the value of  $C_{AC1}$  so that the corner frequency of the resulting filter is greater than the lowest switching frequency. The low corner frequency of this filter may compromise the overall power factor.

#### 8.2.2.6 Sense Resistor Selection

The current sense resistor value must be chosen to limit the output power, and it must also use the full dynamic range of the multiplier during normal steady state operation. The value of  $R_{S1}$  is thus selected for maximum power operation at low ac line voltage conditions. To use the full dynamic range, set the  $V_{SENSE}$  threshold as a function of the dynamic input range of  $V_{COMP}$  and the peak of the minimum MULTIN voltage.

$$R_{S1} = \frac{0.67 \times (COMP_{(MAX)} - COMP_{(MIN)}) \times (MULTIN_{(PEAK)@VAC(min)} - 0.075)}{2 \times \sqrt{2} \times \frac{P_{IN(max)}}{V_{AC(min)}}}$$

where

- COMP<sub>(MAX)</sub> = 3.8 V
- COMP<sub>(MIN)</sub> = 2.5 V
- $MULTIN_{(PEAK)@VAC(min)} = \sqrt{2} \times V_{AC(min)}(R_{AC2} / (R_{AC2} + R_{AC1}))$ (13)

If the exact value  $R_{S1}$  is not available,  $R_{S2}$  and  $R_{S3}$  can be added for further scaling. The CS pin already has an internal filter for noise due to switching transients. Additional filtering at switching transient frequencies can be achieved by adding CS1.

#### 8.2.2.7 Output Voltage Sense Design

Select the divider ratio of  $R_{O1}$  and  $R_{O2}$  to set the VO\_SNS voltage to 2.5 V at the desired output voltage. The current through the divider should be at least 200  $\mu$ A.

#### 8.2.2.8 Voltage Loop Design

How well the voltage control loop is designed directly impacts line current distortion. UCC38050 employs a transconductance amplifier ( $g_M$  amp) with gain scheduling for improved transient response (refer to Figure 9). Integral type control at low frequencies is preferred, because the loop gain varies considerably with line conditions. The largest gain occurs at maximum line voltage. If the power factor corrector load is dc-to-dc switching converter, the small signal model of the controller and the power factor corrector, from COMP to PFC output voltage is given by:

$$\frac{\hat{V}_{OUT}(s)}{\hat{V}_{COMP}(s)} = \frac{k_1 \times (V_{AC})^2}{V_{OUT(avg)} \times R_{S1} \times k_{CRM} \times C_{OUT}} \times \frac{1}{S}$$

where

- ^V<sub>OUT</sub> = small signal variations in V<sub>OUT</sub>
- ^V<sub>COMP</sub> = small signal variations in V<sub>COMP</sub>
- $k_1$  = multiplier gain = 0.65
- k<sub>CRM</sub> = peak to average factor = 2

(14)

A controller that has integral control at low frequencies requires a zero near the crossover frequency to be stable. The resulting gM amplifier configuration is shown in Figure 21.

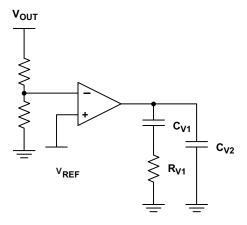


Figure 21. gM Amplifier Configuration

The compensator transfer function is:

$$A_{V} = \frac{gM}{C_{V1} + C_{V2}} \times \frac{1 + (R_{V1} \times C_{V1} \times s)}{s \left(1 + \left(R_{V1} \times \frac{[C_{V1} \times C_{V2}]}{[C_{V1} \times C_{V2}]}\right) \times s\right)}$$

where

gM = DC transconductance gain = 100 μs

The limiting factor of the gain is usually the allowable third harmonic distortion, although other harmonics can dominate. The crossover frequency of the control loop will be much lower than twice the AC line voltage. To choose the compensator dynamics, determine the maximum allowable loop gain at twice the line frequency, and solve for capacitor  $C_{V2}$ . This also determines the crossover frequency.

$$C_{V2} = \left(\frac{V_{AC(max)}}{4\pi f_{AC}}\right) 2 \times \left(\frac{gM \times k_{1}}{V_{OUT(avg)} \times R_{S1} \times k_{(crm)} \times C_{OUT(max loop gain at 2f_{AC})}}\right)$$
(16)  
$$f_{CO} = \frac{V_{AC}}{\pi} \sqrt{\frac{gM \times k_{1}}{C_{V2} \times V_{OUT} \times R_{S1} \times k_{(crmr)} \times C_{OUT}}}$$
(17)

Select  $C_{V1}$  so that the low frequency zero is one-tenth of the crossover frequency.

$$C_{V1} = 9 C_{V2}$$
 (18)

Select  $R_{V1}$  so that the pole is at the crossover frequency.

/

(15)

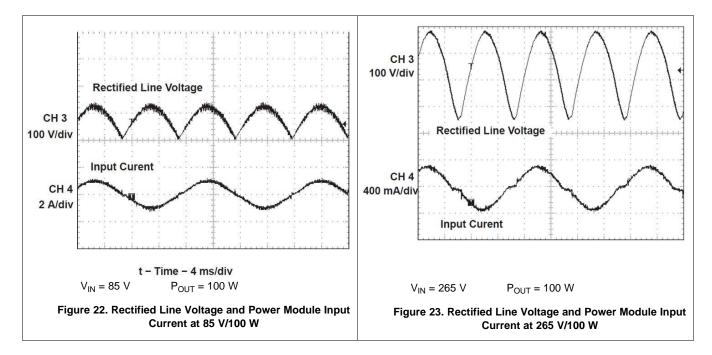
(19)



### 8.2.3 Application Curves

Figure 22 and Figure 23 show the input current and rectified line for the power module.

- Channel 3 = Rectified Line Voltage
- Channel 4 = Power Module Input Current



### 9 Power Supply Recommendations

The supply voltage for the device comes from VCC pin. This pin must be bypassed with a high-frequency capacitor (greater than 0.1  $\mu$ F) and tied to GND. The UCC38050 has a wide UVLO hysteresis of approximately 6.3 V that allows use of a lower value supply capacitor on this pin for quicker and easier start-up. The UCC38051 has a narrow UVLO hysteresis with of about 2.8 V, and a start-up voltage of about 12.5 V for applications where the operation of the PFC device must be controlled by a downstream PWM controller.



### 10 Layout

### 10.1 Layout Guidelines

#### 10.1.1 Bias Current

The bias voltage is supplied by a bias winding on the inductor. Select the turns ratio so that sufficient bias voltage can be achieved at low AC line voltage. The bias capacitor must be large enough to maintain sufficient voltage with AC line variations. Connect a 0.1- $\mu$ F bypass capacitor between the VCC pin and the GND pin as close to the integrated circuit as possible. For wide line variations, a resistor, R<sub>B</sub>, is necessary to permit clamping action. The bias voltage should also be clamped with an external zener diode to a maximum of 18 V.

#### 10.1.2 Zero Current Detection

The zero current detection activates when the ZCD voltage falls below 1.4 V. The bias winding can provide the necessary voltage. This pin has a clamp at approximately 5 V. Add a current limiting resistor,  $R_{ZC}$ , to keep the maximum current below 1 mA.

### 10.2 Layout Example

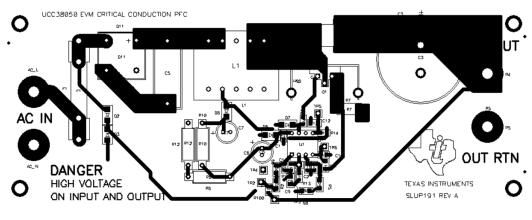


Figure 24. UCC38050 Layout Example

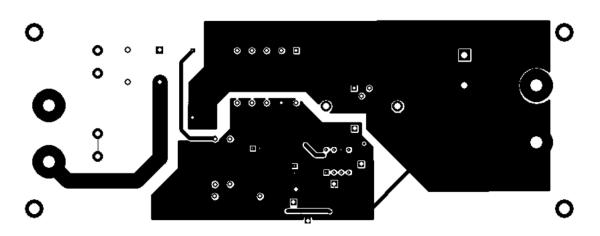


Figure 25. UCC38050 Bottom-Layer Layout Example



### **11** Device and Documentation Support

### **11.1 Device Support**

### 11.1.1 Development Support

Reference Design, 100-W Universal Line Input PFC Boost Converter Using the UCC38050 (SLUU134)

### 11.2 Related Links

The table below lists quick access links. Categories include technical documents, support and community resources, tools and software, and quick access to sample or buy.

PARTS	PRODUCT FOLDER	SAMPLE & BUY	TECHNICAL DOCUMENTS	TOOLS & SOFTWARE	SUPPORT & COMMUNITY				
UCC28050	Click here	Click here	Click here	Click here	Click here				
UCC28051	Click here	Click here	Click here	Click here	Click here				
UCC38050	Click here	Click here	Click here	Click here	Click here				
UCC38051	Click here	Click here	Click here	Click here	Click here				

#### Table 2. Related Links

### **11.3 Community Resources**

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### 11.4 Trademarks

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#### 11.5 Electrostatic Discharge Caution



These devices have limited built-in ESD protection. The leads should be shorted together or the device placed in conductive foam during storage or handling to prevent electrostatic damage to the MOS gates.

### 11.6 Glossary

SLYZ022 — TI Glossary.

This glossary lists and explains terms, acronyms, and definitions.



### 12 Mechanical, Packaging, and Orderable Information

The following pages include mechanical, packaging, and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.



5-Nov-2016

## PACKAGING INFORMATION

Orderable Device	Status	Package Type	Package Drawing	Pins	Package Qty	Eco Plan (2)	Lead/Ball Finish	MSL Peak Temp	Op Temp (°C)	Device Marking (4/5)	Samples
UCC28050D	ACTIVE	SOIC	D	8	75	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM	-40 to 85	28050	Samples
UCC28050DR	ACTIVE	SOIC	D	8	2500	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM	-40 to 85	28050	Samples
UCC28050P	ACTIVE	PDIP	Ρ	8	50	Pb-Free (RoHS)	CU NIPDAU	N / A for Pkg Type	-40 to 85	28050	Samples
UCC28051D	ACTIVE	SOIC	D	8	75	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM	-40 to 105	28051	Samples
UCC28051DG4	ACTIVE	SOIC	D	8	75	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM	-40 to 105	28051	Samples
UCC28051DR	ACTIVE	SOIC	D	8	2500	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM	-40 to 105	28051	Samples
UCC28051DRG4	ACTIVE	SOIC	D	8	2500	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM	-40 to 105	28051	Samples
UCC28051P	ACTIVE	PDIP	Ρ	8	50	Pb-Free (RoHS)	CU NIPDAU	N / A for Pkg Type	-40 to 105	28051	Samples
UCC38050D	ACTIVE	SOIC	D	8	75	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM	0 to 70	38050	Samples
UCC38050DR	ACTIVE	SOIC	D	8	2500	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM	0 to 70	38050	Samples
UCC38050P	ACTIVE	PDIP	Р	8	50	Pb-Free (RoHS)	CU NIPDAU	N / A for Pkg Type	0 to 70	38050	Samples
UCC38051D	ACTIVE	SOIC	D	8	75	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM	0 to 70	38051	Samples

<sup>(1)</sup> The marketing status values are defined as follows:

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NRND: Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

**PREVIEW:** Device has been announced but is not in production. Samples may or may not be available.

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	Device	Package Type	Package Drawing		SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
	UCC28050DR	SOIC	D	8	2500	330.0	12.4	6.4	5.2	2.1	8.0	12.0	Q1
	UCC28051DR	SOIC	D	8	2500	330.0	12.4	6.4	5.2	2.1	8.0	12.0	Q1
	UCC38050DR	SOIC	D	8	2500	330.0	12.4	6.4	5.2	2.1	8.0	12.0	Q1

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# PACKAGE MATERIALS INFORMATION

5-Nov-2016



\*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
UCC28050DR	SOIC	D	8	2500	340.5	338.1	20.6
UCC28051DR	SOIC	D	8	2500	340.5	338.1	20.6
UCC38050DR	SOIC	D	8	2500	340.5	338.1	20.6

D (R-PDSO-G8)

PLASTIC SMALL OUTLINE



NOTES: A. All linear dimensions are in inches (millimeters).

- B. This drawing is subject to change without notice.
- Body length does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not exceed 0.006 (0,15) each side.
- Body width does not include interlead flash. Interlead flash shall not exceed 0.017 (0,43) each side.
- E. Reference JEDEC MS-012 variation AA.





NOTES: A. All linear dimensions are in millimeters.

- B. This drawing is subject to change without notice.
- C. Publication IPC-7351 is recommended for alternate designs.
- D. Laser cutting apertures with trapezoidal walls and also rounding corners will offer better paste release. Customers should contact their board assembly site for stencil design recommendations. Refer to IPC-7525 for other stencil recommendations.
   E. Customers should contact their board fabrication site for solder mask tolerances between and around signal pads.



P(R-PDIP-T8)

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